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Resultant of Force systems and equilibrium

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International System of Units (SI):

Length = meters (m);

Time = seconds (s);

Mass = kilograms (kg).

Force = Newtons (N) is derived from F=m*a.

Therefore a 1 kilogram mass has a weight of 9.81 Newton at the earth's surface.

Giga	X 10 ⁹	G
Mega	X 10 ⁶	Μ
Kilo	X 10 ³	k
Meter		m
milli	X 10 ⁻³	mm
micro	X 10-6	μ
nanometer	X 10 ⁻⁹	n
Newton		Ν
Pascal	Pa	N/m²
	X 106Pa	MPa

Dimensional homogeneity - in an equation where you are adding terms, they must all have the same units.

Force Vectors

Scalar and Vectors

Scalar: is a quantity which has magnitude only.

Examples of scalars: speed, distance, energy, charge, volume, mass and temperature.

Vectors are quantities which are fully described by both a magnitude and a direction. Vectors are physical quantities.

Examples of vectors are displacement, velocity, acceleration, force and electric field

Vector notation:

A widely used convention is to denote a vector quantity in bold type, such as **A** and that is the convention that will be used. The magnitude of a vector **A** is written as **A**.



Addition of a system of coplanar forces



Determine the magnitude of the resultant force and its direction measured from the positive x axis.



$$\sum F_s: 70N + 50N \cos[30^\circ] - 65N \cos[45^\circ] = 67.3 \text{ N}$$

$$\sum F_s: -50N \sin[30^\circ] - 65N \sin[45^\circ] = -71.0 \text{ N}$$

$$\tan \alpha = \frac{71.0N}{67.3N} = 1.054 \implies \underline{\alpha} = 46.5^{\circ}$$

3D Three Dimensional Vectors

Cartesian vector representation:

$$\mathbf{A} = A_x \mathbf{i} + A_y \mathbf{j} + A_z \mathbf{k}$$

Magnitude of a Cartesian Vector.

$$A = \sqrt{A_x^2 + A_y^2 + A_z^2}$$

Direction of a Cartesian Vector

$$\cos \alpha = \frac{A_x}{A}$$
 $\cos \beta = \frac{A_y}{A}$ $\cos \gamma = \frac{A_z}{A}$



Unit vector Representation of a Vector

vector \mathbf{u}_{A} is just a vector in the same direction as \mathbf{A} , but with magnitude = 1,



 $\mathbf{u}_{A} = \overline{\mathbf{A}} / |A|$ \mathbf{u}_{A} is **dimensionless.** It serves only to indicate direction and sense.

Direction (orientation) of a Cartesian vector in 3D

- \mathbf{C} = angle between **A** and *positive* x axis •
- β = angle between A and *positive* y axis •

 γ = angle between **A** and *positive* z axis •

$$\cos \alpha = \frac{A_x}{A} \qquad \cos \beta = \frac{A_y}{A} \qquad \cos \gamma = \frac{A_z}{A}$$

$$\mathbf{u}_A = \frac{\mathbf{A}}{A} = \frac{\mathbf{A}_x}{A}\mathbf{i} + \frac{\mathbf{A}_y}{A}\mathbf{j} + \frac{\mathbf{A}_z}{A}\mathbf{k}$$

 $\mathbf{U} = \cos\alpha \mathbf{i} + \cos\beta \mathbf{j} + \cos\gamma \mathbf{k}$

$$1 = \sqrt{\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma}$$
$$\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1$$



Eg. Determine the magnitude and directional cosines of the vector.

$$\vec{A} = 700 \ \vec{i} - 820 \ \vec{j} + 900 \ \vec{k}$$

The magnitude of the vector is

$$\vec{A} = 700 \ \vec{i} - 820 \ \vec{j} + 900 \ \vec{k}$$

 $|\vec{A}| = \sqrt{(700)^2 + (-820)^2 + (900)^2} = 1404.42$

The directional cosines are

Check the cosines

$$\cos^{2} \theta_{x} + \cos^{2} \theta_{y} + \cos^{2} \theta_{z} = 1$$
$$(0.498)^{2} + (-0.584)^{2} + (0.641)^{2} = 1$$

$$\cos\theta_{x} = \frac{700}{1404.42} = 0.498 \Rightarrow \theta_{x} = 60.1^{\circ}$$
$$\cos\theta_{y} = \frac{-820}{1404.42} = -0.584 \Rightarrow \theta_{y} = 125.7^{\circ}$$
$$\cos\theta_{z} = \frac{900}{1404.42} = 0.641 \Rightarrow \theta_{x} = 50.1^{\circ}$$

Express F as Cartesian vector

$$\cos^{2} \alpha + \cos^{2} \beta + \cos^{2} \gamma = 1$$

$$\cos^{2} 30^{\circ} + \cos^{2} 70^{\circ} + \cos^{2} \gamma = 1$$

$$\cos \gamma = \pm 0.3647$$

$$\gamma = 68.61^{\circ} \text{ or } 111.39^{\circ}$$

By inspection, $\gamma = 111.39^\circ$ since the force **F** is directed in negative octant.

 $\mathbf{F} = 2500\{\cos 30^\circ \mathbf{i} + \cos 70^\circ \mathbf{j} + \cos 111.39^\circ \mathbf{k}\}$ N

Adding and Subtracting 3D Cartesian Vectors

Given
$$\mathbf{A} = A_x \mathbf{i} + A_y \mathbf{j} + A_z \mathbf{k}$$
, $\mathbf{B} = B_x \mathbf{i} + B_y \mathbf{j} + B_z \mathbf{k}$,

Addition: $\mathbf{R} = \mathbf{A} + \mathbf{B} = (A_x + B_x)\mathbf{i} + (A_y + B_y)\mathbf{j} + (A_z + B_z)\mathbf{k}$ Subtraction: $\mathbf{R}' = \mathbf{A} - \mathbf{B} = (A_x - B_x)\mathbf{i} + (A_y - B_y)\mathbf{j} + (A_z - B_z)\mathbf{k}$

Given several vectors,

$$\mathbf{F}_R = \Sigma \mathbf{F} = \Sigma F_x \mathbf{i} + \Sigma F_y \mathbf{j} + \Sigma F_z \mathbf{k}$$

2-71 Determine the magnitude and coordinate direction angles of the resultant force and sketch this vector on the coordinate system. $F2 = 250(\frac{4}{5})\cos 30^{\circ}i - 250(\frac{4}{5})\sin 30^{\circ}j + 250(\frac{3}{5})k$ $F1 = 350\cos 60^{\circ}i + 350\cos 60^{\circ}j - 350\cos 45^{\circ}k$ $\mathbf{F}_{R} = \mathbf{F}_{1} + \mathbf{F}_{2}$ $F_2 = 250 \text{ N}$ $F_R = \{348.21i + 75.0j - 97.487k\}$ N $F_R = \sqrt{(348.21)^2 + (75.0)^2 + (97.487)^2} = 369.29$ N $\alpha = \cos^{-1}(\frac{348.21}{369.29}) = 19.5^{\circ}$ 60°, 60° $\beta = \cos^{-1}(\frac{75.0}{369.29}) = 78.3^{\circ}$ 45° $F_1 = 350 \,\mathrm{N}$ $\gamma = \cos^{-1}(\frac{-97.487}{360.20}) = 105^{\circ}$



Cartesian position vector from origin O to point P(x,y,z): r = xi + yj + zk



$$u = \frac{1}{r} = \frac{(z - u)^{2} + (z - u)^{2}}{\sqrt{(x_{B} - x_{A})^{2} + (y_{B} - y_{A})^{2} + (z_{B} - z_{A})^{2}}}$$

$$F = F \frac{r}{r} = F u$$

Conditions for equilibrium of a Particle

To maintain a state of equilibrium, *The resultant force acting on a particle must be zero*.

$$\sum F = 0$$

$$\sum F_x i + \sum F_y j + \sum F_z k = 0$$





Construction of a free body diagram.

- **Step 1:** Isolate the body or combination of bodies are to be shown on the free-body diagram.
- **Step 2:** Prepare drawing or sketch of the outline of the isolated or free body.
- **Step 3:** identify all the forces exerted by contacting or attracting bodies that were removed during isolation
- **Step 4:** Choose the set of coordinate axes to be used in solving the problem and indicate their directions on the freebody diagram. Place any dimensions required for solution of the problem on the diagram.



2. Cables and pulleys (tension)

Cable forces are along the cable

Cables on frictionless pulleys have same tension force in every part of the cable



+s

Determine the stretch in each spring for equilibrium of the 2-kg block. The springs are shown in the equilibrium position



Example

A 90 lb load is suspended from the hook as shown. The load is supported by two cables and a spring with k=500 lb/ft. Determine the force in the cables and the stretch of the spring for equilibrium. Cable AD lies in the x-y plane and cable AC lies in the x-z plane.







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Force System Resultant

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Equilibrium requires the body to have No Translation and No rotation.

Moment of a Force - Scalar Formulation

The moment of the force about a point O is the tendency of the force to rotate the object about point O.





If the resultant moment about point A is 4800 N \cdot m clockwise, determine the magnitude of F3 if F1 = 300 N and F2 = 400 N.



Transmissibility of a force



Cross product

 $\sim \mathbf{B}$

$\mathbf{C} = \mathbf{A} \times \mathbf{B}$

Scalar formulation

C magnitude = **A B** sin θ



If $C = A \times B$, then C will be perpendicular to A and B.



Commutative law - be very careful here

$$\mathbf{A} \times \mathbf{B} \neq \mathbf{B} \times \mathbf{A}$$
$$\mathbf{A} \times \mathbf{B} = -\mathbf{B} \times \mathbf{A}$$





$$i \times j = k \quad i \times k = -j \quad i \times i = 0$$

$$j \times k = i \quad j \times i = -k \quad j \times j = 0$$

$$k \times i = j \quad k \times j = -i \quad k \times k = 0$$



The cross product of two vectors is

 $\mathbf{C} = \mathbf{A} \times \mathbf{B}$

$$\begin{vmatrix} \mathbf{\dot{i}} & \mathbf{\ddot{j}} & \mathbf{\dot{k}} \\ A_{x} & A_{y} & A_{z} \\ B_{x} & B_{y} & B_{z} \end{vmatrix} = \begin{vmatrix} A_{y} & A_{z} \\ B_{y} & B_{z} \end{vmatrix} \vec{i} - \begin{vmatrix} A_{x} & A_{z} \\ B_{x} & B_{z} \end{vmatrix} \vec{j} + \begin{vmatrix} A_{x} & A_{y} \\ B_{x} & B_{y} \end{vmatrix} \vec{k}$$

 $= \left(A_{\mathbf{y}}B_{\mathbf{z}} - A_{\mathbf{z}}B_{\mathbf{y}}\right)\vec{i} - \left(A_{\mathbf{x}}B_{\mathbf{z}} - A_{\mathbf{z}}B_{\mathbf{x}}\right)\vec{j} + \left(A_{\mathbf{x}}B_{\mathbf{y}} - A_{\mathbf{y}}B_{\mathbf{x}}\right)\vec{k}$

Direction of Moments





Moment of a Force - Vector Formulation



Resultant moment of a system of forces



If $\theta = 45$ determine the moment produced by the 4-kN force about point *A*.



45īn45

$$(+M_A = 4\cos 45^\circ (0.45) - 4\sin 45^\circ (3))$$

= -7.21 kN · m = 7.21 kN · m (clockwise)

- 60
Determine the magnitude and directional sense of the moment of the force at A about point P. And O



Determine the magnitude and direction of the moment of the force at A about point P.



$$M_{p} = -(\frac{4}{5}250 lb)(10 ft \sin 30^{\circ}) - (\frac{3}{5}250 lb)(10 ft \cos 30^{\circ})$$
$$M_{p} = -2300 ft lb$$

The force $F = \{6i+8j+10k\}$ N creates a moment about point O of $M_0 = \{-14i+8j+2k\}$ N m. If the force passes through a point having an x coordinate of 1 m, determine the y and z coordinates of the point. Also, realizing that $M_0 = Fd$, determine the perpendicular distance d from point O to the line of action of F.

$\frac{\text{Solution:}}{-141 + 8j + 2k} = \begin{vmatrix} 1 & j & k \\ 1 & y & z \\ 6 & 8 & 10 \end{vmatrix}$	P F
-14 = 10y - 8z	Mo No
8 = -10 + 6z	z d
2 = 8 - 6y	0 /1 m
y=lm Ans	x y
z = 3 m And	

The pipe assembly is subjected to the 80-N force. Determine the moment of this force about point B.

Position Vector And Force Vector :

$$\mathbf{r}_{ac} = \{(0.55-0)\mathbf{i} + (0.4-0.4)\mathbf{j} + (-0.2-0)\mathbf{k}\}\mathbf{m} = \{0.55\mathbf{i} - 0.2\mathbf{k}\}\mathbf{m}$$

Moment of Force F About Point B : Applying Eq.4-7, we have

$$M_{g} = r_{gC} \times F$$

$$= \begin{vmatrix} i & j & k \\ 0.55 & 0 & -0.2 \\ 44.53 & 53.07 & -40.0 \end{vmatrix}$$

$$= \{10.6i + 13.1j + 29.2k\} N \cdot m$$



Moment of a Force on a Rigid Body

Point O is on the line of action of the force



Principle of Transmissibility:

The external effect on a rigid body remains unchanged when a force acting at a given point on the body, is applied to another point lying on the line of action of the force.

Point O Not on Line of Action of Force



Equivalent to a force in the same direction and a moment of magnitude = r x F



Resultant of a Force and Couple System

 $F_{R} = \sum F$ $\hat{\mathbf{M}}_{\mathbf{R}_{o}} = \sum \hat{\mathbf{M}}_{c} + \sum \hat{\mathbf{M}}_{o}$











Resultant of a Force and Couple System – 2D



Eg. Replace the forces acting on the brace shown below with an equivalent resultant force and couple moment at point A.



The couple moment has a magnitude of 220 N.m determine the magnitude of F of the couple forces



Replace the force and couple system by an equivalent force and couple moment at point O.



$$(+M_o = \Sigma M_o: M_o = 8 - 6(\frac{12}{13})(4) + 6(\frac{5}{13})(5) - 4\cos 60^{\circ}(4)$$

 $M_o = -10.62 \text{ kN} \cdot \text{m} = 10.6 \text{ kN} \cdot \text{m}$



Further Reduction of a Force System



If a system of forces is either concurrent, coplanar or parallel, it can always be reduced to a single resultant force acting through a unique point.

Concurrent Force Systems







 $d = \frac{\sum X_i F}{\sum F}$

Replacing a distributed load by single resultant load:



F must pass through the centroid of the area under the curve w(x).

$$F_R = \int_L w(x) dx = \int_A dA = A$$

Magnitude of resultant force is equal to the total area under the loading diagram w = w(x)

dF produces a moment dM = x dF = x w(x) dx

$$\overline{x} F_{R} = \int x \, dF = \int_{L} x \, w(x) \, dx = \int_{A} x \, dA$$
$$\overline{\overline{x}} = \frac{\int_{L} x \, w(x) \, dx}{F_{R}} = \frac{\int_{L} x \, w(x) \, dx}{\int_{L} w(x) \, dx} = \frac{\int_{A} x \, dA}{\int_{A} dA}$$

$$d = \frac{\sum X_i F}{\sum F}$$





Find the equivalent resultant force and specify the magnitude and location of the force measured from A.

500 N/m dA = wdx BENGHER $F_{R} = \int dA = \int_{0}^{10} \frac{1}{2} x^{3} dx$ $w=(0.5x^3)\mathrm{N/m}$ $=\left[\frac{1}{8}x^4\right]^{10}$ 10 m $\omega = \frac{1}{2}x^2$ = 1250 N $F_{\rm r} = 1.25 \, \rm kN$ ٠ $\int \bar{x} dA = \int_{0}^{10} \frac{1}{2} x^4 dx$ τ 10m đr $=\left[\frac{1}{10}x^{5}\right]^{10}$ $\ddot{x} = \frac{10\ 000}{1250} = 8.00\ \mathrm{m}$ = 10 000 N·m

Replace the loading by a simple resultant force, and specify the location of the force on the beam measured from point O.

Solution:





Replace the force system acting on the beam by an equivalent force and specify its location from point A.





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Equilibrium of rigid body

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5.1 Conditions for Rigid-Body Equilibrium



For equilibrium of a rigid body:

Moments (applied pure twists, and due to external forces) should sum to zero about any point.

Equilibrium in Two Dimensions

Free Body Diagrams

Support Reactions



If a support prevents the translation of a body in a given direction, then a force is developed on the body in that direction.

if rotation is prevented a couple moment is exerted on the body.

Number of Support or Connection Reaction Unknowns 1 Force with known line of action Frictionless Rocker Rollers surface 1 Short cable Short link Force with known line of action 1 Collar on frictionless rod Force with known Frictionless pin in slot line of action 2 a Frictionless pin or hinge Rough surface Force of unknown direction 3 Fixed support Force and couple

Type of supports



Modeling





Procedure for Drawing a Free-Body Diagram

- 1. Select co-ordinate axes.
- 2. Draw outlined shape isolated or cut "free" from its constraints and connections.
- 3. Show all forces and moments acting on the body. Include applied loadings and reactions.
- Identify each loading and give dimensions. Label forces and moments with proper magnitudes and directions. Label unknowns.


















FBD



FBD

Important Points

- 1. No equilibrium problem should be solved without first drawing the appropriate F.B.D.
- 2. If a support prevents translation in a direction, then it exerts a force on the body in that direction.
- 3. If a support prevents rotation of the body then it exerts a moment on the body.
- 4. Couple moments are <u>free vectors</u> and can be placed anywhere on the body.
- 5. Forces can be placed anywhere along their line of action. They are *sliding vectors*.

Equilibrium of a Rigid Body in Two Dimensions

• Equations of equilibrium become

$$\sum F_x = 0$$
 $\sum F_y = 0$ $\sum M_A = 0$

where A is any point in the plane of the structure.

- The 3 equations can be solved for no more than 3 unknowns.
- The 3 equations can not be augmented with additional equations, but they can be replaced with:

$$\sum F_x = 0$$
 $\sum M_A = 0$ $\sum M_B = 0$

A fixed crane has a mass of 1000 kg and is used to lift a 2400 kg crate. It is held in place by a pin at A and a rocker at B. The center of gravity of the crane is located at G.

Determine the components of the reactions at A and B.

$$\sum M_A = 0: + B(1.5m) - 9.81 \text{ kN}(2m)$$

- 23.5 kN(6m) = 0

$$B = +107.1 \,\mathrm{kN}$$

$$\sum F_x = 0: \quad A_x + B = 0$$
$$A_x = -107.1 \,\text{kN}$$

$$\sum F_y = 0$$
: $A_y - 9.81 \text{kN} - 23.5 \text{kN} = 0$

$$A_y = +33.3 \,\text{kN}$$



G

2400 kg

4 m

 Δ

В

←2 m→

 $1.5 \mathrm{m}^{\mathrm{T}}$

Determine the reactions at the supports necessary for equilibrium of the beam.



$$\sum M_{A} := 800 Nm - (500 N) \left(\frac{2}{3} 13m\right) + B(8m) = 0$$

$$\sum F_{x} := A_{x} + \frac{4}{13} 500 N = 0$$

$$\sum F_{y} := A_{y} - \frac{12}{13} 500 N + B = 0$$

These equations can easily be solved .:

$$A_x = 192.3 N; A_y = 180.1 N; B = 642 N$$



These equations are easily solved:

 $A_x = 54 kN; A_y = 16 kN; BC = 80 kN$



A = 5125lb, B = 3625lb

The frame supports part of the roof of a small building. The tension in the cable is 150 kN.



A loading car is at rest on an inclined track. The gross weight of the car and its load is 5500 lb, and it is applied at at *G*. The cart is held in position by the cable.



• Determine the cable tension.

 $\sum F_x = 0: +4980 \, \text{lb} - \text{T} = 0$

 $T = +4980 \, \text{lb}$

 $W_y = -(5500 \,\text{lb})\sin 25^\circ$ = -2320 lb

 $= +4980 \, \text{lb}$

Find the reaction at A and E







Find the reactions







Determine the reactions at A and the force in bar CD due to the loading.





"Properly constrained" means that

• the supports can theoretically maintain equilibrium regardless of what forces and moments are applied

- To "properly constrain" a body, if the only support reactions are forces (no moments):
- reaction forces must not all intersect a common axis
- reaction forces must not all be parallel







Journal bearing



Thrust bearing





(b) Holding a supported bar.(c) A built-in support can exert six reactions: three force components and three couple components.







Hinge and bearing supporting radial load only



axial thrust and radial load

(and two couples)

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Structural Analysis

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Simple Trusses

Simple Trusses truss

structure composed of straight, slender members joined at their endpoints

- joint connection can consist of pin through the ends of the members
- ends of members can bolted or welded to a gusset plate



- Simplest shape that is rigid or stable is a triangle
- Trusses are generally built out of triangular elements











Truss analysis

Truss analysis consists of finding forces in individual members when a truss is subject to a given loading.

Assumptions

- Trusses are composed of two force members
- Members are pin connected
- Loads are applied at joints
 - Weight of member usually neglected
 - If not neglected, typically split & applied at each joint



Truss members are two force members • Either in *tension* (T) or *compression* (C) –











Truss Analysis Methods

- Two types of analysis
 - 1. Method of joints: used when axial forces in all members are desired
 - 2. Method of sections: used when axial forces in only a few members are desired

6.2 Method of Joints

If a truss is in equilibrium, then all parts of the truss are in equilibrium. • Every joint (assume a pin joint) is in equilibrium.

- Every pin is acted on by external forces, support reactions, or forces from two-force members
- Draw FBD of each pin
- Use 2D particle equilibrium equations to solve for unknown tension or compression forces

Procedure for Analysis

- 1. Determine support reactions
- 2. Draw a FBD
- 3. Write equilibrium equations and solve
- 2. Method of joints
 - For each joint:
 - Draw a FBD
 - Write equilibrium equations (x and y components) and solve



Tension vs. Compression members in compression "push" on the pin, members in tension "pull" on the pin



6.3 Zero-Force Members

Why are they there?

- sometimes zero-force members are added during construction of the truss to improve stability, and aren't removed afterwards
- 2. sometimes if the applied loading changes, they will no longer be zero-force members'

Two cases where you can tell if a member is a zero-force member.

Case 1 - pin joins two members and has no external load applied to it Case 2 - pin joins three members, has no external load applied to it, and two of the members are collinear

Case 1: Two non-collinear members, no load at a pin

Both members are zero force members



- Case 2: Three members connect at a pin, two members are collinear and no applied load
 - Non-collinear member is a zero force member



• Identify the zero force members






6–6. Determine the force in each member of the truss and state if the members are in tension or compression.



6.4 Method of Sections

Method of Joints typically used to find forces in all members of a truss Method of Sections typically used to find forces in a few members

Method of Sections:

- 1. make a cut or "section" through the entire truss
- 2. section should divide truss into two parts
- 3. section should pass through no more than three members
- 4. for which forces are unknown (we have only 3 equilibrium equations, after all)



 If a truss is in equilibrium, then any subpart of the truss must be in equilibrium







Procedure for Analysis

Determine support reactions (in general)

- Draw a FBD
- Write equilibrium equations and solve
- Find forces in members *BC*, *GC* and *GF* and whether they are in (T) or (C)



Method of sections

- Decide which part to analyze
 - Typically pick the one with the fewest number of forces



- Draw FBD of the truss sub-part to be analyzed
- Write equilibrium equations to solve for unknown forces (at most three)
- Try to write equations with direct solutions, e.g. sum moments about a point with multiple forces acting on it



Determine the force in member GC of the truss and state if this member is in tension or compression.





The Howe bridge truss is subjected to the loading shown. Determine the force in members DE, EH, and HG, and state if the members are in tension or compression.





 $BC = 3.67 \ kN \ T$ $FG = 15.26 \ kN \ C$ $BF = 11.85 \ kN \ T$



4. Find the force in member BC and indicate if it is in tension or compression



Find the force in member BC and indicate if it is in tension or compression





6. Find two zero force members by inspection



7. Find the force in member BC



F _{BC} = (1 point)

6.6 Frames and Machines

Frames: support loads, generally stationary Machines: transmit or alter forces, often have moving parts

As with trusses, if a frame or machine is in static equilibrium, then every individual part of the frame or machine is in static equilibrium

any collection of individual parts are, together, in static equilibrium
every joint in the frame or machine is in static equilibrium

Steps Determine the reactions at the supports .

FBD, Σ **F** = **0**, Σ **M**= **0**

If the structure is statically indeterminate, determine as many of the reactions as possible .

Identify any 2-force members (simplify the problem) Analyze the members .FBD, $\Sigma F = 0$, $\Sigma M = 0$

If a load is applied at a joint, place the load on only one of the members at that joint









Find pin forces, and force in member BE.



6–68. Determine the force P needed to hold the 20-lb block in equilibrium.



Find the reactions







Note that the horizontal and vertical forces in the pin at A are just

$$A_x = A_y = -\frac{1}{\sqrt{2}}AB = -100lb$$

In summary

$$A_z = A_y = C_x = C_y = -100 \, lb$$



Now let's examine BED

$$\sum M_{s}: E_{y}(3ft) + (300lb)(1ft) - (300lb)(7ft) = 0 \implies E_{y} = 600lb$$

These are the two extra pieces of information that we need. Now we are ready to look at body CEF.

$$\sum M_{\varepsilon} := -C_{\varepsilon} (4 ft) - (300 lb) (1 ft) = 0 \implies C_{\varepsilon} = -75 lb$$

$$\sum F_{y} : C_{y} - E_{y} + F = 0 \implies C_{y} = 100 lb$$

 $C_x = -75 lb$ $C_y = 100 lb$



Determine the greatest force P that can be applied to the frame if the largest force resultant acting at A can have a magnitude of 2 kN.



 $+ (P)^{2}$

= 743 N

$$(\pm \Sigma M_A = 0; \quad T(0.6) - P(1.5) = 0$$

 $\Rightarrow \Sigma F_x = 0; \quad A_x - T = 0$
 $\pm \uparrow \Sigma F_y = 0; \quad A_y - P = 0$
aus, $A_x = 2.5P, \quad A_y = P$
 $P = 0.743 \text{ kN}$

 $A_x = 2.5P$,

Thus,

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Internal Forces

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(b) Combined beams

Internal Forces Developed in Structural Members

For each cross section, there is a shear force V and a bending moment M and a normal force N.





Internal Forces

- Shear Forces
- Bending Moment
- Normal Forces

Sign Convention



Negative Moment





Positive Moment



a shear force, which tends to rotate the beam fibers in the clockwise direction, is a negative shear force whereas a force that tends to rotate the beam fibers in the counter clockwise is positive.



General Solution Scheme

The general scheme for finding the internal set of forces is

a) Draw the free-body diagram

b) Determine the support reactions

c) Apply the equations of equilibrium



Determine the axial forces at point B and C,



Find the axial force, shear force, and bending moment acting internally on the beam at D.




$$\sum M_A = -(2 \text{ m})(60 \text{ kN}) - (6 \text{ m})(20 \text{ kN}) + (8 \text{ m})R_B = 0$$
$$\implies R_B = 30 \text{ kN}$$
$$\sum F_y = R_A + R_B - (60 \text{ kN}) - (20 \text{ kN}) = 0$$
$$\implies R_A = 50 \text{ kN}$$

Internal forces at distance x from A

$$\sum F_y = (50 \text{ kN}) - \left(15\frac{\text{kN}}{\text{m}}\right)x - V = 0$$

$$\implies V = 50 - 15x \text{ (kN)} \quad \{x \text{ in meters}\}$$

$$\sum M_o = M - (50 \text{ kN})x + \left(15\frac{\text{kN}}{\text{m}}\right)(x)\left(\frac{x}{2}\right) = 0$$

$$\implies M \approx 50x - 7.5x^2 \text{ (kN·m)}$$



Force Diagrams

Force diagrams show the all of the internal forces acting in the member.

1) Axial Force Diagram

2) Shear Diagram

3) Moment Diagram



When drawing freebody diagrams for beams, always apply positive shear forces and bending moments





In





Shear and Bending moment Diagrams

In order to generate a shear and bending moment diagram one needs to

- Draw the free-body diagram
- Solve for reactions
- Solve for the internal forces (shear, V, and bending moment, M)







Concentrated Loads:

Shear forces are consistent in magnitude.
 Therefore, shear diagrams are flat lines (no slope; horizontal).

 Moment vary linearly between concentrated loads. Therefore, moment diagrams are composed of sloping lines for concentrated loads.



• UDLs produce linearly varying shear forces—shear diagrams consist of sloped lines.

• UDLs produce parabollically varying moments; therefore, moment diagrams are curves.





$$\frac{\mathrm{d}M}{\mathrm{d}x} = V$$

$$M = \frac{1}{2} \left(\frac{wL}{2}\right) \left(\frac{L}{2}\right) = \frac{wL^2}{8}$$

Note that the slope of the moment diagram is equal to the shear.





For the beam shown draw the shear and moment diagram:









For the beam shown here draw the shear and moment diagram:





Construction of the shear force diagram









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Centroids of an Area

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Centroid of an Area



The centroid of the area coincides with the center of symmetry.



Locate the Centroid of the area shown





Find: The centroid location $(\overline{x}, \overline{y})$





1. Since y is given in terms of x, choose dA as a vertical rectangular strip.

fl

2.
$$dA = y dx = (9 - x^2) dx$$

3. $\tilde{x} = x$ and $\tilde{y} = y/2$

$$\mathbf{k} \cdot \mathbf{\bar{x}} = (\int_{A} \mathbf{\bar{x}} \, dA) / (\int_{A} dA)$$

$$= \frac{\int_{0}^{3} \mathbf{x} \, (9 - \mathbf{x}^{2}) \, d\mathbf{x}}{\int_{0}^{3} (9 - \mathbf{x}^{2}) \, d\mathbf{x}} = \frac{[9 \, (\mathbf{x}^{2})/2 - (\mathbf{x}^{4}) / 4]_{0}^{3}}{[9 \, \mathbf{x} - (\mathbf{x}^{3}) / 3]_{0}^{3}}$$

$$= (9 \, (9) / 2 - 81 / 4) / (9 \, (3) - (27 / 3))$$

$$= 1.13 \, \text{ft}$$

$$\overline{\mathbf{y}} = \frac{\int_{A} \mathbf{\bar{y}} \, dA}{\int_{A} \, dA} = \frac{\frac{1}{2} \int_{0}^{3} (9 - \mathbf{x}^{2}) \, (9 - \mathbf{x}^{2}) \, d\mathbf{x}}{\int_{0}^{3} (9 - \mathbf{x}^{2}) \, d\mathbf{x}} = 3.60$$

9.3 Centroids – Composite Bodies



Many industrial objects can be considered as **composite bodies** <u>made up of a series of connected "simpler" shaped</u> <u>parts or holes</u>, like a rectangle, triangle, and semicircle.

Knowing the location of the centroid, C, or center of gravity, G, of the simpler shaped parts, we can easily determine the location of the C or G for the more complex composite body.



	A _i	Xi	Уi	Zi	x _i A _i	y _i A _i	$z_i A_i$
1							
2							
Sum	ΣA_i				$\Sigma A_i x_i$	$\Sigma A_i y_i$	$\Sigma A_i z_i$

Find the centroid of the given area





Body	Area(mm ²)	x (mm)	y(mm)	x*Area (mm ³)	y*Area (mm ³)
Triangle	3600	40	40	144000	144000
Square	12000	60	110	720000	1320000
Sum	15600			864000	1464000
centroid (x)	55.38	mm			
centroid (y)	93.85	mm			



Component	A, mm²	x , mm	ӯ, mm	īzA, mm ³	ӯA, mm³
Rectangle Triangle Semicircle Circle	$\begin{array}{l} (120)(80) = 9.6 \times 10^3 \\ \frac{1}{2}(120)(60) = 3.6 \times 10^3 \\ \frac{1}{2}\pi(60)^2 = 5.655 \times 10^3 \\ -\pi(40)^2 = -5.027 \times 10^3 \end{array}$	60 40 60 60	40 -20 105.46 80	$\begin{array}{r} +576 \times 10^{3} \\ +144 \times 10^{3} \\ +339.3 \times 10^{3} \\ -301.6 \times 10^{3} \end{array}$	$\begin{array}{r} +384 \times 10^{3} \\ -72 \times 10^{3} \\ +596.4 \times 10^{3} \\ -402.2 \times 10^{3} \end{array}$
	$\Sigma A = 13.828 \times 10^3$			$\Sigma \bar{x}A = +757.7 \times 10^3$	$\Sigma \overline{y}A = +506.2 \times 10^3$



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Moment of Inertia

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Moment of Inertia (Mol) (second moment of an area (m⁴⁾

Definition of Moments of Inertia for Areas: Used in formulas for Mechanics of Materials, Fluid Mechanics, Structural Mechanics

The moment of inertia is found by integrating





 J_0 is the polar moment of inertia about the pole O or Z axis $J_0 = \int_A r^2 dA = \int_A (x^2 + y^2) dA = I_x + I_y$

EXAMPLE

Given: The shaded area shown in the figure.

Find: The MoI of the area about the x- and y-axes.

Solution

$$I_x = \int y^2 dA$$

$$dA = a dy$$

$$I_x = \int_0^b y^2 \cdot a dy$$

$$= [a \cdot y^3/3]_0^b = ab^3/3 in^4$$

$$I_x = \int x^2 dA$$

$$dA = b dx$$

$$I_y = \int_0^a x^2 \cdot b dx$$

$$= [b \cdot x^3/3]_0^a = ba^3/3 in4$$







x

Given: The shaded area shown in the figure.

Find: The MoI of the area about the x- and y-axes.



Solution

)*-



Moment of Inertia: Parallel-Axis Theorem

$$I_x = \int_A y^2 dA, \quad I_y = \int_A x^2 dA$$

Given I_{xc} , I_{yc} (or $I_{x,}$, I_{y}), determine I_{x} , I_{y} (or I_{xc} , I_{yc})



$$I_x = \int (y+d_1)^2 dA$$

= $\int y^2 dA + 2d_1 \int y dA + d_1^2 \int dA$
= $I_{xc} + Ad_1^2$

$$I_y = \int (x+d_2)^2 dA$$

= $\int x^2 dA + 2d_2 \int x dA + d_2^2 \int dA$
= $I_{yc} + Ad_2^2$

Moment of Inertia for simple shapes



Moment of Inertia



Memorize the moments of inertia of these two cross sections!
Moments of Inertia for Composite Areas

Composite area consists of group of connected simple shapes.

If MOI of parts about common axis can be determined, then MOI of the composite is algebraic sum of parts.

$$\mathbf{I}_{\mathbf{X}} = \sum_{\mathbf{i}} \mathbf{I}_{\mathbf{X}}^{\mathbf{i}}, \qquad \mathbf{I}_{\mathbf{Y}} = \sum_{\mathbf{i}} \mathbf{I}_{\mathbf{Y}}^{\mathbf{i}}$$

Procedure for Analysis

Composite Area Moment of Inertia about reference axis.

- **1.0 Composite Parts.** Divide area into composite parts. Indicate perpendicular distance from centroid of parts to reference axis.
- **2.0 Apply Parallel Axis Theorem.** Determine MOI of each part about centroidal axis parallel to reference axis. Use parallel axis theorem to calculate MOI of parts about reference axis.
- **3.0 Sum MOI of parts.** Calculate MOI of component by summing MOI of parts. If any part is a "hole", subtract the MOI of hole in making summation.

MOI about the centroid of composite the section

Bodies	Ai	Уi	y _i *A _i	l _i	d _i =y _i -ybar	$d_i^2 A_i$

$$\overline{y} = \frac{\sum y_i A_i}{\sum A_i} \qquad I_x = \sum \left(\overline{I_x} + d^2 A\right)_i$$
$$= \sum \overline{I_{xi}} + \sum \left(y_i - \overline{y}\right)^2 A_i$$



Find I_x and r_x (x- axis passing through the centroid of the section

Bodies	Ai	Уi	y _i *A _i	li	d _i =y _i -ybar	$d_i^2 A_i$
1	18	1	18			
2	18	5	90			
	36		108			



$$\overline{y} = \frac{\sum y_i A_i}{\sum A_i} = \frac{108 \text{ in}^3}{36 \text{ in}^2} = 3.0 \text{ in.}$$

Bodies	A _i	Уi	y _i *A _i	li	d _i =y _i -ybar	$d_i^2 A_i$
1	18	1	18	6	-2	72
2	18	5	90	54	2	72
	36		108	60		144
ybar	3	in.				
I	204	in ⁴				

$$I_{x} = \sum \overline{I_{xi}} + \sum (y_{i} - \overline{y})^{2} A_{i}$$

= 60 in⁴ + 144 in⁴ = 204 in⁴

$$r_{\rm x} = \sqrt{\frac{I_{\rm x}}{A}} = \sqrt{\frac{204 \text{ in}^4}{36 \text{ in}^2}}$$

= 2.38 in.



Element	Area	Х	У	A.x	A.y
1	5	2.5	0.5	12.5	2.5
2	4	0.5	3	2	12
3	10	5	5.5	50	55
Σ	19			64.5	69.5

Hence centroid is

$$\left(\overline{x} = \frac{64.5}{19} = 3.39mm, \ \overline{y} = \frac{69.5}{19} = 3.66mm\right)$$
 from origin

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Tension, Compression and Shear

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Normal Stress and Strain

Prismatic bar: is a straight structural member having the same cross section throughout its length

Non prismatic member with non uniform stresses

Axial force: A load directed along the axis of the member resulting either tension of compression in the bar.











Limitations

The equation $\sigma = P/A$ is valid only if the stress is uniformly distributed over the cross section of the bar. (the load acts at the centroid of the cross sectional area)

For homogeneous materials and uniform stress in prismatic bar





 σ_v

Х

Ζ

Normal Strain (Axial Strain)



Example 1-1

A short post constructed from a hollow circular tube of Aluminum supports a compressive load of 26 kips. The inner and outer diameters of the tube are d1 = 4.0 in and d2 = 4.5 in respectively, and its length is 16 in. the shortening of the post due to the load is 0.012 in.

Determine the compressive stress and strain the post.



The 80-kg lamp is supported by two rods AB and BC as shown in Fig. 1–17*a*. If AB has a diameter of 10 mm and BC has a diameter of 8 mm, determine the average normal stress in each rod.





Internal Loading. We must first determine the axial force in each rod. the

$$\sigma_{BC} = \frac{F_{BC}}{A_{BC}} = \frac{395.2 \text{ N}}{\pi (0.004 \text{ m})^2} = 7.86 \text{ MPa}$$
$$\sigma_{BA} = \frac{F_{BA}}{A_{BA}} = \frac{632.4 \text{ N}}{\pi (0.005 \text{ m})^2} = 8.05 \text{ MPa}$$

Problem 1.2-1 A solid circular post *ABC* (see figure) supports a load $P_1 = 2500$ lb acting at the top. A second load P_2 is uniformly distributed around the shelf at *B*. The diameters of the upper and lower parts of the post are $d_{AB} = 1.25$ in. and $d_{BC} = 2.25$ in., respectively.

- (a) Calculate the normal stress σ_{AB} in the upper part of the post.
- (b) If it is desired that the lower part of the post have the same compressive stress as the upper part, what should be the magnitude of the load P₂?

section1

(a) NORMAL STRESS IN PART AB

$$\sigma_{AB} = \frac{P_1}{A_{AB}} = \frac{2500 \text{ lb}}{\frac{\pi}{4}(1.25 \text{ in.})^2} = 2040 \text{ psi}$$

section2

(b) Load P_2 for equal stresses

$$\sigma_{BC} = \frac{P_1 + P_2}{A_{BC}} = \frac{2500 \text{ lb} + P_2}{\frac{\pi}{4}(2.25 \text{ in.})^2}$$
$$= \sigma_{AB} = 2040 \text{ psi}$$
Solve for P_2 : $P_2 = 5600 \text{ lb}$



The bar in Fig. has a constant width of 35 mm and a thickness of 10 mm. Determine the maximum average normal stress in the bar when it is subjected to the loading shown.



Mechanical Properties of Materials

The design of machines and structures so that they will function properly requires that we understand the *mechanical behavior of the materials* being used.



Tensile Testing

Tensile tests are carried out by gripping the ends of a suitably prepared standardised test piece in a tensile testing machine and then applying a continually increasing uni-axial load until such time as failure occurs

Tensile Testing Machine



Stress- Strain Diagram

- σ = normal stress on a plane perpendicular to the longitudinal axis of the specimen
- P = applied load
- A = original cross sectional area
- ϵ = normal strain in the longitudinal direction
- δ = change in the specimen's gage length
- L = original gage length
- Engineering stress

 $\sigma = P/A_0$

• True stress

σ=P/A

- Engineering strain
 ε=(l-l₀)/l₀
- True strain (Logarithmic strain) $\epsilon = \ln(l/l_0) = \ln(A/A_0)$
- Volume must be the same $Al = A_0 l_0$

stress-strain curve or diagram gives a direct indication of the material properties.

$$\sigma = \frac{P}{A} \qquad \qquad \varepsilon = \frac{\delta}{L}$$





Linear relationship between stress and strain

Strain is temporary, meaning that all strain is fully recovered upon removal of the stress

The slope of this is called the elastic modulus

C . Modulus of Elasticity (Young's Modulus) - Slope of the initial linear portion of the stress-strain diagram. The modulus of elasticity may also be characterized as the "stiffness" or ability of a material to resist deformation within the linear range.

Proportional limit : is the maximum value of the stress from the stress-strain diagram, where the stress and strain are proportional

Elastic Limit : is the maximum stress for a material to behave elastically, - the specimen will return to its original undeformed shape if the load is removed so long as the stress is below the elastic limit.

Yield Point: This defined as the maximum stress on stress-strain curve, where there is an appreciable increase in strain with no increase in stress. It is generally easier to determine than the proportional limit or elastic

Some materials do not exhibit a distinct yield point

Yield Strength : It is the stress which induces a specified permanent set. This is useful for materials which have no well defined yield point. The offset method is generally used to determine yield stress

Tensile strength: the maximum stress applied to the specimen.

Failure stress: the stress applied to the specimen at failure (usually less than the maximum tensile strength because necking reduces the cross-sectional area).

Ductility

It is the ability of a material to deform plastically. Two measurements of ductility:

Percent (%) elongation of the member = $(L_f - L_0) / (L_0) * 100.0$

Percent (%) reduction in area at the location of fracture

% Area = $(A_0 - A_f) / (A_0) * 100.0$



The yield point may be determined by the offset method. A line is drawn on the stress-strain diagram parallel to the initial linear part of the curve but is offset by some standard amount of strain, such as 0.002 or 0.2%). The intersection of the offset line and the stress-strain curve (point A in the figure) defines the yield stress.



Stress-strain diagram for a brittle material.

Materials that fail in tension at relatively low values of strain are classified as <u>brittle materials</u>. Examples are concrete, stone, cast iron, glass, ceramic materials, and many common metallic alloys. These materials fail with only little elongation after the proportional limit (point A) is exceeded, and the fracture stress (point B) is the same as the ultimate stress



- The <u>true-stress vs. true-strain curve</u> is a plot of the stress in the sample at its minimum diameter, after necking has begun, vs the local elongation.
- This more accurately reflects the physical processes happening in the material, but is much more difficult to measure than the engineering stress and strain, which divide the applied load by the original cross-sectional area, and the total elongation by the original length.

Brittle and Ductile Metal Comparison



tensile stress-strain diagrams for brittle and ductile metals loaded to fracture. under the curve, which measures the energy absorbed by the specimen in the process of breaking



Compression stress-strain diagram for copper.

Stress-strain diagrams for compression have different shapes from those for tension. Ductile metals such as steel, aluminum, and copper have proportional limits in compression very close to those in tension, hence the initial regions of their compression stress-strain diagrams are very similar to the tension diagrams. When yielding begins, the behavior is quite different. In a tension test, the specimen is being stretched, necking may occur, and ultimately fracture takes place. When a small specimen of ductile material is compressed, it begins to bulge outward on the sides and become barrel shaped. With increasing load, the specimen is flattened out, thus offering increased resistance to further shortening (which means the stress-strain curve goes upward

Ductile Material – Materials that are capable of undergoing large strains (*at normal temperature*) before failure. An advantage of ductile materials is that visible distortions may occur if the loads before too large. Ductile materials are also capable of absorbing large amounts of energy prior to failure. Ductile materials include mild steel, aluminum and some of its alloys, copper, magnesium, nickel, brass, bronze and many others.

Brittle Material – Materials that exhibit very little inelastic deformation. In other words, materials that fail in tension at relatively low values of strain are considered brittle. Brittle materials include concrete, stone, cast iron, glass and plaster.





 ε' (lateral strain) = - $v \varepsilon$

Isotropic – Isotropic materials have elastic properties that are independent of direction. Most common structural materials are isotropic.

Anisotropic – Materials whose properties depend upon direction. An important class of anisotropic materials is fiber-reinforced composites.

Homogeneous – A material is homogeneous if it has the same composition at every point in the body. A homogeneous material may or may not be isotropic.





Solution ⁻

E

$$E = 29 \times 10^{6} \text{ psi} \qquad \nu = 0.29$$
AXIAL STRESS
$$\sigma = E\varepsilon = (29 \times 10^{6} \text{ psi})(-0.001724)$$

$$= -50.00 \text{ ksi (compression)}$$

LATERAL STRAIN
$$\varepsilon' = \frac{\Delta d}{d} = \frac{0.001 \text{ in.}}{2.00 \text{ in.}} = 0.0005$$

AXIAL STRAIN

$$\varepsilon = -\frac{\varepsilon'}{\nu} = -\frac{0.0005}{0.29} = -0.001724$$
(shortening)

MAXIMUM COMPRESSIVE LOAD

$$P_{\text{max}} = \sigma A = (50.00 \text{ ksi}) \left(\frac{\pi}{4}\right) (2.00 \text{ in.})^2$$

= 157 k

Problem 1.5-3 A nylon bar having diameter $d_1 = 3.50$ in. is placed inside a steel tube having inner diameter $d_2 = 3.51$ in. (see figure). The nylon bar is then compressed by an axial force P.

At what value of the force P will the space between the nylon bar and the steel tube be closed? (For nylon, assume E = 400 ksi and $\nu = 0.4$.)





Average Shear Stress



(a)

 $\tau = V/A \quad \begin{array}{l} \text{average shear stress at the section, which is} \\ \text{assumed to be the} \\ \text{same at each point located on the section} \end{array}$

V = internal resultant shear force at the section determined from the equations of equilibrium











Shear stress on bolt

 $\tau = F/A = F/\pi r^2$

Where r is the radius of the bolt





 $\tau = F/bc$

Where (bc) is the area of contact subjected to the shear force

Double Shear





 $\tau = (F/2)/A = F/2A$

Where A is the parallel area of the bolt subjected to shear force

The bolted connection is subjected to a tensile force of P= 91kN. The diameter of the bolt d= 22mm. Determine the average shear stress in the bolt in (MPa)

Cross section area of bolt = 380.13 mm²

Shear stress (τ) = 91x 1000 N /(2*380.13) = 119.7 MPa
Allowable Stress and allowable Load

Factors to be considered in design includes :

- functionality,
- strength,
- appearance,
- economics and
- environmental protection.

Factor of safety considerations:

- · uncertainty in material properties
- · uncertainty of loadings
- · uncertainty of analyses
- · number of loading cycles
- types of failure
- maintenance requirements and deterioration effects
- importance of member to integrity of whole structure
- risk to life and property
- influence on machine function

Factor of Safety =
$$n = \frac{Actual strength}{Required strength}$$

The factor of safety must be greater than one to avoid failure The allowable load = (Permissible load or safe load) = (Allowable stress) (Area)

 $P_{allow} = \sigma_{allow} A$

Allowable Stress and allowable Load

Factors to be considered in design includes functionality, strength, appearance, economics and environmental protection.

Factor of Safety =
$$n = \frac{Actual strength}{Required strength}$$

The factor of safety must be greater than one to avoid failure

The allowable load = (Permissible load or safe load) = (Allowable stress) (Area)

$$P_{allow} = \sigma_{allow} A$$

The factor of safety is a number greater than unity (*n*>1).

The allowable stress for a given material is: the maximum stress the material can take (normally the ultimate or yield stress) divided by the factor of safety.

$$\sigma_{allow} = \frac{\sigma_y \underline{or} \sigma_u}{n}$$
$$\tau_{allow} = \frac{\tau_y \underline{or} \tau_u}{n}$$

Design for Axial Loads and Direct Shear

Analysis: Given the structure and loads, determine stresses and strains. *Design*: Given the loads and allowable stresses, determine the properties of the structure.

Design for axial loads and direct shear entails finding the required area to carry the loads

Required area = Load to be transmitted Allowable stress (i.e., Strength Consideration)

Other design considerations include

- *Stiffness*: Designing the structure to resist changes in shape.
- *Stability*: Designing the structure to resist buckling under compressive loads.
- **Optimization:** Designing the best structure to meet a particular goal.

Design of Simple Connections



The two members pinned together at *B*. If the pins have an allowable shear stress of $\tau_{allow} = 90$ MPa, and allowable tensile stress of rod *CB* is $(\sigma_t)_{allow} = 115$ MPa

Determine to nearest mm the smallest diameter of pins *A* and *B* and the diameter of rod *CB* necessary to support the load.



(a)

F.B.D





Choose a size larger to nearest millimeter.

$$d_{\rm A} = 7 \text{ mm}$$
 $d_{\rm B} = 10 \text{ mm}$

Bearing stress

 $A = \frac{P}{(\sigma_b)_{allowable}}$

where $(\sigma_b)_{allowable}$ is the allowable bearing stress of the weaker material







Bearing Stress Due to a Bolt

Bearing Stress

The average bearing stress is the force pushing against a structure divided by the area. Exact bearing stress is more complicated but for most applications, the following equation works well for the average,

 $\sigma_{b} = P/A_{b}$

 $\sigma_{b} = \frac{P}{dt}$

This relationship can be further refined by using the width and height of the bearing area as





Required Area to resist shear caused by axial load



Punch Shear



Stress acts on the perimeter surface of the slug. To compute the shear stress at failure, divide the applied load by the area of the slug perimeter EXAMPLE: The connection shown in the figure consists of five steel plates, each 2.5 mm thick, to be joined by a single bolt. Determine the required diameter of the bolt if the allowable bearing stress, σ_b , is 180.0 MPa and the allowable shear stress, τ_{alow} , is 45.0 MPa?



Maximum Bearing Stress:

$$\sigma_{b} = \frac{P_{b}}{t_{\text{plate}} \times d_{\text{bolt}}} = \frac{3,000 \text{ N}}{(2.5 \times 10^{-3} \text{ m})d_{\text{bolt}}} = 180 \text{ MPa}$$
$$d_{\text{bolt}} = \frac{3,000 \text{ N}}{(2.5 \times 10^{-3} \text{ m}) \times 180 \times 10^{6} \text{ N/m}^{2}}$$
$$= 0.00667 \text{ m} = 6.67 \text{ mm}$$

Maximum Shear Stress:

$$\tau = \frac{V}{A_{\text{bolt}}} = \frac{1,800 \text{ N}}{\pi d_{\text{bolt}}^2/4} = 45 \text{ MPa}$$
$$d_{\text{bolt}} = \sqrt{\frac{4 \times 1,800 \text{ N}}{\pi \tau_{\text{allow}}}} = \sqrt{\frac{4 \times 1,800 \text{ N}}{\pi \times 45 \times 10^6}}$$
$$= 0.00714 \text{ m} = 7.14 \text{ mm}$$

The suspender rod is supported at its end by a fixed-connected circular disk as shown If the rod passes through a 40-mmdiameter hole, determine the minimum required diameter of the rod and the minimum thickness of the disk needed to support the 20-kN load. The allowable normal stress for the rod is $\sigma_{\text{allow}} = 60$ MPa, and the allowable shear stress for the disk is $\tau_{\text{allow}} = 35$ MPa.



Diameter of Rod. By inspection, the axial force in the rod is 20 kN. Thus, the required cross-sectional area of the rod is

$$A = \frac{P}{\sigma_{\text{allow}}} = \frac{20(10^3) \text{ N}}{60(10^6) \text{ N/m}^2} = 0.3333(10^{-3}) \text{ m}^2$$

So that

$$A = \pi \left(\frac{d^2}{4}\right) = 0.3333(10^{-2}) \text{ m}^2$$
$$d = 0.0206 \text{ m} = 20.6 \text{ mm} \qquad Ans.$$

Thickness of Disk. As shown on the free-body diagram of the core section of the disk, Fig. 1–33b, the material at the sectioned area must resist *shear stress* to prevent movement of the disk through the hole. If this shear stress is *assumed* to be distributed uniformly over the sectioned area, then, since V = 20 kN, we have

$$A = \frac{V}{\tau_{\text{allow}}} = \frac{20(10^3) \text{ N}}{35(10^6) \text{ N/m}^2} = 0.571(10^{-3}) \text{ m}^2$$

Since the sectioned area $A = 2\pi (0.02 \text{ m})(t)$, the required thickness of the disk is

$$t = \frac{0.5714(10^{-3}) \text{ m}^2}{2\pi (0.02 \text{ m})} = 4.55(10^{-3}) \text{ m} = 4.55 \text{ mm} \qquad Ans.$$

The bar shown has a square cross section for which the depth and thickness are 40 mm. If an axial force of 800 N is applied along the centroidal axis of the bar's cross-sectional area, determine the average normal stress and average shear stress acting on the material along (a) section plane a-a and (b) section plane b-b.





Part (a)

Internal Loading. The bar is sectioned, Fig. 1–24b, and the internal resultant loading consists only of an axial force for which P = 800 N.

Average Stress. The average normal stress is determined from Eq.1-6.

$$\sigma = \frac{P}{A} = \frac{800 \text{ N}}{(0.04 \text{ m})(0.04 \text{ m})} = 500 \text{ kPa}$$
 Ans

No shear stress exists on the section, since the shear force at the section is zero.

$$\tau_{avg} = 0$$
 Ans.

The distribution of average normal stress over the cross section is shown in Fig. 1–24c.



$$N = 692.8 \text{ N}$$
$$V = 400 \text{ N}$$

$$\frac{\text{Inclined Plane}}{\sigma = \frac{P}{A}\cos^2 \theta}$$
$$\tau = \frac{P}{A}\cos\theta\sin\theta$$
$$\Pr(\tau) = \frac{P}{A}\cos\theta\sin\theta}$$
$$Area = A$$

Average Stresses. In this case the sectioned area has a thickness and depth of 40 mm and 40 mm/sin $60^\circ = 46.19$ mm, respectively, Fig. 1-24a. Thus the average normal stress is

$$\sigma = \frac{N}{A} = \frac{692.8 \text{ N}}{(0.04 \text{ m})(0.04619 \text{ m})} = 375 \text{ kPa}$$
 Ans.

and the average shear stress is

$$\tau_{\rm avg} = \frac{V}{A} = \frac{400 \text{ N}}{(0.04 \text{ m})(0.04619 \text{ m})} = 217 \text{ kPa}$$



Ans.

The joint is fastened together using two bolts. Determine the required diameter of the bolts if the allowable shear stress for the bolts is $\tau_{\text{allow}} = 110$ MPa. Assume each bolt supports an equal portion of the load.



The yoke-and-rod connection is subjected to a tensile force of 5 kN. Determine the average normal stress in each rod and the average shear stress in the pin A between the members.



The plastic block is subjected to an axial compressive force of 600 N. Assuming that the caps at the top and bottom distribute the load uniformly throughout the block, determine the average normal and average shear stress acting along section $\alpha - \alpha$.





A shear strain in an element is positive when the angle between two positive faces (or two negative faces) is reduced, and is <u>negative</u> if the angle is increased.

Hooke's Law in Shear

 $\tau = G\gamma$

The constant G is called the shear modulus and relates the shear stress and strain in the elastic region .



It is also used to relate shear and elastic moduli-

$$\mathbf{E} = 2\mathbf{G}(1+\mathbf{v})$$



Engineering Mechanics Statics & Strength of Materials

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Axially deformation and thermal stresses

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Saint-Venant's Principle (discovered by Barré de Saint-Venant in 1855)

A sufficient distance away from the point of application of the load, the stresses will be identical for any load with the same resultant force.

Localized deformation occurs at each end, and the deformations decrease as measurements are taken further away from the ends



Introduction

Axially loaded Members : Structural components subjected only to tension or compression

(solid bars, cables, coil springs)

eg.

Truss members Connecting rods in engines Columns in buildings



Typical cross sections of structural members.



Solid cross sections

$$\left(\frac{P}{A}\right) = E\left(\frac{\delta}{L}\right) \Rightarrow \delta = \frac{PL}{EA} \text{ o}$$

Stiffness : $k = \frac{EA}{L}$
Flexibility : $f = \frac{L}{EA}$

Hollow or tubular cross sections



Thin-walled open cross sections



Cables are used to transmit large tensile force.

Cables are constructed from large number of wires wound in some particular manner.





The cross sectional area of a cable is equal to the total cross sectional area of the individual wires, called the effective area or metallic area. This area is less than the area of a circle having the same diameter as the cable because there are spaces between the individual wires



P = 23200 N

Changes in Lengths of Non-Uniform Bars



(a) Bar with external loads acting at intermediate points; (b) (c), and (d) free-body diagrams (F.B.D.) showing the internal axial forces N_f, N₂, and N₃.

Bars with Intermediate Axial Loads

- Denote the internal forces in segments AB, BC, and CD as N₁, N₂, and N₃, respectively. Draw F.B.D. as shown to expose those internal forces.
- Determine the internal force in each segment from the FBDs. The internal force remains constant in each segment

$$N_1 = -P_B + P_C + P_D$$
, $N_2 = P_C + P_D$, $N_3 = P_D$

 Determine the change in the length of each segment (of length L₁, L₂, and L₃, respectively)

$$\delta_1 = \frac{N_1 L_1}{EA}, \quad \delta_2 = \frac{N_2 L_2}{EA}, \quad \delta_3 = \frac{N_3 L_3}{EA}$$

The change in length for the entire bar is the sum of the changes in length of all segments

$$\delta = \delta_1 + \delta_2 + \delta_3 = \sum_{i=1}^3 \frac{N_i L_i}{EA}$$

Several constant loads are applied:

Cross-sectional areas are constant Material is homogeneous and isotropic





2 Bars Consisting of Prismatic Segments Each Having Different Axial Forces, Dimensions, and Materials







Use equilibrium equations for member ABC

Then **R**_A = 2900 lb

 δ_{C} = 0.0088 in

Required the minimum thickness P = 85 k





$$L = 30,000 \text{ ksr}$$
$$L = 8.0 \text{ ft}$$
$$d = 7.5 \text{ in.}$$
$$\sigma_{\text{allow}} = 7,000 \text{ psi}$$
$$\delta_{\text{allow}} = 0.02 \text{ in.}$$

F = 30.000 kc

REQUIRED AREA BASED UPON ALLOWABLE STRESS

$$\sigma = \frac{P}{A}$$
 $A = \frac{P}{\sigma_{allow}} = \frac{85 \text{ k}}{7,000 \text{ psi}} = 12.14 \text{ in.}^2$

REQUIRED AREA BASED UPON ALLOWABLE SHORTENING

$$\delta = \frac{PL}{EA} \quad A = \frac{PL}{E\delta_{\text{allow}}} = \frac{(85 \text{ k})(96 \text{ in.})}{(30,000 \text{ ksi})(0.02 \text{ in.})}$$
$$= 13.60 \text{ in.}^2$$

MINIMUM THICKNESS
$$t_{min}$$

 $A = \frac{\pi}{4} [d^2 - (d - 2t)^2]$ or
 $\frac{4A}{\pi} - d^2 = -(d - 2t)^2$
 $(d - 2t)^2 = d^2 - \frac{4A}{\pi}$ or $d - 2t = \sqrt{d^2 - \frac{4A}{\pi}}$
 $t = \frac{d}{2} - \sqrt{\left(\frac{d}{2}\right)^2 - \frac{A}{\pi}}$ or
 $t_{min} = \frac{d}{2} - \sqrt{\left(\frac{d}{2}\right)^2 - \frac{A_{min}}{\pi}}$
SUBSTITUTE NUMERICAL VALUES
 $t_{min} = \frac{7.5 \text{ in.}}{2} - \sqrt{\left(\frac{7.5 \text{ in.}}{2}\right)^2 - \frac{13.60 \text{ in.}^2}{\pi}}$
 $t_{min} = 0.63 \text{ in.}$

Assuming that E = 206 GPa, determine the total shortening δ_{AC} of the two columns due to the combined action of the loads P_1 $P_1 = 400 \text{ kN}$ and P_{2} . $P_2 = 720 \text{ kN}$ (a) Shortening δ_{AC} of the two columns $\delta_{AC} = \sum \frac{N_i L_i}{E_i A_i} = \frac{N_{AB} L}{E A_{AB}} + \frac{N_{BC} L}{E A_{BC}}$ (1120 kN)(3.75 m) = (206 GPa)(11,000 mm²) L =length of each (400 kN)(3.75 m) column (206 GPa)(3,900 mm²) = 3.75 m= 1.8535 mm + 1.8671 mm = 3.7206 mm E = 206 GPa $\delta_{AC} = 3.72 \text{ mm}$ $A_{AB} = 11,000 \text{ mm}^2$ $A_{BC} = 3,900 \text{ mm}^2$

3 Bars with Continuously Varying Loads and/or Dimensions



Reaction at A:

$$R_A = P_B + \int_0^L p(x) dx$$

Change in length of segment dx:

$$N(x) = R_A - \int_0^x p(x) dx = P_B + \int_x^L p(x) dx$$
$$d\delta = \frac{N(x) dx}{EA(x)}$$

Change in length of the entire member:

$$\delta = \sum d\delta = \int_0^L d\delta = \int_0^L \frac{N(x)dx}{EA(x)}$$

Thermal Stress

 $\delta_{\text{Thermal}} = \alpha(\Delta T) L$

 $\delta_{Thermal} =$ deformation in length due to temperature change $\alpha =$ linear coefficient of thermal expansion (1/°C,1/°F,1/°K) $\Delta T =$ Temperature change L = original length of the structure member

If free expansion is not allowed such as in a statically indeterminate member

 $\sigma = \sigma_{\text{mechanical}} + \sigma_{\text{thermal}}$ $= E\varepsilon_{\text{mechanical}} + E\varepsilon_{\text{thermal}} = E(\varepsilon_{\text{mechanical}} + \alpha\Delta T)$

Thermal Stresses and Strains


Example 2.7 Statically indeterminate bar with a uniform What is the thermal temperature increase ΔT .



The constraint on top is removed to allow the bar to expand freely as the temperature rises

Rp

The bar is then pushed back to its original length by applying the reaction force.

 $\delta_{AB} = \delta_T - \delta_B = 0$ Compatibility: $\sum F_{\text{verti}} = 0 \Longrightarrow R_A = R_B$ Equilibrium: Force-displacement relations $\delta_R = \frac{R_A L}{EA}$ Temperature-displacement relation $\delta_{T} = \alpha(\Delta T)L$ $\delta_{\rm T} - \delta_{\rm R} = \alpha (\Delta T) L - \frac{R_{\rm A} L}{EA} = 0$ $R_A = EA\alpha(\Delta T)$ $\sigma_T = \frac{R_A}{A} = \frac{R_B}{A} = E\alpha(\Delta T)$

Example:

Two copper bars and aluminum bar are fixed at the bottom as shown in the figure. The top ends of all three bars are supposed to be welded to a rigid steel plate. The aluminum bar, however, is a little shorter (δ = 0.1 in.) than the copper bars and it had to be heated to make it extend to the same length as the copper bars to complete the welding What is the temperature increase, ΔT (°*F*), that is needed to bring the

aluminum bar to the same length as that of copper bars?

$$E_{AL} = 10.6 \times 10^{6} \text{ psi} \quad E_{Cu} = 18.0 \times 10^{6} \text{ psi}$$

$$\alpha_{Al} = 13 \times 10^{-6} / ^{\circ} F \quad A_{Al} = A_{Cu} = 1.0 \text{ in}^{2} \quad L = 30 \text{ in}$$
Rigid Plate
$$\delta = \alpha_{Al} \Delta TL \quad \Rightarrow \quad \Delta T = \frac{\delta}{\alpha_{Al} L} = \frac{0.1}{(13 \times 10^{-6})(30)} = 256.4^{\circ} F$$

$$Cu \quad Al \quad Cu \quad L$$

After the welding is done the temperature returns to normal, what will the stresses be in the aluminum bar and the copper bars, respectively?

The free-body diagram shown below indicates that force in the aluminum bar must balance the forces in the two copper bars. The copper bars will be shortened and the aluminum bar be stretched.



4-42. The post is constructed from concrete and six A-36 steel reinforcing rods. If it is subjected to an axial force of 900 kN, determine the required diameter of each rod so that one-fifth of the load is carried by the steel and four-fifths by the concrete. $E_{st} = 200$ GPa, $E_c = 25$ GPa.

The normal force in each steel rod is

$$P_{st} = \frac{\frac{1}{5}(900)}{6} = 30 \,\mathrm{kN}$$

The normal force in concrete is

$$P_{\rm con} = \frac{4}{5} (900) = 720 \, \rm kN$$

Since the steel rods and the concrete are firmly bonded, their deformation must be the same. Thus

$$\delta_{con} = \delta_{st}$$

$$\frac{P_{con} L}{A_{con} E_{con}} = \frac{P_{\pi} L}{A_{st} E_{st}}$$

$$\frac{320(40^3) \mathcal{L}}{\left[0.25(0.375) - 6(\frac{\pi}{4} d^2)\right] \left[25(40^9)\right]} = \frac{30(40^3) \mathcal{L}}{\frac{\pi}{4} d^2 \left[200(40^9)\right]}$$

$$49.5\pi d^2 = 0.09375$$



$$d = 0.02455 \text{ m} = 24.6 \text{ mm}$$
 An



Engineering Mechanics

Statics & Strength of Materials

Stresses in Beams

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Pure Bending and Nonuniform Bending

Pure bending = No shear,







Sign Convention for Curvature



Longitudinal Strains in beams

- *xy* plane is a plane of symmetry
- Loading is applied in *xy* plane
- Beam deflects in xy plane
- Thickness of the beam, *h, remains* unchanged
- Axis of the beam coincides with the centroidal line of the cross section (



1. Cross sections (mn and pq) remain plane

2. Cross sections remain perpendicular to the axis of the beam

3. For positive moments (hence positive curvature), lines on the lower part of the beam (nq) are elongated; those on the upper part (mp) are shortened





$\varepsilon_x = \frac{e'f' - ef}{ef} = \frac{(\rho - y)d\theta - dx}{dx}$ $= \frac{\left[\frac{dx - \frac{y}{\rho}dx}{\rho}\right] - dx}{dx} = -\frac{y}{\rho}$



- Strains vary linearly with y
- Along x-axis (y = 0) strain is zero
- For a positive curvature, strains on upper part of the beam (y > 0) are negative (in compression) and those on lower part (y < 0) are positive (in tension)

Normal Strain Due to Bending

Problem 5.4-2 A copper wire having diameter d = 3 mm is bent into a circle and held with the ends just touching (see figure). If the maximum permissible strain in the copper is $\epsilon_{\text{max}} = 0.0024$, what is the shortest length L of wire that can be used?

$$d = 3 \text{ mm}$$
 $\varepsilon_{\text{max}} = 0.0024$
 $L = 2\pi\rho$ $\rho = \frac{L}{2\pi}$

$$\varepsilon_{\max} = \frac{y}{\rho} = \frac{d/2}{L/2\pi} = \frac{\pi d}{L}$$

$$L_{\min} = \frac{\pi d}{\varepsilon_{\max}} = \frac{\pi (3 \text{ mm})}{0.0024} = 3.93 \text{ m}$$

What is the normal strain?

The deflection curve is very flat (note that $L/\delta = 80$) and therefore θ is a very small angle.

 $\sin\theta = \frac{L/2}{\rho}$

For small angles, $\theta = \sin \theta = \frac{L/2}{\rho}$ (θ is in radians)

$$\delta = \rho - \rho \cos \theta = \rho(1 - \cos \theta)$$
$$= \rho \left(1 - \cos \frac{L}{2\rho}\right)$$

Substitute numerical values (ρ = inches):

0.25 = $\rho\left(1 - \cos\frac{10}{\rho}\right)$ Solve numerically: ρ = 200.0 in. NORMAL STRAIN $\varepsilon = \frac{y}{\rho} = \frac{t/2}{\rho} = \frac{0.1 \text{ in.}}{200 \text{ in.}} = 500 \times 10^{-6}$



Normal Stress Due to Bending



Flexural Formula

$$\sigma_x = E\varepsilon_x = -\frac{Ey}{\rho} = -E\kappa y$$

Moment due to $\sigma_x dA$:

$$dM = (\sigma_x dA)y = -E\kappa y^2 dA$$

The resultant moment of the normal stress over the cross section must equal to the applied moment *M*

 $I_z = \int_A y^2 dA =$ Moment of Inertia (Chapter 12)





Memorize the moments of inertia of these two cross sections!

Relationships Between Bending Moments and Curvatures.



Relationships Between Bending Moments and Normal Stresses



Maximum Stresses at a Cross Section



Section Moduli for Doubly Symmetric Shapes Rectangular: Circular:



$$c_1 = c_2 \implies \sigma_1 = -\sigma_2 = -\frac{Mc}{I} = -\frac{M}{S}$$
$$\sigma_{\max} = \frac{M}{S}, \quad S = \frac{I}{c}$$

The beam is constructed of a glued laminated wood . Determine the maximum compressive and tensile stresses in the beam due to bending?

- 1. Find reactions
- 2. Draw shear and moment diagrams
- 3. Find maximum moment
- 4. Find the centroid location and moment of inertia

b = 8.75 in.

5. Calculate the stresses



$$\sigma_{\max} = \frac{M_{\max}}{S} = \frac{151.6 \times 1,000 \times 12}{1,063} = 1,710 \text{ psi}$$









$$I_{z} = 2.469 \times 10^{6} \text{ mm}^{4}$$

$$c_{1} = 18.48 \text{ mm} \implies S_{1} = \frac{I_{z}}{c_{1}} = 133,600 \text{ mm}^{3}$$

$$c_{2} = 61.52 \text{ mm} \implies S_{2} = \frac{I_{z}}{c_{2}} = 40,100 \text{ mm}^{3}$$
at $x = 1.125 \text{ m}, M = 2.025 \text{ kN} \cdot \text{m}$

$$\sigma_{1} = -\frac{M}{S_{1}} = -\frac{2.025 \text{ kN} \cdot \text{m}}{133,600 \text{ mm}^{3}} = -15.2 \text{ MPa}$$

$$\sigma_{2} = \frac{M}{S_{2}} = \frac{2.025 \text{ kN} \cdot \text{m}}{40,100 \text{ mm}^{3}} = 50.5 \text{ MPa}$$
at $x = 3.0 \text{ m}, M = -3.6 \text{ kN} \cdot \text{m}$

$$\sigma_{1} = -\frac{M}{S_{1}} = -\frac{-3.6 \text{ kN} \cdot \text{m}}{133,600 \text{ mm}^{3}} = 26.9 \text{ MPa}$$

$$\sigma_{2} = \frac{M}{S_{2}} = \frac{-3.6 \text{ kN} \cdot \text{m}}{40,100 \text{ mm}^{3}} = -89.8 \text{ MPa}$$

Design of Beams for Bending Stresses



Which cross section is the most efficient one?

Design of Beams for Bending Stresses

I. Circular Cross Sections







II. Square Cross Sections



Compare to a circular cross section of identical area Area = $h^2 = \frac{\pi d^2}{4} \implies h = \frac{\sqrt{\pi} d}{2} = 0.886d$ Area = h^2 = $\frac{h^4}{1 \pi}$, $c = \frac{h}{2}$ $S_{\text{square}} = \frac{1}{c} = \frac{h^3}{6} = \frac{1}{6} \left(\frac{\sqrt{\pi}d}{2}\right)^3 = 0.116d^3 = 1.181S_{\text{circle}}$



1. Determine the moment M that should be applied to the beam in order to create a compressive stress at point D of 10 ksi.





Beams With Axial Loads



3. Determine the maximum normal stress in the horizontal portion of the bracket. The bracket has a thickness of 1 in. and a height of 0.75 in. 700 lb





Sandwich beams with: (a) plastic core, (b) honeycomb core, and (c) corrugated core. Examples of composite beams: (a) bimetallic beam, (b) plasticcoated steel pipe, and (c) wood beam reinforced with a steel plate.





Composite Beams

A *composite* beam is composed of two or more elemental structural forms, or different

materials, bonded, knitted, or otherwise joined together. *Composite materials or forms* include such heavy handed stuff as concrete (one material) reinforced with steel bars (another material); high-tech developments such as tubes built up of graphite fibers embedded in an epoxy matrix; sports structures like *laminated* skis, the poles for vaulting, even a golf ball can be viewed as a *filament wound* structure encased within another material.















(a) Composite beam of two materials, (b) cross section of beam, (c) distributions of strains of ε_x throughout the height of the beam, and (d) distributions of stresses σ_x in the beam for the case where $\mathbf{E}_2 > \mathbf{E}_1$.

$$\varepsilon_{\mathbf{x}}(y) = -y \cdot \left(\frac{d\phi}{ds}\right) = -(y/\rho)$$

For material #1 we have $\sigma_x = -E_1 \cdot (y/\rho)$

while for #2

 $\sigma_{\mathbf{x}} = -\mathbf{E}_2 \cdot (\mathbf{y}/\mathbf{\rho})$

Transformed Section Method

- 1. Transform the cross section of a composite beam into an equivalent cross section (of an imaginary beam composed of only one material) is called the transformed section
- 2. Analyze the transformed section as customary for a beam of one material .
- 3. Convert the stresses back to the original beam .
- 4. Modular ratio



5. The dimensions of area 1 remain unchanged, and the width of area 2 is multiplied by *n*). all dimensions perpendicular to the neutral axis remain the same(



A similar procedure can be used to transform the beam into material 2 or a completely different material. One can also extend this technique to cover beams of more than two materials.

Flexure Formula

$$\sigma_{x1} = -\frac{My}{I_T} \qquad \sigma_{x2} = -\frac{My}{I_T}n$$



After the section is transformed all calculations are made using the transformed cross section, just as they would be on a beam of one material. The neutral axis of bending is at the centroid of the transformed section and flexure stresses are calculated with the flexure stress formula .

One final step is required to return to the original cross section. If in going from the stress state in the transformed material we find a reduction in area then we must increase the stresses accordingly to carry the same load. Conversely if we increase area then we reduce stress. Those portions of the cross section which were unaltered in the transformation process carry the same stresses on both the original and transformed sections.


- Consider a composite beam formed from two materials with E_1 and E_2 .
- Normal strain varies linearly.

$$\varepsilon_x = -\frac{y}{\rho}$$

• Piecewise linear normal stress variation. $\sigma_1 = E_1 \varepsilon_x = -\frac{E_1 y}{\rho}$ $\sigma_2 = E_2 \varepsilon_x = -\frac{E_2 y}{\rho}$

Neutral axis does not pass through section centroid of composite section.

- Elemental forces on the section are $dF_1 = \sigma_1 dA = -\frac{E_1 y}{\rho} dA \quad dF_2 = \sigma_2 dA = -\frac{E_2 y}{\rho} dA$
- Define a transformed section such that $dF_2 = -\frac{(nE_1)y}{\rho}dA = -\frac{E_1y}{\rho}(ndA) \qquad n = \frac{E_2}{E_1}$

6.3-4 The composite beam shown in the figure is simply supported and carries a total uniform load of 40 kN/m on a span length of 5 m. The beam is built of a wood member having cross-sectional dimensions 150 mm \times 250 mm and two steel plates of cross-sectional dimensions 50 mm \times 150 mm. Determine the maximum stresses σ_s and σ_w in the steel and wood, respectively, if the moduli of elasticity are $E_s = 209$ GPa and $E_w = 11$ GPa.

√ (¥¥)

M

(Khum)



40 kN/m

50 mm

250 mm

C



6.3-8 The cross section of a composite beam made of aluminum and steel is shown in the figure. The moduli of elasticity are $E_a = 75$ GPa and $E_s = 200$ GPa. Under the action of a bending moment that produces a maximum stress of 50 MPa in the aluminum, what is the maximum stress σ_s in the steel?

<u>Yan</u> = 93.52 MPA

0.=







A 4-in. wide \times 6-in. deep timber <u>cantilever</u> beam 8 ft long is reinforced by bolting two $1/2 \times 6$ -in. steel plates to the sides of the timber beam, as shown. The moduli of elasticity of the timber and steel are 1600 ksi and 29,000 ksi, respectively. Determine the **maximum tensile bending stress in each of the materials** when a static load of 1250 lb is applied to the free end of the beam.



What is the thickness t of the steel plates

Mmax =
$$\frac{q_1^2}{2}$$
 = 61.44 KN · m
Simple beam : L = 3.2 m q = 48 KN/m
 $\textcircledightarrow with respect to the last set of the las$

$$\frac{\text{Required thickness based upon the wood} \oplus (Eq. 6-15)}{\text{Gi} = \frac{M(h/2)}{\text{IT}}} \xrightarrow{(IT)_{1} = \frac{M_{max}(h/2)}{(OT)} = 1.418 \times 10^{9} \text{mm}} \xrightarrow{(IT)_{2} = \frac{M_{max}(h/2)n}{(ST)}} \xrightarrow{(IT)_{2} = \frac{M_{max}(h/2)n}{(ST)} = 1.612 \times 10^{9} \text{mm}} \xrightarrow{(IT)_{2} = \frac{M_{max}(h/2)n}{(ST)} = 1.612 \times 10^{9} \text{mm}}$$
Equate IT and (IT), and solve for t: t_1 = 12.92 mm} the steel governs. t_{min} = 15.0 mm (IT)



Reinforced concrete sections





Reinforced concrete beam with longitudinal reinforcing bars and vertical stirrups.

Reinforced Concrete Beams



- Concrete beams subjected to bending moments are reinforced by steel rods.
- The steel rods carry the entire tensile load below the neutral surface. The upper part of the concrete beam carries the compressive load.
- In the transformed section, the cross sectional area of the steel, A_s , is replaced by the equivalent area nA_s where $n = E_s/E_c$.
- To determine the location of the neutral axis, $(bx)\frac{x}{2} - nA_s(d - x) = 0$ $\frac{1}{2}bx^2 + nA_sx - nA_sd = 0$
- The normal stress in the concrete and steel

$$\sigma_x = -\frac{My}{I}$$

$$\sigma_c = \sigma_x \qquad \sigma_s = n\sigma_x$$

A concrete floor slab is reinforced with 5/8-in-diameter steel rods. The modulus of elasticity is 29x106psi for steel and 3.6x106psi for concrete. With an applied bending moment of 40 kip*in for 1-ft width of the slab, determine the maximum stress in the concrete and steel.



SOLUTION:

- Transform to a section made entirely of concrete.
- Evaluate geometric properties of transformed section.
- Calculate the maximum stresses in the concrete and steel.

$$n = \frac{E_s}{E_c} = \frac{29 \times 10^6 \text{ psi}}{3.6 \times 10^6 \text{ psi}} = 8.06$$
$$nA_s = 8.06 \times 2 \left[\frac{\pi}{4} \left(\frac{5}{8} \text{ in}\right)^2\right] = 4.95 \text{ in}^2$$

• Evaluate the geometric properties of the transformed section.

$$12x\left(\frac{x}{2}\right) - 4.95(4 - x) = 0 \qquad x = 1.450in$$
$$I = \frac{1}{3}(12in)(1.45in)^3 + (4.95in^2)(2.55in)^2 = 44.4in^4$$

• Calculate the maximum stresses.

 $\sigma_c = \frac{Mc_1}{I} = \frac{40 \operatorname{kip} \cdot \operatorname{in} \times 1.45 \operatorname{in}}{44.4 \operatorname{in}^4}$

 $\sigma_s = n \frac{Mc_2}{I} = 8.06 \frac{40 \text{kip} \cdot \text{in} \times 2.55 \text{in}}{44 \text{ Ain}^4}$

$$\sigma_s = 18.52$$
ksi

 $\sigma_c = 1.306 \mathrm{ksi}$

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Shear Stresses in Beams

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Shear Stresses in Beams



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Effects of Shear Strain



Pure Bending Assumption: Cross sections remain plane Warping of the cross sections of a beam due to shear strains.

The effect of shear strain becomes negligible when the aspect ratio, L/h, of the beam is greater than 10.

Shear Stresses in Beams





Side view of element

$$\sigma_1 = -\frac{My}{I} \quad \sigma_2 = -\frac{(M+dM)y}{I}$$





$$F_3 = F_2 - F_1 = \int_{y_1}^{y_2} \frac{(dM)y}{I} dA$$

Shear stresses in beams



Shear Stresses in Rectangular Beams



Parabolic Distribution

Determine the normal and shear stresses at Point C





 $b = 100 \text{ mm} \qquad h = 150 \text{ mm}$ $\sigma_{allow} = 11 \text{ MPa} \qquad \tau_{allow} = 1.2 \text{ MPa}$

$$M_{\max} = Pa, \quad V_{\max} = P$$

$$S = \frac{I}{c} = \frac{bh^3/12}{h/2} = \frac{bh^2}{6}, \quad A = bh$$

$$\sigma_{\max} = \frac{M_{\max}}{S} = \frac{6Pa}{bh^2} \implies P_{\max}^{Bending} = \frac{\sigma_{allow}bh^2}{6a}$$

$$\tau_{\max} = \frac{3V_{\max}}{2A} = \frac{3P}{2bh} \implies P_{\max}^{Shear} = \frac{2\tau_{allow}bh}{3}$$

$$P_{\max}^{Bending} = 8.25 \text{ kN}, \quad P_{\max}^{Shear} = 12.0 \text{ kN},$$



(a)





(a) ALLOWABLE LOAD P BASED UPON BENDING STRESS

 $\sigma_{\rm allow} = 8.5 \text{ MPa}$ $\sigma = \frac{M_{\rm max}}{\sigma}$ Equate values of M_{max} and solve for P: 0.3P + 32.66 = 11,424 P = 37,970 N $M_{\rm max} = \frac{PL}{A} + \frac{qL^2}{8} = \frac{P(1.2 \text{ m})}{A} + \frac{(181.44 \text{ N/m})(1.2 \text{ m})^2}{6}$ $= 0.3P + 32.66 \text{ N} \cdot \text{m} \quad (P = \text{newtons}; M = \text{N} \cdot \text{m})$ $M_{\text{max}} = S\sigma_{\text{allow}} = (1344 \times 10^3 \,\text{mm}^3)(8.5 \,\text{MPa}) = -11,424 \,\text{N} \cdot \text{m}$

(b) ALLOWABLE LOAD P BASED UPON SHEAR STRESS

 $\tau_{\text{allow}} = 0.8 \text{ MPa}$ $\tau = \frac{3V}{24}$ $V = \frac{P}{2} + \frac{qL}{2} = \frac{P}{2} + \frac{(181.44 \text{ N/m})(1.2 \text{ m})}{2}$ $=\frac{P}{2}+108.86$ (N) $V = \frac{2A\tau}{2} = \frac{2}{2} (33,600 \text{ mm}^2)(0.8 \text{ MPa}) = 17,920 \text{ N}$

Equate values of V and solve for P: $\frac{P}{2}$ + 108.86 = 17,920 P = 35,622 N or P = 35.6 kN

or $P = 38.0 \, \text{kN}$

NOTE: The shear stress governs and $P_{\text{allow}} = 35.6 \text{ kN}$

Shear Stresses in beams of Circular cross section





The exact distribution of shear stress in a beam of circular cross section is very complicated and only that along the neutral axis can be determined relatively easily.

$$I = \frac{\pi r^4}{4}, \quad Q = A\overline{y} = \left(\frac{\pi r^2}{2}\right)\left(\frac{4r}{3\pi}\right) = \frac{2r^3}{3}$$
$$\tau_{\max} = \frac{VQ}{hI} = \frac{4V}{3\pi r^2} = \frac{4V}{3\pi} = 1.33\tau_{ave}$$

3A

 $3\pi r^2$

Shear Stresses in the Webs of Beams with Flanges





Shear Force in the Web: = (The are of he shear stress diagram x the thickness of the web)

 $V = [\tau_{\min} h_1 + 2/3 h_1 (\tau_{\max} - \tau_{\min})]t$

= t $h_1/3$ (2 τ_{max} + τ_{min})

Shear force in the web is 90% -98% of the total shear force V acting on the cross section

Assuming the web carries all of the shear force... $\tau_{avg} = V / th_1$



(c)



Shear Force:
$$F_3 = \frac{dM}{I} \int y dA$$

Shear Stress: $\tau = \frac{F_3}{bdx} = \frac{dM}{dxbI} \int y dA = \frac{VQ}{bI}$
Shear Flow: $f = \frac{F_3}{dx} = \frac{dM}{dx} \frac{1}{I} \int y dA = \frac{VQ}{I}$
 $r = \frac{Number of rows of nails}{F = Strength of each nail}$
 $f = \frac{nF}{s} = \frac{Shear force provided by nails}{Nail Spacing}$
Nail Spacing: $s = \frac{nF}{f}$

Shear Force in Fasteners :

In many applications, beam sections consist of several pieces of material that are attached together in a number ways: bolts, rivets, nails, glue, weld, etc. In such so called built-up sections we are interested in knowing the amount of shear stress and the resulting shear force at the cross section of fasteners or over the glued surface.



Ex. 5-16 The plywood is fastened to the flanges by wood screws having an allowable load in shear of F = 800 N each if the shear force V acting on the cross section = 10.5 kN. Determine the max. permissible longitudinal spacing s of the screws.



Find the spacing for each case



Will the beam be able to support the load if the allowable normal stress of southern pine is 15 MPa? (b) What is the maximum nail spacing if the allowable shear load of each nail is 2,000 N?



Maximum Nail Spacing



Nails are to resist the shear flow between the two 2 x 6 Q = (150)(50)(75-25) $= 375.0 \times 10^3 \text{ mm}^3$

$$f = \frac{VQ}{I} = \frac{(9,375)(375.0 \times 10^{-6})}{53.125 \times 10^{-6}} = 66.18 \times 10^3 \frac{N}{m}$$
$$s = \frac{2F}{f} = \frac{2 \times 2,000}{66.18 \times 10^3} = 0.0604 \text{ m} = 60.4 \text{ mm}$$

A box beam of wood is constructed of two 260 mm \times 50 mm boards and two 260 mm \times 25 mm boards (see figure). The boards are nailed at a longitudinal spacing s = 100 mm.

If each nail has an allowable shear force F = 1200 N, what is the maximum allowable shear force V_{max} ?

All dimensions in millimeters.

$$b = 260 \qquad b_1 = 260 - 2(50) = 160$$

$$h = 310 \qquad h_1 = 260$$

$$s = \text{nail spacing} = 100 \text{ mm}$$

$$F = \text{allowable shear force}$$

for one nail = 1200 N

$$f = \text{shear flow between one flange}$$

and both webs



$$f_{\text{allow}} = \frac{2F}{s} = \frac{2(1200 \text{ N})}{100 \text{ mm}} = 24 \text{ kN/m}$$

$$f = \frac{VQ}{l} \qquad V_{\text{max}} = \frac{f_{\text{allow}}l}{Q}$$

$$I = \frac{1}{12} (bh^3 - b_1h_1^3) = 411.125 \times 10^6 \text{ mm}^4$$

$$Q = Q_{\text{flange}} = A_f d_f = (260)(25)(142.5) = 926.25 \times 10^3 \text{ mm}^3$$

$$V_{\text{max}} = \frac{f_{\text{allow}}l}{Q} = \frac{(24 \text{ kN/m})(411.125 \times 10^6 \text{ mm}^4)}{926.25 \times 10^3 \text{ mm}^3}$$

$$= 10.7 \text{ kN} \quad \longleftarrow$$

4. Determine the shear stress in the beam at point A, which is located at the top of the web.





3. The beam is constructed from three boards as shown. If each nail can support a shear force of 300 N, determine the maximum spacing s of the nails within region BC.



$$\overline{y} = \frac{150(30)(300)(2) + 285(200)(30)}{30(300)(2) + 200(30)} = 183.75 \text{ mm from bottom}$$

$$\overline{I} = \left[\frac{0.03(.3)^3}{12} + (.18375 - .15)^2(.30)(.03)\right](2) + \frac{2(.03)^3}{12} + (.285 - .18375)^2(.2)(.03)$$

$$g = \frac{20,000(.285 - .18375)(.2)(.03)}{0.0002175} = \frac{2(300)}{5}$$

S = 10.74mm

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Torsion Deformation of a Circular Shaft

Torque is a moment that twists a member about its longitudinal axis.

Angle of twist (Φ) is defined as the rotation of a radial line from a fixed end to a cross section some distance x from the end.



Bar subjected to torsion by torques *T1* and *T2*.

Sign Convention:

Right-Hand Rule



(c)




Limitations

- 1. The longitudinal axis of the shaft remains straight
- 2. The shaft does not increase or decrease in length
- 3. Radial lines remain straight and radial as the cross section rotates
- 4. Cross sections rotate about the axis of the member

The right end will rotate with respect to the left end of the bar. The angle of rotation = Angle of twist ϕ . It changes along the length L of the bar linearly.





Before torque application



after torque application



\theta: Rate of Twist : = angle of twist per unit length

$$\theta = d\phi/dx \quad \gamma_{max} = r\theta$$
If ϕ is linear, then $\theta = \phi_L/L$
For pure torsion $\gamma_{max} = r \phi/dt$

The Torsion Formula



Tensile and compressive stresses acting on a stress element oriented at 45° to the longitudinal axis.



Determination of the resultant of the shear stresses acting on a cross section.







$$dM = (\rho)(\tau)dA = \rho^2 \frac{\tau_{\max}}{r} dA$$
$$T = \int_A dM = \frac{\tau_{\max}}{r} \int_A \rho^2 dA = \frac{\tau_{\max}}{r} I_p$$
$$\tau_{\max} = \frac{Tr}{I_p}, \quad \tau = \frac{T\rho}{I_p}$$

 $I_p = \int_A \rho^2 dA$ = Polar Moment of Inertia

For Circular Bars



$$I_P = \frac{\pi r^4}{2} = \frac{\pi d^4}{32}$$

For Circular Tubes



$$I_{p} = \frac{\pi}{2} \left(r_{2}^{4} - r_{1}^{4} \right) = \frac{\pi}{32} \left(d_{2}^{4} - d_{1}^{4} \right)$$
$$= \frac{\pi r t}{2} \left(4r^{2} + t^{2} \right) = \frac{\pi d t}{4} \left(d^{2} + t^{2} \right)$$

where
$$r = \frac{r_1 + r_2}{2}$$
 and $d = \frac{d_1 + d_2}{2}$

If $d_1 \approx d_2$, i.e., $t \ll d$, then $I_p \approx 2\pi r^3 t = \frac{\pi d^3 t}{4}$



$$\tau = \frac{T\rho}{I_P}, \quad \tau_{\max} = \frac{Tr}{I_P}$$

$$\phi = \frac{TL}{GI_p}$$

Circular tube in torsion.





. Three failure modes of a torqued specimen: (a,b): material failure in solid shaft, (c): wall buckling in thin walled tubular shaft.

Angle of Twist

$$\tau = G\gamma$$

$$\tau = \frac{\rho}{r}\tau_{\max} = \frac{T\rho}{I_p}$$
Recall $\tau = G\rho\theta \implies \theta = \frac{\tau}{G\rho} = \frac{T}{GI_p}$
Recall $\phi = \theta L \Rightarrow \qquad \phi = \frac{TL}{GI_p}$

$$k_T = \frac{GI_p}{L} = \text{Torsional Rigidity (Stiffness)}$$



This rotation is called the *twist angle* φ . *The twist angle per unit of x-length is* called the *twist rate* : $\theta = d\varphi/dx$.

$$\frac{d\phi}{dx} = \frac{\gamma_{max}}{R} = \frac{\gamma}{\rho} \quad \text{so} \quad \gamma = \rho \frac{d\phi}{dx}$$
$$\gamma = \frac{\tau}{G} = \frac{T\rho}{GJ} = \rho \frac{d\phi}{dx}$$

$$\frac{d\phi}{dx} = \frac{T}{GJ}$$



This is the twist rate formula. To find the twist angle ϕ_{BA} , where subscripts identify the angle measurement endpoints, integrate along the length of the shaft:

$$\phi_{BA} = \phi_B - \phi_A = \phi_B - \mathbf{0} = \phi_B = \int_0^L d\phi = \int_0^L \frac{d\phi}{dx} dx = \int_0^L \frac{T}{GJ} dx.$$

If T, G and J are constant along the shaft:

$$\phi_{BA} = \frac{T}{GJ} \int_0^L dx = \frac{TL}{GJ}$$

D=30mm **Bar in torsion.** (a) Determine the torsional stiffness of the bar. ____ L=1.2m (b) If the angle of twist of the bar is 4°, what is the maximum shear stress? What is the maximum shear strain (in radians)? $\tau_{\max} = \frac{Tr}{I_{\text{B}}} = \frac{Td}{2I_{\text{B}}} = \left(\frac{GI_{P}\phi}{I_{\text{C}}}\right) \left(\frac{d}{2I_{\text{B}}}\right)$ L = 1.2 m d = 30 mm $G = 28 \text{ GPa} \qquad \Phi = 4^{\circ}$ $\tau_{\max} = \frac{Gd\phi}{2I}$ (a) TORSIONAL STIFFNESS = (28 GPa)(30 mm)(0.069813 rad) $k_T = \frac{GI_P}{L} = \frac{G\pi d^4}{32L} = \frac{(28 \text{ GPa})(\pi)(30 \text{ mm})^4}{32(1.2 \text{ m})}$ 2(1.2 m)= 24.43 MPa $k_T = 1860 \text{ N} \cdot \text{m} \quad \longleftarrow$ MAXIMUM SHEAR STRAIN (b) MAXIMUM SHEAR STRESS Hooke's Law: $\phi = 4^{\circ} = (4^{\circ})(\pi/180)$ rad = 0.069813 rad $\gamma_{\max} = \frac{\tau_{\max}}{G} = \frac{24.43 \text{ MPa}}{28 \text{ GPa}}$ $\phi = \frac{TL}{GL} \quad T = \frac{GI_F\phi}{I}$

$$\gamma_{\rm max} = 873 \times 10^{-6} \text{ rad} \quad \Leftarrow$$

A plastic bar of diameter d = 50 mm is to be twisted by torques T (see figure) until the angle of rotation between the ends of the bar is 5.0° .

If the allowable shear strain in the plastic is 0.012 rad, what is the minimum permissible length of the bar?



- (a) SHEAR STRESS AT OUTER SURFACE
- (b) SHEAR STRESS AT INNER SURFACE
- (c) RATE OF TWIST
- (d) Shear stress diagram

$$I_P = \frac{\pi}{32}(d_2^4 - d_1^4) = 39.88 \times 10^6 \text{ mm}^4$$

$$d_2 = 150 \text{ mm}$$
 $r_2 = 75 \text{ mm}$
 $d_1 = 100 \text{ mm}$ $r_1 = 50 \text{ mm}$
 $G = 75 \text{ GPa}$
 $T = 16 \text{ kN} \cdot \text{m}$



(a) SHEAR STRESS AT OUTER SURFACE

$$\tau_2 = \frac{Tr_2}{I_P} = \frac{(16 \text{ kN} \cdot \text{m})(75 \text{ mm})}{39.88 \times 10^6 \text{ mm}^4}$$

= 30.1 MPa \leftarrow

$$\theta = \frac{T}{GI_P} = \frac{16 \text{ kN} \cdot \text{m}}{(75 \text{ GPa})(39.88 \times 10^6 \text{ mm}^4)}$$

 $\theta = 0.005349 \text{ rad/m} = 0.306^{\circ}/\text{m}$

(d) Shear stress diagram

(b) SHEAR STRESS AT INNER SURFACE

$$\tau_1 = \frac{Tr_1}{I_P} = \frac{r_1}{r_2} \tau_2 = 20.1 \text{ MPa}$$



Non-Uniform Torsion

Case 1. Bar consisting of Prismatic segments with constant torque throughout each segment

$$\sum T = T_1 + T_2 - T_3 + T_4 = 0$$

Cross sections between CD $\sum T = T_1 + T_2 - T_3 + T_{CD} = 0$ $\Rightarrow T_{CD} = -T_1 - T_2 + T_3$

Cross sections between BC $\sum T = T_1 + T_2 + T_{BC} = 0$ $\Rightarrow T_{BC} = -T_1 - T_2$

Cross sections between AB

$$\sum T = T_1 + T_{AB} = 0 \Longrightarrow T_{AB} = -T_1$$



Find the shear stress in each part of the shaft Find the angle of twist of point B relative to D





Free-body diagrams.



Shear stress in each segment:



Angle of twist in each segment



Total angle of twist	Total	angle	of	twist
----------------------	-------	-------	----	-------



Calculate the following quantities: (a) the maximum shear stress τ_{max} in the shaft, and (b) the angle of twist ϕ_C (in degrees) at end C.

$$d_{1} = 2.25 \text{ in.} \qquad L_{1} = 30 \text{ in.} \\ d_{2} = 1.75 \text{ in.} \qquad L_{2} = 20 \text{ in.} \\ G = 11 \times 10^{6} \text{ psi} \\ T_{1} = 20,000 \text{ lb-in.} \\ T_{2} = 8,000 \text{ lb-in.} \\ T_{2} = 8,000 \text{ lb-in.} \\ T_{BC} = \frac{16}{\pi d_{2}^{5}} = \frac{16(8,000 \text{ lb-in.})}{\pi(1.75 \text{ in.})^{5}} = \frac{7602 \text{ psi}}{7602 \text{ psi}} \\ \text{SEGMENT AB} \\ T_{AB} = T_{2} - T_{1} = -12,000 \text{ lb-in.} \\ \tau_{AB} = \left| \frac{16}{\pi d_{1}^{3}} \right| = \frac{16(12,000 \text{ lb-in.})}{\pi(2.25 \text{ in.})^{3}} = 5365 \text{ psi} \\ \phi_{AB} = \frac{T_{AB}L_{1}}{G(I_{p})_{AB}} = \frac{(-12,000 \text{ lb-in.})(30 \text{ in.})}{(11 \times 10^{6} \text{ psi})\left(\frac{\pi}{32}\right)(2.25 \text{ in.})^{4}} \quad \phi_{C} = \phi_{AB} + \phi_{BC} = (-0.013007 + 0.015797) \text{ rad} \\ = -0.013007 \text{ rad} = 0.002790 \text{ rad} = 0.15^{6} \\ \text{Figure 1} = 0.002790 \text{ rad} = 0.00202790 \text{ rad} = 0.00202790 \text{ rad} = 0.0020$$

The copper pipe has an outer diameter of 40 mm and an inner diameter of 37 mm. If it is tightly secured to the wall at A and three torques are applied to it as shown, determine the absolute maximum shear stress developed in the pipe. $\tau_{max} = \frac{T_{max} c}{J} = \frac{90(0.02)}{\frac{\pi}{2} (0.02^4 - 0.0185^4)}$



= 26.7 MPa

The solid 30-mm-diameter shaft is used to transmit the torques applied to the gears. Determine the absolute maximum shear stress on the shaft.

Internal Torque: As shown on torque diagram.

Maximum Shear Stress: From the torque diagram $T_{max} = 400 \text{ N} \cdot \text{m}$. Then, applying torsion Formula.

$$\tau_{\max}^{\text{abs}} = \frac{T_{\max} c}{J}$$

= $\frac{400(0.015)}{\frac{\pi}{2} (0.015^4)} = 75.5 \text{ MPa}$





The coupling is used to connect the two shafts together. Assuming that the shear stress in the bolts is *uniform*, determine the number of bolts necessary to make the maximum shear stress in the shaft equal to the shear stress in the bolts. Each bolt has a diameter d.

n is the number of bolts and F is the shear force in each bolt.

$$T - nFR = 0; \qquad F = \frac{T}{nR}$$
$$\tau_{\text{avg}} = \frac{F}{A} = \frac{\frac{T}{nR}}{\frac{\pi}{(\frac{\pi}{4})d^2}} = \frac{4T}{nR\pi d^2}$$

Maximum shear stress for the shaft:

$$\tau_{\max} = \frac{Tc}{J} = \frac{Tr}{\frac{\pi}{2}r^4} = \frac{2T}{\pi r^3}$$
$$\tau_{\max} = \tau_{\max}; \quad \frac{4T}{nR\pi d^2} = \frac{2T}{\pi r^3}$$
$$2r^3$$

 $n = \frac{2 r^3}{R d^2}$





5-14. The solid 50-mm-diameter shaft is used to transmit the torques applied to the gears. Determine the absolute maximum shear stress in the shaft.

The internal torque developed in segments AB, BC and CD of the shaft are shown in Figs. a, b and c.

The maximum torque occurs in segment *AB*. Thus, the absolute maximum shear stress occurs in this segment. The polar moment of inertia of the shaft is $J = \frac{\pi}{2} (0.025^4) = 0.1953 \pi (10^{-6}) \text{m}^4$. Thus,

$$(\tau_{\max})_{abs} = \frac{T_{AB}c}{J} = \frac{250(0.025)}{0.1953\pi(10^{-6})} = 10.19(10^{6})Pa = 10.2 MPa$$
 Ans.





Thin walled Tubes



Torsion formula for thin walled tubes



 $dF = \tau(t ds) = f ds$

The moment of dF about an arbitrary point O is

 $dM_{\circ} = b dF = b (\mathbf{f} ds) = \mathbf{f} (b ds)$ $dA = \frac{1}{2} b ds \rightarrow b ds = 2 dA$ now $dM = \mathbf{f} (2dA)$ $T = \oint dM_{\circ} = \oint \mathbf{f} (2dA)$







Angle of twist ϕ for a thin-walled tube



Problem 3.10-6 Calculate the shear stress τ and the angle of twist ϕ (in degrees) for a steel tube (G = 76 GPa) having the cross section shown in the figure. The tube has length L = 1.5 m and is subjected to a torque $T = 10 \text{ kN} \cdot \text{m}.$ | *I* = 8 mm $r = 50 \, \text{mm}$ $r = 50 \, \text{mm}$ $A_m = \pi (50 \text{ mm})^2 + 2(100 \text{ mm})(50 \text{ mm})$ = 17,850 mm² $L_m = 2b + 2\pi r$ $= 2(100 \text{ mm}) \pm 2\pi(50 \text{ mm})$ = 514.2 mm $b = 100 \, \mathrm{mm}$ $J = \frac{4LA_m^2}{L_m} = \frac{4(8 \text{ mm})(17,850 \text{ mm}^2)^2}{514.2 \text{ mm}}$ ANGLE OF TWIST $\frac{TL}{GJ} = \frac{(10 \text{ kN} \cdot \text{m})(1.5 \text{ m})}{(76 \text{ GPa})(19.83 \times 10^6 \text{ mm}^4)}$ SHEAR STRESS = 0.00995 rad 10 kN · m = 0.570° 2(8 mm)(17,850 mm²) 241-= 35.0 MPa

Outer dimensions:
2.0 in. × 2.0 in.

$$G = 4 \times 10^6$$
 psi
 $T = 3000$ lb-in.
 $\tau_{allow} = 4500$ psi
 $\theta_{allow} = 0.01$ rad/ft $= \frac{0.01}{12}$ rad/in.
THICKNESS *t* BASED UPON SHEAR STRESS
 $\tau = \frac{T}{2tA_m} + tA_m = \frac{T}{2\tau} - t(b-t)^2 = \frac{T^6}{2\tau}$
UNITS: $t = in.$ $b = in.$ $T = lb-in.$ $\tau = psi$
 $t(2.0 in. -t)^2 = \frac{3000}{2(4500-psi)} = \frac{1}{3} in.^3$
 $3t(2-t)^2 - 1 = 0$
Solve for *t*: $t = 0.0915$ in.

Centerline dimension = b - t

$$A_{m} = (b - t)^{2} \qquad L_{m} = 4(b - t)$$

$$J = \frac{4tA_{m}^{2}}{L_{m}} = \frac{4t(b - t)^{4}}{4(b - t)} = t(b - t)^{3}$$

THICKNESS / BASED UPON RATE OF TWIST

$$\theta = \frac{T}{GJ} = \frac{T}{Gt(b-t)^3} \qquad t(b-t)^3 = \frac{T}{G\theta}$$

UNITS: t = in. $G = psi \theta = rad/in$.

 $t(2.0 \text{ in.} - t)^{3} = \frac{3000 \text{ lb-in}}{(4 \times 10^{6} \text{ psi})(0.01/12 \text{ rad/in.})}$ $= \frac{9}{10}$ $10t(2 - t)^{3} - 9 = 0$ Solve for t:t = 0.140 in.ANGLE OF TWIST GOVERNS

 $t_{\rm min} = 0.140$ in.