

جامعة البلقاء التطبيقية

كلية الهندسة التكنولوجية

هندسة الطاقة الكهربائية

تلخيص

تحليل أنظمة كهربائية (1)

إعداد: محمود يوسف صالح

بسم الله الرحمن الرحيم

* هذا الملخص يحتوي على تلخيص لمادة تحليل أنظمة كهربائية (1)، وقد وضعت فيه شرح الدروس وإثبات كل نظرية حصلنا عليها وجميع المعلومات المتعلقة بها وفي النهاية وضعت أمثلة على شرح للمواضيع وأسئلة عامة تجمع بين عدة أفكار لا بد من حلها وفهم فكرتها

* استعنت بكتابة هذا الملخص بدفتر تحليل (1) الذي كنت أتابع به جميع المحاضرات عند المهندس ياسين الشبول وأيضاً ببعض الكتب، ثم أسئلة السنوات

* هذا الملخص من إعداد الطالب: محمود يوسف صالح

- * المراجع :
- 1) Modern Power System Analysis
 - 2) Power System Analysis

* وضعت فيه هذا الملخص جميع المعلومات التي تمكنت من مراجعتها والوصول إليها لكن لا بد من العودة إلى الكتاب لقراءته ودراسته وفهمه جيداً ومن ثم حل الأسئلة المتعلقة بالمادة المطلوبة.

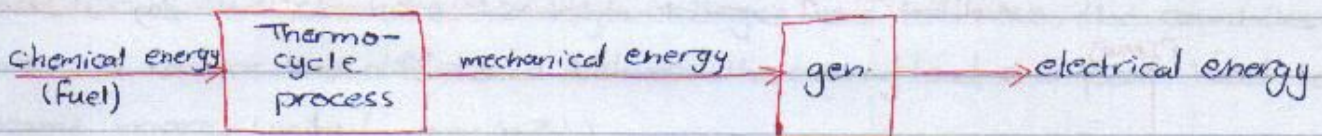
Power System Analysis

* Introduction to power system analysis-

- Electrical energy is generally produced by-

- 1) Burning of fuels (gas, oil, coal, ---).
- 2) Hydro sources.
- 3) Nuclear energy.
- 4) Other sources (solar cells, wind energy, ---)

* By burning of fuels or nuclear energy is transformed to mechanical energy through thermodynamic cycle process, then we used that mechanical energy to move a turbine (generator) to get electricity.



- The thermocycle process is inefficient process.
 - 45% mechanical energy
 - 55% heat (losses)
- With increasing the rated power of the generated unit, the efficiency increase
- Generally, transmitting electrical energy is cheaper than transmitting the electrical quantity of fuel. Generated station is build next/near to sources
- What is said before is not valid for nuclear energy because the amount of fuel for nuclear station is little so it's build not so far from the local center

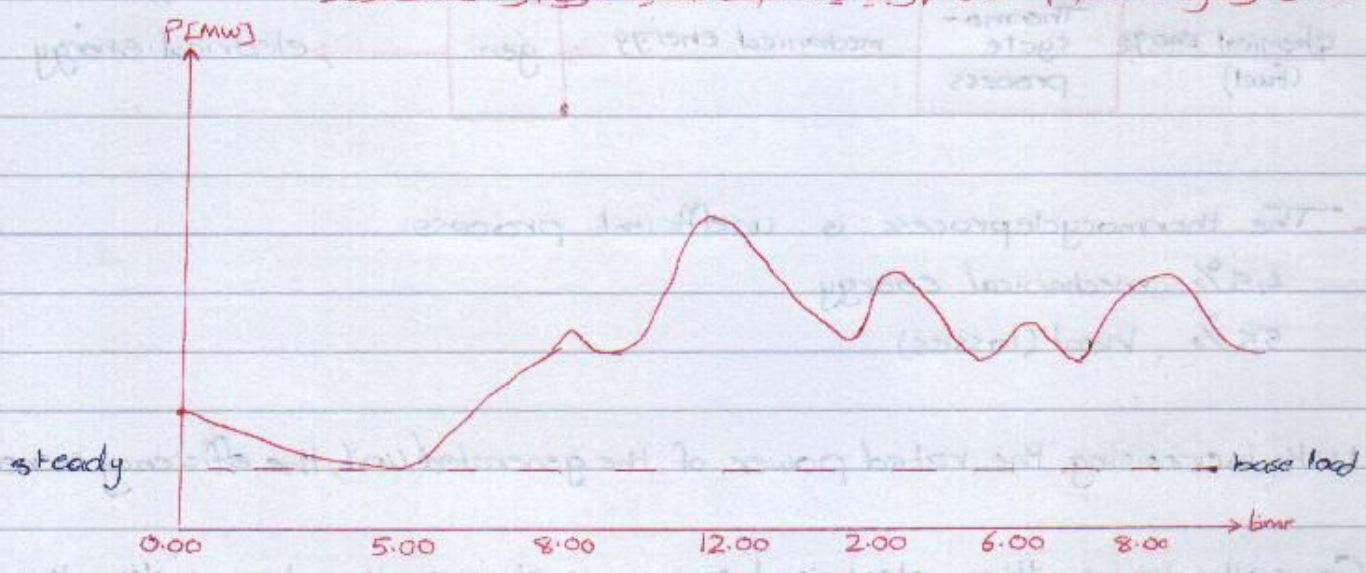
* ملاحظة 8 - يتم تخزين الطاقة الكهربائية عن battery or pumping storage scheme

* The annual consumption of electrical energy is measure of development of the country.

* Characteristic of Electrical Energy:

- 1) electrical energy cannot be stored except in small quantity.
- 2) electrical companies don't have a control on the demand, except in small quantity but the electrical generator generate active and reactive power as required from the customer.
- 3) electrical demand not constant, it's variable with time, this change depends on time of day, monthly, weekly, -----

مثلاً لو درست نظام حمل كهربائي في منطقة معينة في أوقات مختلفة



يختلف الحمل الكهربائي باختلاف الوقت والفصل
 نظام الحمل الكهربائي مرتبط بخامية Load Curve

- From this curve we can conclude that the load consist of:

- Steady part (base load)
- predicted which can be known from previous history
- purely random component

- The load curve is described what is called load factor

$$\text{load factor} = \frac{\text{av. load}}{\text{peak load}} < 1$$

load factors the average power (load) divided by peak load over a period of time less than 1

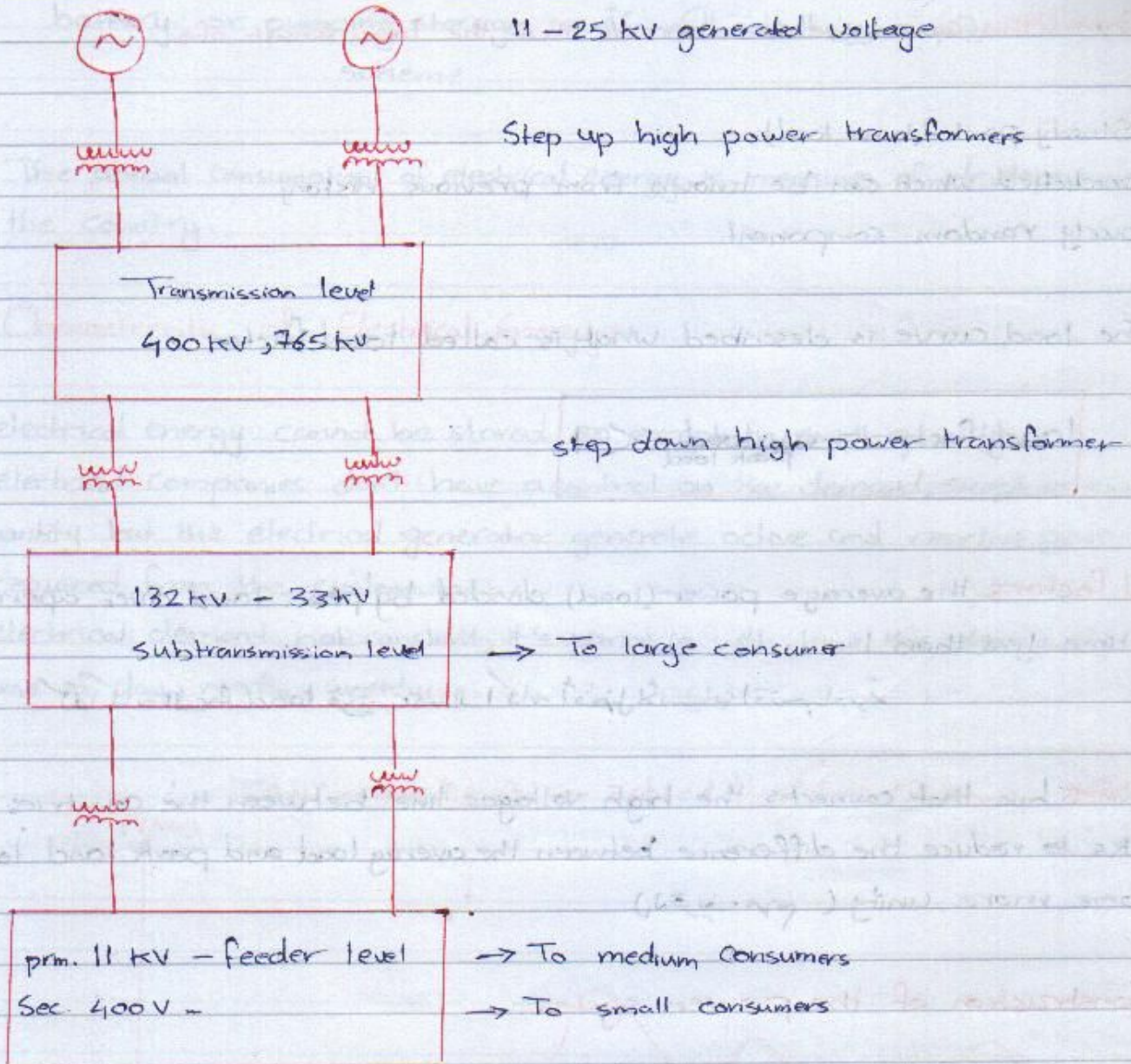
هذا هو load factor وهو نسبة الأحمال المتوسطة إلى أعلى الأحمال المتوسطة

Tie lines line that connects the high voltages line between the countries and works to reduce the difference between the average load and peak load to become more unity (التقريب)

* Construction of the power system

- The components of power system are-

- generating stations.
- transmission lines.
- distribution systems
- Other Component (switches, protection appliances, ...)



يتم رفع الفولتية لتقليل التيار المار في أسلاكه وبالتالي خفض التكلفة لأن $P = \frac{V^2}{R}$ لقوة تصبح أعلى

* أمثلة رفع الفولتية :

- ١) تفريغ جزئي حول الخط (partial discharge around the conductor) مما يؤدي إلى ضياعات في الطاقة ونشوء ظواهر Corona (تتشع لاحقاً)
- ٢) تداخل المجالات الكهربائية القوية مع موجات البث الراديوي (Radio interface)
- ٣) صعوبات تصمم عوازل لهذه الفولتية العالية
- ٤) صعوبة تصميم قواطع لهذه الفولتية العالية (Circuit Breaker)

* The most common generating stations:

1) Thermal Stations تعمل عن طريق حرق الوقود الأحفوري وتسخين المياه والاستفادة من ضغط البخار الذي يعمل في درجات حرارة عالية ويطلق هذا البخار على توربينات تعمل على تحويله المولد مشكلة تباين وتطلب وقت كبير لتجهيزها وتشغيلها وبالتالي لا يلبي الاستجابة في حالة peak load

2) Hydrolic Stations تعمل بسرعة ولكن تحتاج إلى تصميم مبدئي صعب ويحتاج وقت لبنائه

3) Nuclear station تعتمد على مبدأ الانشطار النووي لذرة اليورانيوم ^{235}U (الانشطار النووي) تستعمل الطاقة لتخزين المياه وتوليد البخار المضغوط

$$^{235}\text{U} + \text{neutrons} \rightarrow ^{238}\text{U} + \text{heat}$$

$$^{238}\text{U} + \text{neutrons} \rightarrow ^{239}\text{U} (\text{plutonium}) + \text{heat}$$
مشاكلها: صعب التخلص من النفايات فيه بحظيرة لنا ونقل على الباص load حساساتها: توليد الكهرباء غير مكلف وتوليد كميات كبيرة

4) Gas Stations يستعمل الغاز (1-8) استقاله كوقود في محركات الاحتراق الداخلي التي تولد المولد تسليطه تحت ضغط عالي على توربينات المولد

5) Diesel engine Stations يتم استقالها كحطرات ديم/ احتياط للشبكة في حالة system down كفاءة قليلة ولكنها سريعة التشغيل

6) Solar energy sources يتم التوليد بواسطة تسخين المياه وبالتالي توليد ضغط البخار أو توليد الكهرباء (DC) وتحويلها إلى (AC) عن طريق inverter

7) Winds generators استغلال طاقة الرياح

8) Geothermal Sources طريقة استغلال ضغط البخار الصاعد من التيارات الجوفية في باطن الأرض أو استغلال الحرارة الصاعدة من البراكين

9) Tidal Sources استغلال طاقة المد والجزر للبخار

* Basic Concepts

- Electrical quantity can be represented in two forms:-

- 1) instantaneous values (as a function of time).
- 2) phasors.

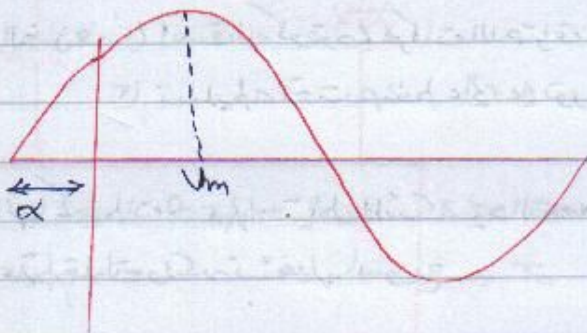
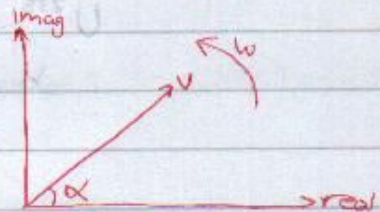
1) as a function

$$V(t) = V_m \sin(\omega t + \alpha)$$

(S) ω rad/sec α phase shift

$$V = |V| \angle \alpha = |V| e^{j\alpha} \quad \text{polar form}$$

$$V = |V| [\cos \alpha + j \sin \alpha] \quad \text{cartesian form}$$

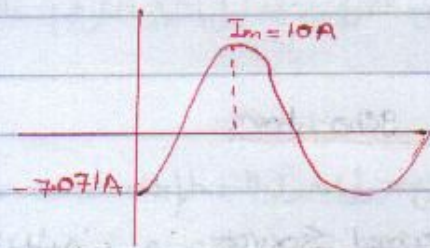


$$V(t) = V_m \sin(\omega t + \alpha)$$

$$= \sqrt{2} |V| \sin(\omega t + \alpha)$$

$$|V| = \frac{V_m}{\sqrt{2}}$$

e.g. for the following sinusoidal current waveform shown, express the current as a function of time



$$i(t) = I_m \sin(\omega t + \alpha)$$

$$i(t) = 10 \sin(\omega t + \alpha)$$

$$\text{At } \omega t = 0, i(t) = -7.071$$

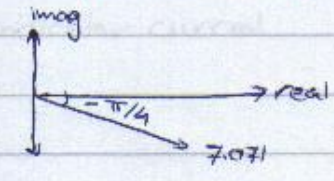
$$-7.071 = 10 \sin \alpha$$

$$\sin \alpha = \frac{-7.071}{10}$$

$$\alpha = -\frac{\pi}{4}$$

$$i(t) = 10 \sin(\omega t - \frac{\pi}{4})$$

draw the phasor diag of current



express in polar and cartesian form

$$I = 7.071 \angle -\pi/4 = 7.071 e^{-j\pi/4}$$

$$I = 7.071 [\cos(-\pi/4) + j\sin(-\pi/4)] = 5 - j5$$

if the $f = 50\text{HZ}$ find the period

$$f = \frac{1}{T} \Rightarrow T = \frac{1}{50} \text{ sec} = 20 \text{ ms}$$

find the time t_1 (x-axis)

$$2\pi \rightarrow 20 \text{ ms}$$

$$\frac{\pi}{4} \rightarrow ?? \Rightarrow t_1 = \frac{20 \text{ ms} \times \pi/4}{2\pi} = 2.5 \text{ ms}$$

* Power in Single phase AC Circuits

$$v(t) = V_m \sin \omega t$$

$$i(t) = I_m \sin(\omega t - \phi)$$

$$P(t) = v(t) \cdot i(t)$$

$$\begin{aligned} P(t) &= V_m \cdot I_m \sin \omega t \sin(\omega t - \phi) \quad \text{متكافئة} \\ &= V_m \cdot I_m \sin \omega t [\sin \omega t \cos \phi - \cos \omega t \sin \phi] \\ &= V_m \cdot I_m \sin^2 \omega t \cos \phi - V_m I_m \sin \phi \sin \omega t \cos \omega t \\ &= \frac{V_m}{\sqrt{2}} \cdot \frac{I_m}{\sqrt{2}} \cos \phi [1 - \cos 2\omega t] - \frac{V_m}{\sqrt{2}} \cdot \frac{I_m}{\sqrt{2}} \sin \phi \sin 2\omega t \\ &= V \cdot I \cos \phi [1 - \cos 2\omega t] - V \cdot I \sin \phi \sin 2\omega t \quad \text{--- ①} \end{aligned}$$

$$\begin{aligned} P(t) &= V \cdot I \cos \phi - V \cdot I \cos \phi \cos 2\omega t - V \cdot I \sin \phi \cdot \sin 2\omega t \\ &= V \cdot I \cos \phi - V \cdot I [\cos \phi \cos 2\omega t + \sin \phi \cdot \sin 2\omega t] \\ &= V \cdot I \cos \phi - V \cdot I \cos(2\omega t - \phi) \quad \text{--- ②} \end{aligned}$$

$$\sin(x - y) = \sin x \cos y - \cos x \sin y$$

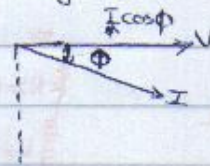
$$\sin^2 \omega t = \frac{1 - \cos 2\omega t}{2}$$

$$\sin \phi \cos \phi = \frac{\sin 2\phi}{2}$$

- From equ. 2 it's clear that the inst power is a pulsating with frequency double of that of the frequency voltage waveform and the average value equal $V \cdot I \cdot \cos \phi$ which is defined as active power

- From equ. 1 we find that the inst power contain from two terms, first one never goes negative it has average value equal $V \cdot I \cdot \cos \phi$ which called the active power the second one has average value equal zero and having a max value which defined as a reactive power.

- Reactive power can be defined as a product of voltage and the component of perpendicular current

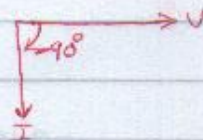


⇒ For resistive load $\phi = 0$

$P = V \cdot I$, $Q = 0$

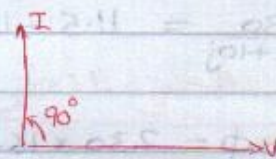
⇒ For inductive load

$P = 0$, $Q < 0$



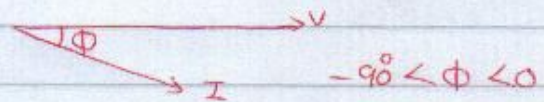
⇒ For capacitive load

$P = 0$, $Q > 0$



⇒ For res, ind load

$P > 0$, $Q < 0$



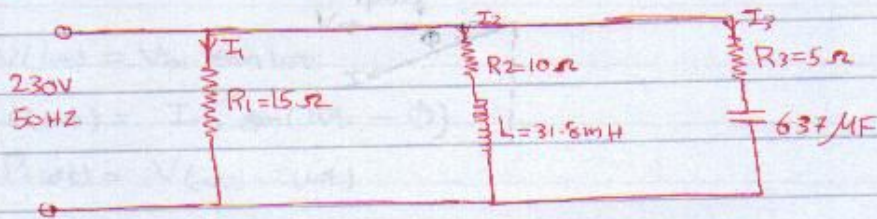
⇒ For res, cap load

$P > 0$, $Q > 0$

consume generate



Ex: for the following circuit Calculate the variable power absorbed (P, Q)



$$I_1 = \frac{230 \angle 0^\circ}{15} = 15.33 \text{ A}$$

unity $\phi=0$

$$P = V \cdot I = 230 \times 15.33 = 3526.6 \text{ W}$$

$$Q = 0$$

} Res

$$Z = R_2 + j\omega L = 10 + j2\pi \times 50 \times 31.8 \times 10^{-3} = 10 + 10j$$

$$I = \frac{V}{Z} = \frac{230}{10 + 10j} = 11.5 - 11.5j = 16.26 \angle -45^\circ$$

$$P = V \cdot I \cos \phi = 230 \times 16.26 \times \cos -45^\circ = 2644.44 \text{ W}$$

$$Q = V \cdot I \sin \phi = 230 \times 16.26 \times \sin -45^\circ = -2644.44 \text{ VA}$$

} Res, ind

$$Z = R_3 - j/\omega C = R - \frac{j}{2\pi \times 50 \times 637 \times 10^{-6}} = 5 - 5j$$

$$I = \frac{V}{Z} = \frac{230}{5 - 5j}$$

$$P = 230 \times 32.52 \times \cos 45^\circ = 5288.87 \text{ W}$$

$$Q = 5288.87 \text{ W}$$

} Cap, Res

* The Concept of Complex power

$$V = |V| \angle \phi_v$$

$$I = |I| \angle \phi_i$$

$$S = V \cdot I = |V| \cdot |I| \angle (\phi_v + \phi_i)$$

but $I^* = |I| \angle \phi_i$

$$S = V \cdot I^* = |V| |I| \angle (\phi_v - \phi_i) = \underbrace{|V| |I| \cos \phi}_P + j \underbrace{|V| |I| \sin \phi}_Q$$

$$S = V \cdot I^* = P + jQ \dots \dots \dots \text{Complex Power}$$

$$|S| = \sqrt{P^2 + Q^2} \text{ VAR}$$

بعض المصطلح الأخرى

$$S = V \cdot I^*$$

but $V = I \cdot Z$

$$S = I \cdot I^* \cdot Z \Rightarrow S = Z \cdot |I|^2$$

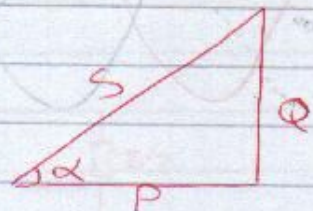
$$I = V \cdot Y$$

$$I^* = Y^* \cdot V^*$$

$$S = V \cdot V^* \cdot Y^* = Y^* \cdot |V|^2$$

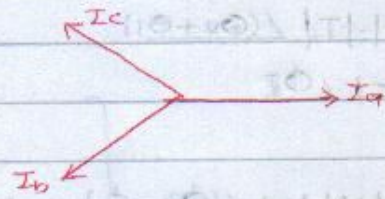
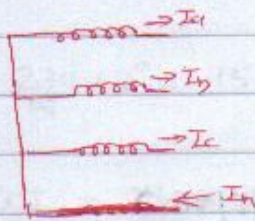
$$S = \sum S_i = (P_1 + P_2 + \dots) + j(Q_1 + Q_2 + \dots)$$

$$S = \sqrt{(P_1 + P_2 + \dots)^2 + (Q_1 + Q_2 + \dots)^2} \neq \sqrt{P_1^2 + Q_1^2} + \sqrt{P_n^2 + Q_n^2}$$

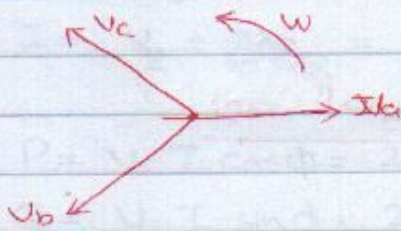


* Voltage and Current in 3-phase

- Usually 3-ph sys are symmetrical, it's such mean that the 3-phase sys are equally loaded also in I in 3phase equal in magnitude and phase shift 120°



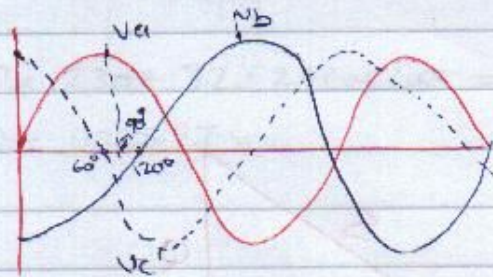
Positive Sequence



$$V_a = |V_a| \angle 0^\circ$$

$$V_b = |V_a| \angle 120^\circ$$

$$V_c = |V_a| \angle 240^\circ$$

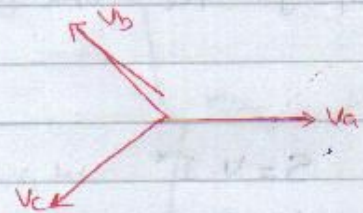


$$V_a = \sqrt{2} |V_a| \sin(\omega t)$$

$$V_b = \sqrt{2} |V_a| \sin(\omega t - 120^\circ)$$

$$V_c = \sqrt{2} |V_a| \sin(\omega t + 120^\circ)$$

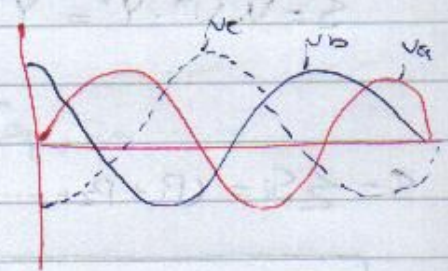
Negative Sequence



$$V_a = |V_a| \angle 0^\circ$$

$$V_b = |V_a| \angle 120^\circ$$

$$V_c = |V_a| \angle -120^\circ$$

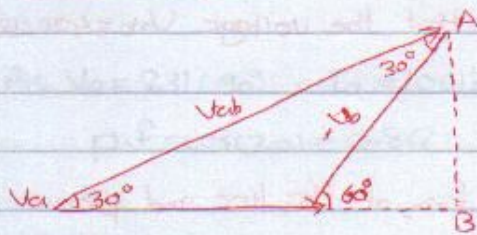


$$V_a = \sqrt{2} |V_a| \sin(\omega t)$$

$$V_b = \sqrt{2} |V_a| \sin(\omega t + 120^\circ)$$

$$V_c = \sqrt{2} |V_a| \sin(\omega t - 120^\circ)$$

+ve Sequence



نفس الشيء بالنسبة ل -ve Seq

$$V_{ab} = V_a - V_b$$

$$|V_b| \sin 60^\circ = |V_{ab}| \sin 30^\circ = \overline{AB}$$

$$|V_b| \times \frac{\sqrt{3}}{2} = |V_{ab}| \times \frac{1}{2}$$

$$|V_{ab}| = \sqrt{3} |V_b|$$

$$V_{ab} = \sqrt{3} |V_a| \angle 30^\circ$$

$$V_{bc} = V_b - V_c$$

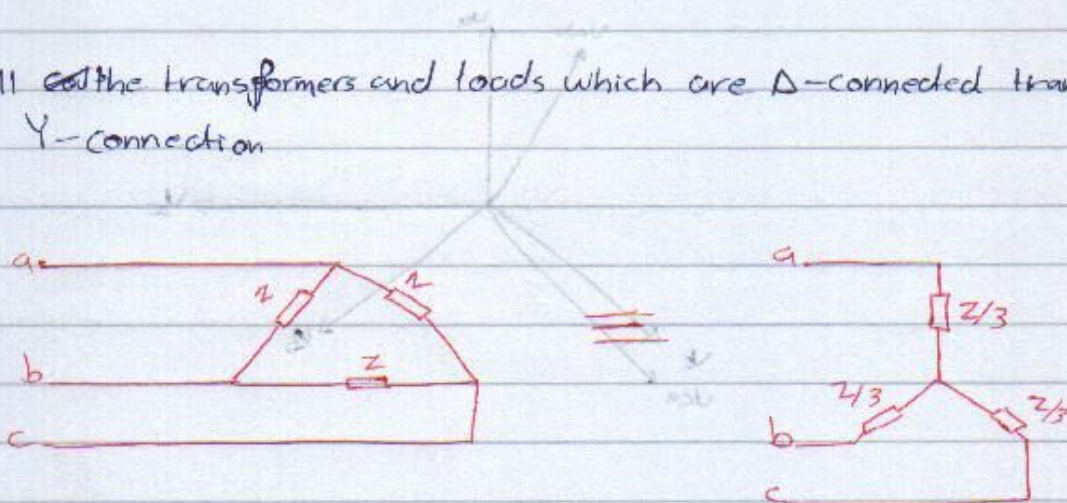
$$V_{bc} = \sqrt{3} |V_a| \angle -90^\circ = \sqrt{3} |V_a| \angle (-30^\circ - 120^\circ) = \sqrt{3} |V_a| \angle -150^\circ$$

$$V_{ca} = \sqrt{3} |V_a| \angle 150^\circ$$

$$V_{ab} + V_{bc} + V_{ca} = 0$$

Usually, all the calculations done in case of normal operation of 3-phase sys and done per phase

All the transformers and loads which are Δ -connected transferred to equivalent Y-connection



✓ ✓ [First 2011/2012]

Ex: A three phase Y-connected balanced load is supplied by a three phase positive sequence, 50 Hz, symmetrical power system. knowing that the voltage $V_{ab} = 400 \angle 120^\circ$

$$V_{ab} = 400 \angle 120^\circ, I_a = 10 \angle 120^\circ$$

a) Find the phasor expressions in polar and rectangular form, of the line and phase voltages and currents (3 marks)

$$V_{ab} = 400 \angle 120^\circ = 400 (\cos 120^\circ + j \sin 120^\circ) = -200 + j346.4$$

$$V_{bc} = 400 \angle 0^\circ = 400 (\cos 0^\circ + j \sin 0^\circ) = 400$$

$$V_{ca} = 400 \angle -120^\circ = 400 (\cos -120^\circ + j \sin -120^\circ) = -200 - j346.4$$

$$V_{ca} = \frac{400}{\sqrt{3}} \angle 90^\circ = 231 \angle 90^\circ = 231 \cos(90^\circ + j \sin 90^\circ) = j231$$

$$V_b = 231 \angle -30^\circ = 231 (\cos -30^\circ + j \sin -30^\circ) = 200 - j115.5$$

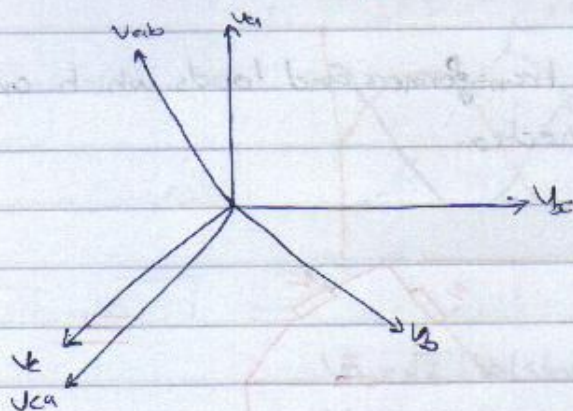
$$V_c = 231 \angle -150^\circ = 231 (\cos(-150^\circ) + j \sin(-150^\circ)) = -200 + j115.5$$

$$I_a = 10 \angle 120^\circ = 10 (\cos 120^\circ + j \sin 120^\circ) = -5 + j8.66$$

$$I_b = 10 \angle 0^\circ = 10 (\cos 0^\circ + j \sin 0^\circ) = 10$$

$$I_c = 10 \angle -120^\circ = 10 (\cos -120^\circ + j \sin -120^\circ) = -5 - j8.66$$

b) Draw the phasor diagram of the line and phase voltages (2 marks)



c) Is the load ind, cap or res and what is the power factor of load (1 mark)

As $V_a = 231 \angle 40^\circ$, $I_a = 10 \angle 120^\circ$ the load is res. capacitive

$$p.f = \cos(30) = 0.866$$

d) Find the complex, the apparent, the active and reactive powers consumed by the load (2 marks)

$$S = 3 V_a \cdot I_a^* = 3(j231)(-5 - j8.66) = 6000 - j3465$$

$$|S| = \sqrt{(6000)^2 + (3465)^2} = 6930 \text{ VA}$$

$$P = 6000 \text{ W}$$

$$Q = -3465 \text{ VAR}$$

e) Prove that $V_{ab} + V_{bc} = 3V_{an}$ (2 marks)

$$V_{ab} = 400 \angle 120^\circ = 400(\cos 120^\circ + j \sin 120^\circ) = -200 + j346.4$$

$$V_{ca} = -200 - j346.4$$

$$V_{ab} + V_{bc} = 3V_{an}$$

* Power in a balanced 3-phase System

$$P = 3 V_{ph} I_{ph} \cos \phi$$

for Y-connection

$$I_L = I_{ph}$$

$$V_{ph} = \frac{V_L}{\sqrt{3}}$$

$$P = 3 \frac{V_{line}}{\sqrt{3}} I_{line} \cos \phi = \sqrt{3} \cdot V_{line} \cdot I_{line} \cos \phi$$

for Δ -connection

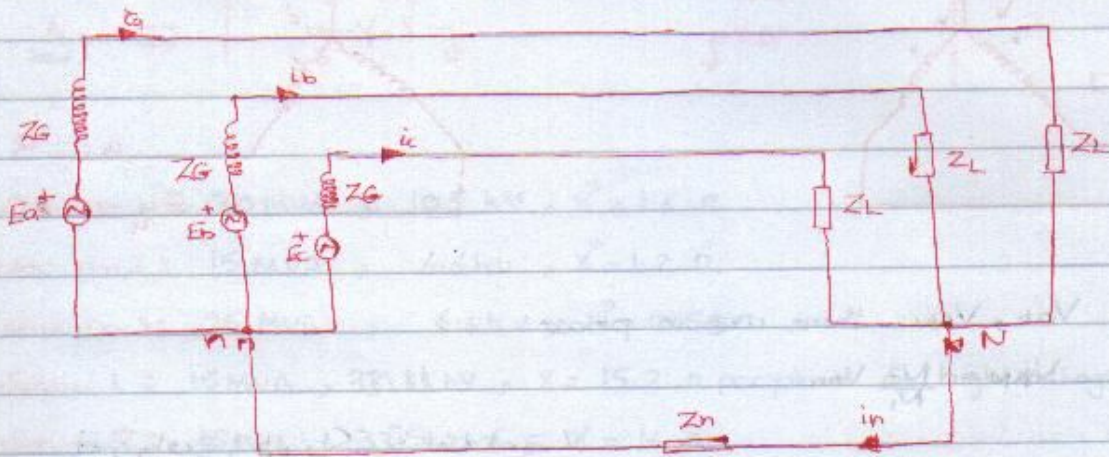
$$P = 3 V_{ph} I_{ph} \cos \phi$$

$$= 3 V_{line} \frac{I_{line}}{\sqrt{3}} \cos \phi = \sqrt{3} \cdot V_{line} \cdot I_{line} \cos \phi$$

Regardless of connection type, the power is same

* Representation of Power System Component

في أي نظام كهربائي يتم إعادة تمثيل عناصره حيث في أي نظام قسري يتم تحويل النظام إلى دائرة single phase مما يسهل على تشغيل الحسابات للعناصر والكميات الكهربائية فربما يوجد شبكة كهربائية كالتالي:

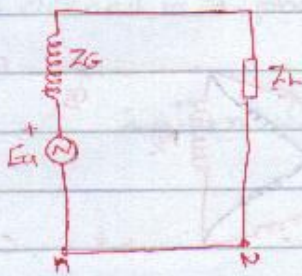


$$I_a + I_b + I_c = I_n = 0$$

$$V_n = V_N$$

يتم تبسيط النظام السابق بأخذ فاز واحد فقط كمرجع لتوصيل يكون Y لكل النظام

⇒ equivalent circuit per phase

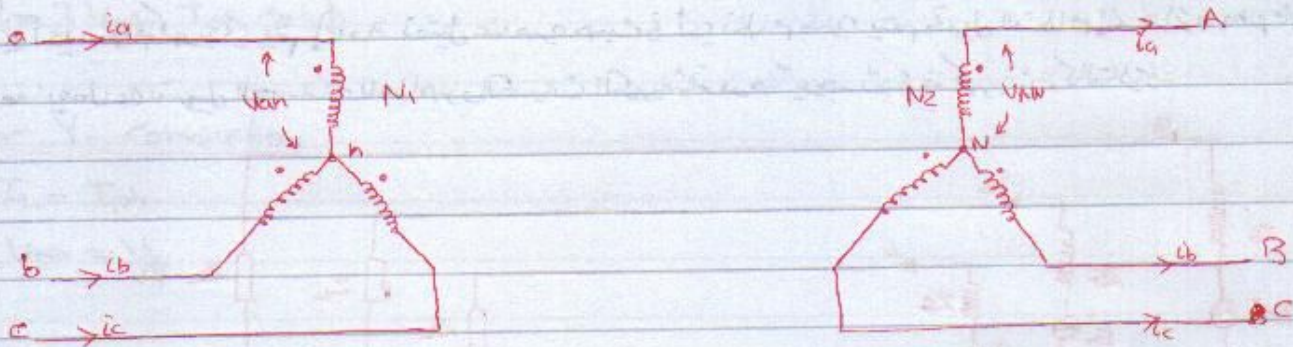


$$I_{ca} = \frac{E_a}{Z_G + Z_L}$$

طريقة الربط سوف تسبب إزاحة في القيم الطورية الطولية

أما إذا وصل هوائي الشبكة يتم تحويله إلى دائرة مكافئة شرطها أن يكون كلا الطرفين للمحول توصلة Y بحيث إذا وجدت توصلة Δ حولها إلى توصلة Y وفيما يلي شرح للطريقة ٤:

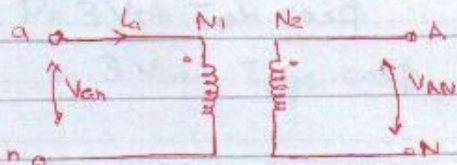
⇒ Transformers (Y-Y)



V_{an}, V_{AN} there are in phase

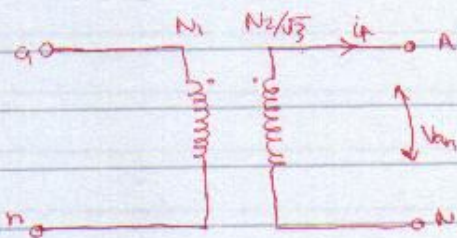
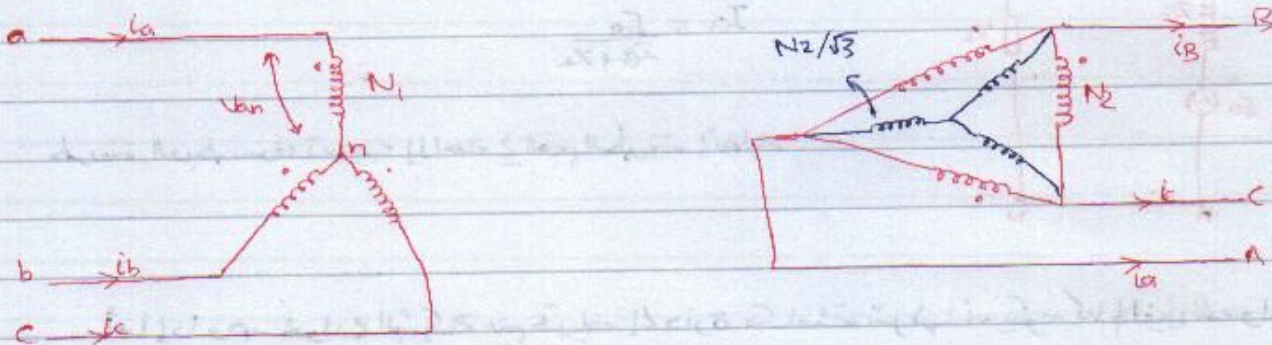
$$V_{AN} = \frac{N_2}{N_1} V_{an}$$

العلاقة بين الجهد في الطرف الثانوي والاولي



equivalent circuit of (Y-Y) per phase

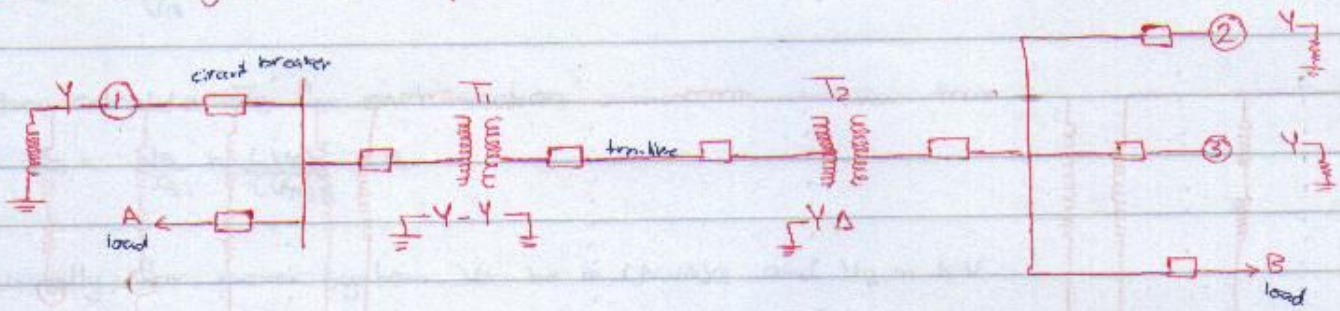
⇒ Transformers (Y-Δ)



$$V_{AN} = \frac{N_2}{\sqrt{3} N_1} V_{an} \angle 90^\circ$$

where $V_{an} = |V_{an}| \angle 0^\circ$

* One line diagram and impedance or reactance diagram



Generator no. 1: 30 MVA, 10.5 kV, $X'' = 1.6 \Omega$

Generator no. 2: 15 MVA, 6.6 kV, $X'' = 1.2 \Omega$

Generator no. 3: 25 MVA, 6.6 kV, $X'' = 0.56 \Omega$

Transformer 1: 15 MVA, 33/6.6 kV, $X = 15.2 \Omega$ per phase on high voltage side

Transformer 2: 15 MVA, 33/6.2 kV, $X = 16 \Omega$

Transmission lines: 20.5 Ω / per phase

load A: 15 MW, 11 kV, 0.9 lagging P.F

load B: 40 MW, 6.6 kV, 0.85 lagging P.F

- Generator are satisfied in 3ph power, L-L voltage per phase reactance
- The method of connection of N-point has no effect in case the system in normal operation
- load is defined in 3-phase power L-L voltage at power factor

يرسم المولد دائماً مع مقاومته الداخلية، وشكل التوصيلة Δ بحيث تكون n أرضية

مثلاً حظرات (ع) رسم الدائرة للكافة ٥-

(١) يتم رسم مع المولد مقاومته ومخاطبة (ع) التوالي (إشارة إلى P, Q للمولد)

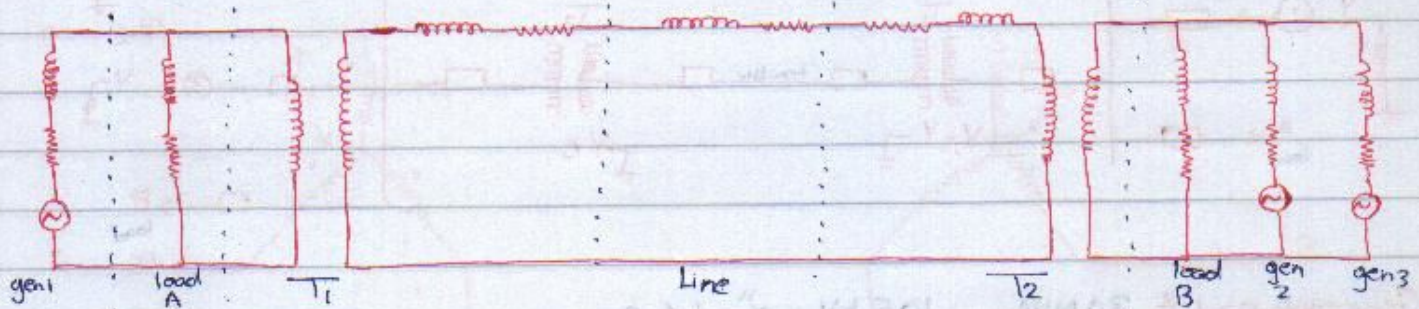
(٢) يتم تمثيل الحمل (ع) شكل مقاومته مع مخاطبة (ع) التوالي (إشارة إلى P, Q للحمل)

(٣) رمزية المحول تكون - Ideal trans.

(٤) يتم رسم مقاومته ومخاطبة للحمل (ع) الملف إنري له فولتية أعلى

(٥) يرسم القاطع (ع) شكل مربع والحمل (ع) شكل مستطيل

⇒ Impedance and reactance diagram per phase



* Per Unit Analysis

This method can be used to simplify the analysis of power system have transformers

⇒ Advantages:-

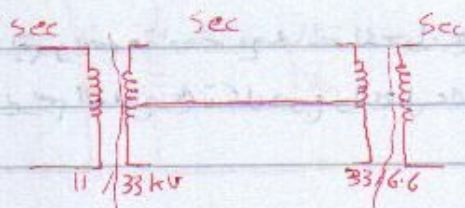
- 1) All values are given related to their rated values
- 2) Simply the analysis of the circuits have transformers
- 3) V, I values of power system under load operation are around 1 (\pm error)

$$\text{P.U value} = \frac{\text{actual value}}{\text{base value}}$$

⇒ P.U analysis is Single phase Circuits

$(VA)_B$ Base Voltamper is selected for a system and it's common for all system.

V_B Base Voltage is selected for one section and calculated to other system



كل مقطع يغير الفولتية يعتبر section

$$I_B = \frac{(VA)_B}{V_B} \text{ A}$$

then calculate Z_B for each section

$$Z_B = \frac{V_B}{I_B} = \frac{(V_B)^2}{(VA)_B} \Omega$$

usually, for power system VA be in $(MVA)_B$ and V_B in kV

$$I_B = \frac{1000 \times (MVA)_B}{(kV)_B} \text{ A} \quad \text{A (متريناهah}$$

$$Z_B = \frac{V_B}{I_B} = \frac{1000 \times (kV)_B}{1000 \times (MVA)_B} = \frac{(kV)_B^2}{(MVA)_B} \Omega$$

⇒ For 3-phase System

- 1) Select total 3-phase base VA in MVA
- 2) Select L-L voltage in $(kV)_B$ for one section and calculated for other section according to transformer ratio:

$$I_B = \frac{1000 (MVA)_B}{\sqrt{3} \times (kV)_B}$$

$$Z_B = \frac{(kV)_B}{\sqrt{3} \times I_B} = \frac{(kV)_B \times 1000}{\sqrt{3} \times \frac{1000 (MVA)_B}{\sqrt{3} (kV)_B}} = \frac{(kV)_B^2}{(MVA)_B}$$

$$Z_{actual} = Z_{p.u} \times Z_B \quad (\text{not depend on the base value})$$

$$Z_{p.u. old} \cdot Z_{B old} = Z_{p.u. new} \cdot Z_{B new}$$

$$Z_{p.u. new} = Z_{p.u. old} \frac{Z_{B old}}{Z_{B new}}$$

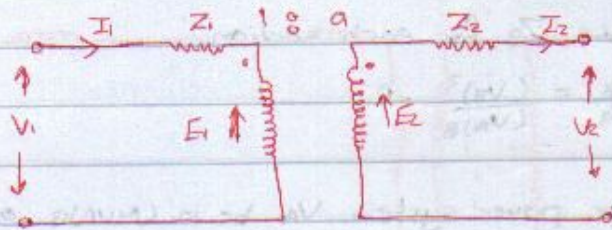
هناك حالة تحويل نسبة التحويل في transformer

$$Z_{p.u. new} = Z_{p.u. old} \cdot \frac{(kV)_B^2 old}{(kV)_B^2 new} \cdot \frac{(MVA)_B new}{(MVA)_B old}$$

* P.U representation for the transformers:

$$\frac{V_{1B}}{V_{2B}} = \frac{1}{a}, \quad \frac{E_{1B}}{E_{2B}} = \frac{1}{a}$$

$$\frac{I_{1B}}{I_{2B}} = a$$



$$V_2 = E_2 - Z_2 I_2$$

$$V_2 = a E_1 - Z_2 I_2$$

$$E_1 = V_1 - Z_1 I_1$$

$$V_2 = a(V_1 - Z_1 I_1) - Z_2 I_2$$

valid for actual values

$$(V_{2pu} * V_{2B} = a \cdot V_{1pu} V_{1B} - a Z_{1pu} Z_{1B} I_{1pu} I_{1B} - Z_{2pu} Z_{2B} \cdot I_{2pu} \cdot I_{2B}) \quad V_{2B} \text{ (constant)}$$

$$V_{2pu} = a V_{1pu} \cdot \frac{V_{1B}}{V_{2B}} - a Z_{1pu} Z_{1B} \frac{I_{1pu} I_{1B}}{V_{2B}} - Z_{2pu} Z_{2B} I_{2pu} \frac{I_{2B}}{V_{2B}} \quad \left(a \frac{Z_{1B} I_{1B}}{V_{2B}} = \frac{V_{1B}}{a \cdot V_{2B}} \right)$$

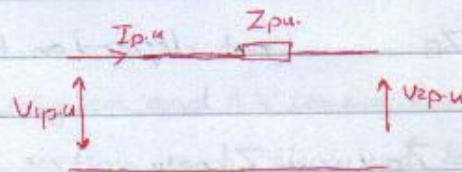
$$V_{2pu} = V_{1pu} - Z_{1pu} I_{1pu} - Z_{2pu} I_{2pu}$$

but $I_{2pu} = \frac{I_{2 \text{ actual}}}{I_{2B}} = \frac{I_{1 \text{ actual}}}{\frac{I_{1B}}{a}} = \frac{I_{1 \text{ actual}}}{I_{1B}} = I_{1pu}$

$$V_{2pu} = V_{1pu} - I_{1pu} (Z_{1pu} + Z_{2pu})$$

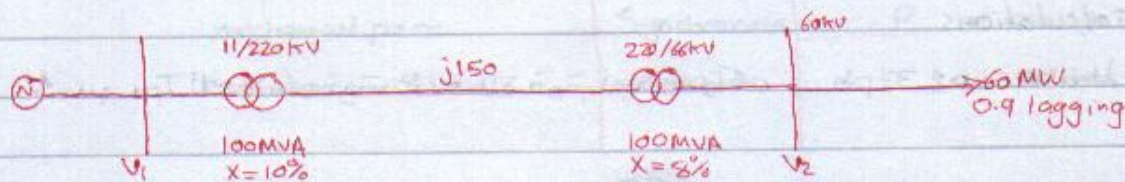
$$V_{2pu} = V_{1pu} - I_{1pu} \cdot Z_{pu}$$

the equivalent circuits



للانسان

E.g.: For the 3-phase System. A load 60 MW is connected to the 66 kV onto bus, if the voltage at the load bus be maintain as 60 kV. Calculate the terminal voltage at generated bus and the value of V_1 must be to obtain a 60 kV at V_2



يعني كم فولتية V_1 التي تجعل فولتية الـ 60kV load

We choose $(MVA)_B = 100 \text{ MVA}$ as a common for all system.

select $(kV)_B$ for the transmission line = 220 kV

Gen. Sec $(MVA)_B = 100 \text{ MVA}$, $(kV)_B = 11 \text{ kV}$

$$I_B = \frac{1000 \times (MVA)_B}{\sqrt{3} \times (kV)_B} = \frac{1000 \times 100}{\sqrt{3} \times 11} = 5248.6 \text{ A}$$

$$Z_B = \frac{(kV)_B^2}{(MVA)_B} = \frac{(11)^2}{100} = 1.21 \Omega$$

Trn. line $(MVA)_B = 100 \text{ MVA}$, $(kV)_B = 220 \text{ kV}$

$$I_B = \frac{1000 \times (MVA)_B}{\sqrt{3} \times (kV)_B} = \frac{1000 \times 100}{\sqrt{3} \times 220} = 262.4 \text{ A}$$

$$Z_B = \frac{(kV)_B^2}{(MVA)_B} = \frac{(220)^2}{100} = 484 \Omega$$

Load Sec $(MVA)_B = 100 \text{ MVA}$, $(kV)_B = 66 \text{ kV}$

$$I_B = \frac{1000 \times 100}{\sqrt{3} \times 66} = 874.7 \text{ A}$$

$$Z_B = \frac{(66)^2}{100} = 43.56 \Omega$$

$$Z_{T1} \text{ pu} = 10\% = 0.1j \Omega$$

$$Z_{T2} \text{ pu} = 8\% = 0.08j \Omega$$

Now, P.U. calculations

حساب I_{pu} للخط بقدرة P العنصر قوة العنصر وتكون 3-ph rated Voltage

$$I_{\text{actual}} = \frac{P}{\sqrt{3} \times V_L \times \cos \phi} = \frac{60 \text{ MW}}{\sqrt{3} \times 66 \times 0.9} = 583 \text{ A}$$

ملاحظة لو قدرة العنصر MVA تكون بقدر Q ولا تدخل P في حساب

$$I_{pu} = \frac{I_{\text{actual}}}{I_B} = \frac{583}{874.7} = 0.667 \text{ pu} \Rightarrow I_{pu} = 0.667 \angle -25.8^\circ$$

Z_{pu} في حساب Z_{total} في نظام pu

$$Z_{pu \text{ line}} = \frac{150}{484} = 0.31 \text{ pu}$$

$$Z_{T \text{ pu}} = Z_{T1} + Z_{T2} + Z_{\text{line}} = 0.49 \text{ pu}$$

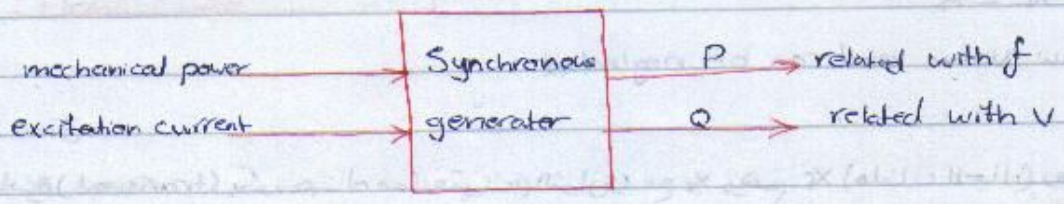
$$V_{1pu} = V_{2pu} + I_{pu} Z_{pu}$$

$$= \left(\frac{60}{66} \right) + (0.667 \angle -25.8^\circ)(0.49) = 1.20 - 0.142j = 1.09 \angle 45.6^\circ$$

$$V_{1 \text{ actual}} = V_{1pu} \cdot V_{1B} = 1.09 \times 11000 = 11.99 \text{ kV}$$

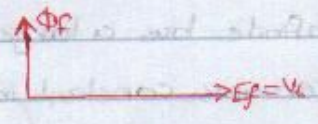
الغولتية (ك) طرف primary

* Synchronous Generator as Element of Power System



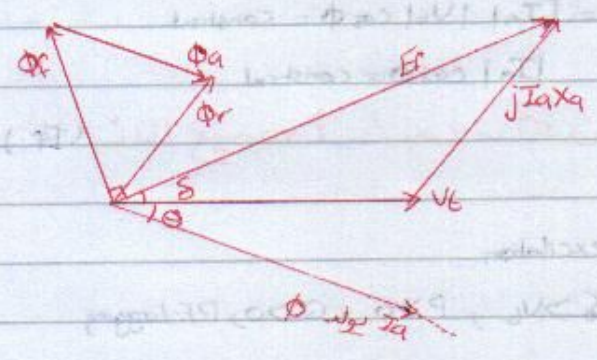
As a element of power system, the synch gen. can be assumed as a system have two input and two output

- At no load state, there is no current but we have (EMF) (Φ mag field from exciter)



- At load state

- Φ_f الفيض الناتج من تيار المجال
- Φ_a الفيض الناتج عن مرور I_a في لاسلاك المجال
- Φ_r الفيض المحصل من Φ_f, Φ_a
- δ power / Torque angle



نتيجة دوران الروتر يتولد مجال يدور باتجاه دوران الرور ويصل إلى استير غير القرة الهوائية وينقل عن توليد armature current وينشأ عن هذا التيار مجال حيث يكون التيار المنتج له نفس زاوية الطور الذي نتج عنه

في الحالة no load تكون إقوتية متأخرة عن المجال بزاوية 90° أما في حالة 3-ph load وتسيكون مرتبطة مع المولد وتسيكون ثلاثة Φ حيث r المجال المحصل للمجالين Φ_f, Φ_a

الزاوية δ هي الزاوية المسؤولة عن القرة الفعالة المولدة في الشبكة ومقدار القوتية مسؤولة عن إقرة الرور فطوية لتولدة في الشبكة.

مع طريقة التحكم بتيار الحمل نستطيع التحكم بمقدار E و δ فتنشأ الحالات السابقة

⇒ Power flow Curve

$$\overline{AB} = |E_f| \sin \delta$$

$$\overline{AB} = |I_a| X_s \cos \theta$$

$$|E_f| \sin \delta = |I_a| X_s \cos \theta \quad \text{by multiply } |V_t|$$

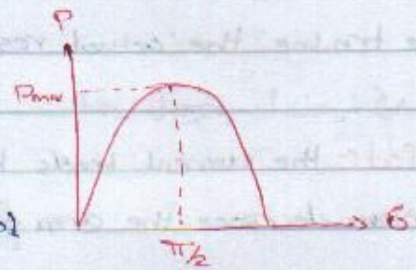
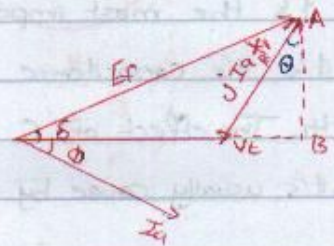
$$|E_f| |V_t| \sin \delta = |I_a| |V_t| X_s \cos \theta$$

$$|E_f| |V_t| \sin \delta = P \cdot X_s$$

$$P = \frac{|E_f| |V_t| \sin \delta}{X_s}$$

$$P_{max} = \frac{|E_f| \cdot |V_t|}{X_s}$$

إذا كانت $\delta < 90^\circ$ تتغير القدرة توافقياً



البيانات مهم أنيت P_{max} تتناسب عكسياً مع X_s (سؤال سنوات سابقة)

من الآن فصاعداً جميع البيانات مهم اعتبارها وكيفية الوصول للصيغة النهائية

* Parameter of Power transmission lines-

The power trn. line has the following parameters-

- 1) R : it's the reason of losses in trn. line and can be neglected.
- 2) L : it's the most important parameter of the trn. line
- 3) C : it's the capacitance between different phases of trn. line, also exist between line and earth. The effect of C cable is greater than that overhead trn. line.
- 4) G : it's usually cause by leakage current through isolator, very small and always neglect

- For the trn. line the actual res is greater than calculated cuz-

- 1) **Skim effects**: the current tends to be constructed in the outer shell of the conductor which mean decrease the area of the conductor and increasing the resistance
- 2) **Proximity effects**: produce by two conductor exists from each other, * then generate between them force so we put the wires with a high distances to avoid this effect emerge

* Inductance of Power transmission line

The flux leakage of an isolated conductor divided into-

- 1) internal flux
- 2) external flux

* Inductance due to internal magnetic flux

حوصلة بتوزع التيار (ك) سطحه الساري واستخدام

current density

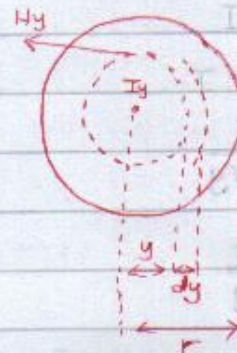
قانون أمبير

$$\int H_y \cdot dl = \vec{J} \cdot \pi y^2$$

$$H_y \cdot 2\pi y = \frac{I}{\pi r^2} \cdot \pi y^2$$

$$H_y = \frac{I y}{2\pi r^2}$$

نسبة المجال المغناطيسي



$$B_y = \mu_0 H_y = \frac{\mu_0 I y}{2\pi r^2}$$

$$d\phi = B_y ds = B_y \cdot dy \quad \text{where } ds = l \cdot dy = dy \quad \text{lm فربان } l \text{ طول } I$$

$$d\phi = \frac{\mu_0 I y}{2\pi r^2} \cdot dy \quad \text{but } d\lambda = d\phi \cdot \frac{y^2}{r^2}$$

$$d\lambda = \frac{\mu_0 I y}{2\pi r^2} \cdot \frac{y^2}{r^2} = \frac{\mu_0 I y^3}{2\pi r^4}$$

$$\lambda = \int_0^r d\lambda = \int_0^r \frac{\mu_0 I y^3}{2\pi r^4} = \frac{\mu_0 I}{2\pi r^4} \cdot \left[\frac{y^4}{4} \right]_0^r$$

$$\lambda = \frac{\mu_0 I r^4}{2\pi r^4 \cdot 4} = \frac{4\pi \times 10^{-7} I}{2\pi \times 4}$$

$$\lambda_{int} = 0.5 \times 10^{-7} I \quad \text{H/m}, \quad L = \frac{\lambda}{I} = 0.5 \times 10^{-7} \text{ H/m}$$

$$\lambda_{int} = 0.5 \times 10^{-7} I \quad \text{Wb/m}$$

flux linkage

$$L = 0.5 \times 10^{-7} \text{ H/m}$$

inductance

* Flux linkage between two point external the conductor

$$\int H_y \cdot dy = I$$

$$2\pi y \cdot H_y = I$$

$$H_y = \frac{I}{2\pi y}$$



$$B_y = \frac{\mu_0 I}{2\pi y}$$

$$d\phi = B_y \cdot ds = B_y \cdot 1 \cdot dy = \frac{\mu_0 I}{2\pi y} dy$$

$$d\lambda_{ext} = \frac{\mu_0 I}{2\pi y} dy$$

$$\lambda_{12} = \int_{D_1}^{D_2} \frac{\mu_0 I}{2\pi y} dy = \frac{\mu_0 I}{2\pi} \ln y \Big|_{D_1}^{D_2} = \frac{\mu_0 I}{2\pi} \ln \frac{D_2}{D_1}$$

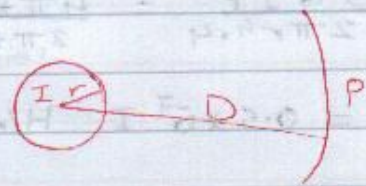
$$\lambda_{12} = \frac{4\pi \times 10^{-7}}{2\pi} I \ln \frac{D_2}{D_1} = 2 \times 10^{-7} \ln \frac{D_2}{D_1} I \text{ Wb/m}$$

$$L_{12} = 2 \times 10^{-7} \ln \frac{D_2}{D_1} \text{ H/m}$$

* Flux linkage due to flux up to an external point

total flux linkage has two component as

$$\lambda = \lambda_{int} + \lambda_{ext}$$



$$\lambda_{int} = 0.5 \times 10^{-7} I$$

$$\lambda_{ext} = 2 \times 10^{-7} I \ln \frac{D}{r}$$

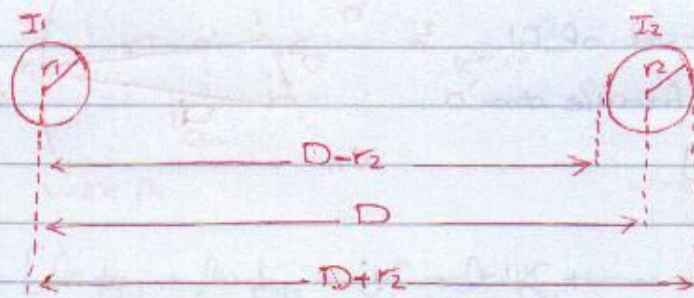
$$\lambda = 0.5 \times 10^{-7} I + 2 \times 10^{-7} I \ln \frac{D}{r} = 2 \times 10^{-7} I \left[\frac{1}{4} + \ln \frac{D}{r} \right]$$

$$\lambda = 2 \times 10^{-7} I \left[\ln e^{1/4} + \ln \frac{D}{r} \right] = 2 \times 10^{-7} I \ln \frac{D}{e^{1/4} r}$$

$$0.7788 \cdot r = r'$$

$$\lambda = 2 \times 10^{-7} I \ln \frac{D}{r'} \quad , \quad L = 2 \times 10^{-7} \ln \frac{D}{r'}$$

* Inductance of a single phase two wire line



- From $0 \rightarrow r_1$, the flux linkage constant and equal $0.5 \times 10^{-7} I_1$
- From $r_1 \rightarrow D-r_2$, the flux linkage caused by current I_1 .
- From $D \rightarrow r_2 \rightarrow D+r_2$, the flux linkage a current whose magnitude progressively reduced from $I_1 \rightarrow 0$ along the distance because the effect of negative current of conductor 2.
- Flux beyond $D+r_2$ links a net current of zero.

$$I_1 \Rightarrow \lambda_1 = 2 \times 10^{-7} I_1 \ln \frac{D}{r_1}, \quad L_1 = 2 \times 10^{-7} \ln \frac{D}{r_1}$$

$$I_2 \Rightarrow L_2 = 2 \times 10^{-7} \ln \frac{D}{r_2}$$

$$L = L_1 + L_2 = 2 \times 10^{-7} \left[\ln \frac{D}{r_1} + \ln \frac{D}{r_2} \right] = 2 \times 10^{-7} \ln \frac{D^2}{r_1 r_2}$$

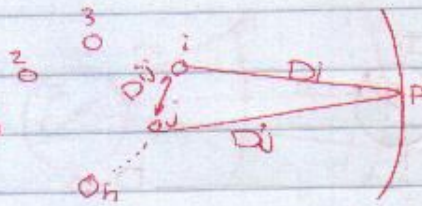
$$L = 2 \times 10^{-7} \ln \frac{D^2}{r_1 r_2} = 4 \times 10^{-7} \ln \frac{D}{\sqrt{r_1 r_2}}$$

usually $r_1 = r_2 = r$

$$\therefore L = 4 \times 10^{-7} \ln \frac{D}{r}$$

* Flux linkage of a single Conductor in a group of Conductor

the f.l of conductor i will consist of f.l caused by i conductor (self) and from the other conductors (mutual flux linkage)



$$\lambda_i = \sum_{j=1}^n \lambda_{ij} = \lambda_{i1} + \lambda_{i2} + \dots + \lambda_{in}$$

$$\lambda_{ii} = 2 \times 10^{-7} I_i \ln \frac{D_i}{r_i} \quad , \quad \lambda_{ij} = 2 \times 10^{-7} I_j \ln \frac{D_{ij}}{D_{ji}}$$

$$\lambda_i = 2 \times 10^{-7} \left[I_1 \ln \frac{D_{i1}}{D_{1i}} + I_2 \ln \frac{D_{i2}}{D_{2i}} + \dots + I_i \ln \frac{D_{ii}}{D_{ii}} + \dots + I_n \ln \frac{D_{in}}{D_{ni}} \right]$$

$$\lambda_i = 2 \times 10^{-7} \left[I_1 \ln D_{i1} + I_1 \ln \frac{1}{D_{1i}} + I_2 \ln D_{i2} + I_2 \ln \frac{1}{D_{2i}} + \dots + I_i \ln D_{ii} + I_i \ln \frac{1}{D_{ii}} + \dots + I_n \ln D_{in} + I_n \ln \frac{1}{D_{ni}} \right]$$

$$I_n = -(I_1 + I_2 + \dots + I_{n-1})$$

$$\lambda_i = 2 \times 10^{-7} \left[I_1 \ln D_{i1} + I_2 \ln D_{i2} + \dots + I_i \ln D_{ii} - I_2 \ln D_{in} - I_2 \ln D_{ni} - \dots - I_{n-1} \ln D_{in} + I_1 \ln \frac{1}{D_{1i}} + I_2 \ln \frac{1}{D_{2i}} + \dots + I_i \ln \frac{1}{D_{ii}} + \dots + I_n \ln \frac{1}{D_{ni}} \right]$$

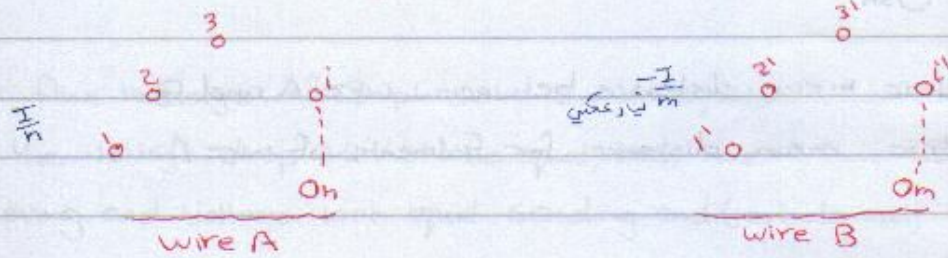
अंत में I_n का चिह्न बदलें

$$\lambda_i = 2 \times 10^{-7} \left[I_1 \ln \frac{D_{i1}}{D_{1i}} + I_2 \ln \frac{D_{i2}}{D_{2i}} + \dots + I_{n-1} \ln \frac{D_{in-1}}{D_{n-1i}} + I_1 \ln \frac{1}{D_{1i}} + I_2 \ln \frac{1}{D_{2i}} + \dots - I_n \ln \frac{1}{D_{ni}} \right]$$

total f.l will be when $D \rightarrow \infty$, so $D_1 = D_2 = \dots = D_n$ $\ln 1 = 0$ (बताने पर)

$$\lambda_i = 2 \times 10^{-7} \left[I_1 \ln \frac{1}{D_{1i}} + I_2 \ln \frac{1}{D_{2i}} + \dots + I_i \ln \frac{1}{D_{ii}} + \dots - I_n \ln \frac{1}{D_{ni}} \right]$$

* Inductance of Composite Conductor Lines



$$\lambda_i = 2 \times 10^{-7} \frac{I}{h} \left[\ln \frac{1}{D_{i1}} + \ln \frac{1}{D_{i2}} + \dots + \ln \frac{1}{D_{in}} + \dots + \ln \frac{1}{D_{in}} \right] - 2 \times 10^{-7} \frac{I}{m'} \left[\ln \frac{1}{D_{i1}'} + \dots + \ln \frac{1}{D_{im}'} \right]$$

$$\lambda_i = -2 \times 10^{-7} \frac{I}{h} \left[\ln D_{i1} + \ln D_{i2} + \dots + \ln D_{in} \right] + 2 \times 10^{-7} \frac{I}{m'} \left[\ln D_{i1}' + \ln D_{i2}' + \dots + \ln D_{im}' \right]$$

$$\lambda_i = -2 \times 10^{-7} \frac{I}{h} \left[\ln (D_{i1} + D_{i2} + \dots + D_{in}) \right] + 2 \times 10^{-7} \frac{I}{m'} \left[\ln (D_{i1}' + D_{i2}' + \dots + D_{im}') \right]$$

$$\lambda_i = 2 \times 10^{-7} \frac{I}{h} \ln (D_{i1} + D_{i2} + \dots + D_{in})^{-1/h} + 2 \times 10^{-7} \frac{I}{m'} \ln (D_{i1}' + \dots + D_{im}')^{1/m'}$$

$$\lambda_i = 2 \times 10^{-7} \frac{I}{h} \ln \frac{(D_{i1}' + \dots + D_{im}')^{1/m'}}{(D_{i1} + \dots + D_{in})^{1/h}}$$

the inductance of filament is-

$$L_i = \frac{\lambda_i}{I} = h \cdot \frac{\lambda_i}{I} = 2 \times 10^{-7} h \cdot \ln \frac{(D_{i1}' + \dots + D_{im}')^{1/m'}}{(D_{i1} + \dots + D_{in})^{1/h}}$$

the average of filament of conductor A is-

$$L_{avg} = \frac{L_1 + L_2 + L_3 + \dots + L_n}{n}$$

$$L_{avg} = 2 \times 10^{-7} \left[\ln \frac{(D_{i1}' + \dots + D_{im}')^{1/m'}}{(D_{i1} + \dots + D_{in})^{1/h}} + \ln \frac{(D_{21}' + \dots + D_{2m}')^{1/m'}}{(D_{21} + \dots + D_{2n})^{1/h}} + \dots + \ln \frac{(D_{n1}' + \dots + D_{nm}')^{1/m'}}{(D_{n1} + \dots + D_{nm})^{1/h}} \right]$$

$$L_{avg} = 2 \times 10^{-7} \ln \left[\frac{(D_{i1}' + \dots + D_{im}') (D_{21}' + \dots + D_{2m}') \dots (D_{n1}' + \dots + D_{nm}')}{[(D_{i1} + \dots + D_{in}) (D_{21} + \dots + D_{2n}) \dots (D_{n1} + \dots + D_{nm})]^{1/h}} \right]^{1/m'}$$

$$L_a = \frac{2 \times 10^{-7}}{n} \ln \left[\frac{(D_{i1}' + \dots + D_{im}') (D_{21}' + \dots + D_{2m}') \dots (D_{n1}' + \dots + D_{nm}')}{[(D_{i1} + \dots + D_{in}) (D_{21} + \dots + D_{2n}) \dots (D_{n1} + \dots + D_{nm})]^{1/h}} \right]^{1/m'}$$

$$L_a = 2 \times 10^{-7} \ln \frac{D_m}{D_{SA}}$$

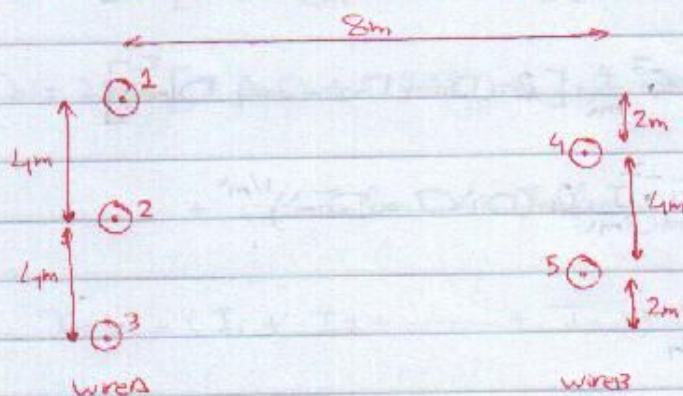
D_m is mutual geometric mean distance between wire A and B

D_{SA} self geometric mean distance for filaments of wire A

$$L_b = 2 \times 10^{-7} \ln \frac{D_m}{D_{SB}}$$

$$L = L_a + L_b$$

Ex For a following configuration of a single phase, find the total inductance of the line. $r_a = 2.5 \text{ mm}$, $r_b = 5 \text{ mm}$



$$D_{14} = 8^2 + 2^2 = \sqrt{68} \quad \text{مقياس عكسي}$$

$$L_a = 2 \times 10^{-7} \ln \frac{D_m}{D_{SA}}$$

$$D_m = (D_{14} \cdot D_{15} \cdot D_{24} \cdot D_{25} \cdot D_{34} \cdot D_{35})^{1/6} = (\sqrt{68} \times 10 \times \sqrt{68} \times \sqrt{68} \times 10 \times \sqrt{68})^{1/6} = 8.8 \text{ m}$$

$$D_{SA} = (D_{11} \cdot D_{12} \cdot D_{13} \cdot D_{21} \cdot D_{22} \cdot D_{23} \cdot D_{31} \cdot D_{32} \cdot D_{33})^{1/9} = ((0.7788 \times 0.0025)^3 \times (4)^4 \times 8^2)^{1/9} = 0.367 \text{ m}$$

$$L_a = 2 \times 10^{-7} \ln \frac{8.8}{0.367} = 0.635 \text{ mH/km}$$

450 H/m → 0.45 mH/km

$$D_{mB} = (D_{41} \cdot D_{42} \cdot D_{43} \cdot D_{51} \cdot D_{52} \cdot D_{53})^{1/6} = (4 \times 4 \times 4 \times 4 \times 4 \times 4)^{1/6} = 8.8 \text{ m}$$

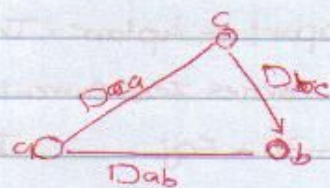
$$D_{SB} = (D_{44} \cdot D_{45} \cdot D_{54} \cdot D_{55})^{1/4} = ((0.7788 \times 0.005)^2 \times (4)^2)^{1/4} = 0.125 \text{ m}$$

$$L_b = 2 \times 10^{-7} \ln \frac{8.8}{0.125} = 0.85 \text{ mH/km}$$

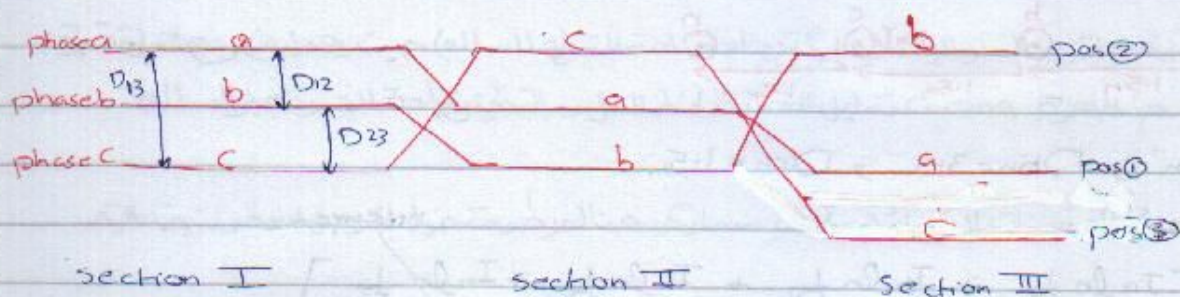
$$L_T = L_a + L_b = 1.485 \text{ mH/km}$$

* Inductance of 3-phase Lines

The flux linkage of 3-phase are not-equal, thus the voltage drop will not be equal, thus the receiving end voltage not equal sending end (unbalanced)



To overcome problem, we use a transposition



$$\lambda_{a1} = 2 \times 10^{-7} \left[I_a \ln \frac{1}{r_a'} + I_b \ln \frac{1}{D_{12}} + I_c \ln \frac{1}{D_{13}} \right]$$

$$\lambda_{a2} = 2 \times 10^{-7} \left[I_a \ln \frac{1}{r_a'} + I_b \ln \frac{1}{D_{23}} + I_c \ln \frac{1}{D_{12}} \right]$$

$$\lambda_{a3} = 2 \times 10^{-7} \left[I_a \ln \frac{1}{r_a'} + I_b \ln \frac{1}{D_{13}} + I_c \ln \frac{1}{D_{23}} \right]$$

$$\text{average } \lambda_a = \frac{2}{3} \times 10^{-7} \left[3 I_a \ln \frac{1}{r_a'} + I_b \ln \frac{1}{D_{12} \cdot D_{23} \cdot D_{13}} + I_c \ln \frac{1}{D_{12} \cdot D_{23} \cdot D_{13}} \right]$$

$$\lambda_a = \frac{2}{3} \times 10^{-7} \left[3 I_a \ln \frac{1}{r_a'} + (I_b + I_c) \ln \frac{1}{D_{12} \cdot D_{23} \cdot D_{13}} \right]$$

$$I_a + I_b + I_c = 0$$

$$\lambda_a = \frac{2}{3} \times 10^{-7} \left[3 I_a \ln \frac{1}{r_a'} - I_a \ln \frac{1}{D_{12} \cdot D_{23} \cdot D_{13}} \right]$$

$$\lambda_a = 2 \times 10^{-7} \left[I_a \ln \frac{1}{r_a'} - I_a \ln \frac{1}{(D_{12} \cdot D_{23} \cdot D_{13})^{1/3}} \right]$$

$$\lambda_a = 2 \times 10^{-7} I_a \ln \frac{(D_{12} \cdot D_{23} \cdot D_{13})^{1/3}}{r_a'} = 2 \times 10^{-7} I_a \ln \frac{D_{eq}}{D_A}$$

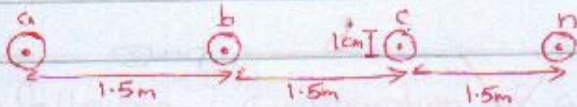
$$L = 2 \times 10^{-7} \ln \frac{D_{eq}}{D_A}$$

Ex 9 A three phase, 50 Hz, 15 km long line has four wires (1 cm diameter) spaced horizontally 1.5 m apart in a plane. The wires carrying current I_a, I_b, I_c and fourth wire is neutral carries zero current.

$$I_a = -30 + 50j \quad I_b = -25 + 55j \quad I_c = 55 - j105$$

The line is untransposed

- 1) Find flux linkage of the neutral wire and voltage
- 2) Find the drop voltage in each wire



$$1) D_{an} = 4.5 \text{ m}, D_{bn} = 3 \text{ m}, D_{cn} = 1.5 \text{ m}$$

$$\lambda_n = 2 \times 10^{-7} \left[I_a \ln \frac{1}{D_{an}} + I_b \ln \frac{1}{D_{bn}} + I_c \ln \frac{1}{D_{cn}} + I_n \ln \frac{1}{D_n} \right]$$

$I_n \text{ current} = 0$

$$\lambda_n = 2 \times 10^{-7} [1.5 I_a + 1.1 I_b + 0.405 I_c]$$

بالقوس بالقيم

$$\lambda_n = -0.01 + 0.0187 = 0.021 \text{ Wb/km}$$

$$V_n = j\omega \lambda_n \times L \rightarrow \text{طاقة}$$

$$= +j 2\pi \times 50 \times 0.021 \times 10^{-3} \times 15 \times 1000 = 99 \text{ V}$$

$$2) \lambda_a = 2 \times 10^{-7} \left[I_a \ln \frac{1}{r_a} + I_b \ln \frac{1}{D} + I_c \ln \frac{1}{2D} \right]$$

أولها في الأعلى
ثانيها في الأسفل

$$\lambda_a = 2 \times 10^{-7} \left[I_a \ln \frac{1}{0.005 \times 0.7788} + I_b \ln \frac{1}{1.5} + I_c \ln \frac{1}{3} \right]$$

$$\lambda_a = 2 \times 10^{-7} [5.55 I_a + (-0.405 I_b) - 1.098 I_c] = -0.043 + 0.074$$

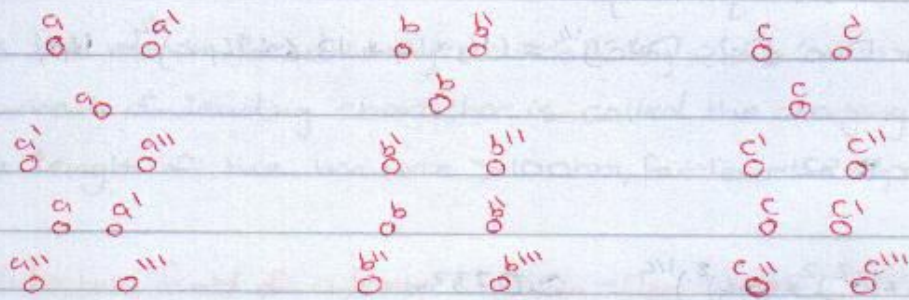
$$= 0.0855 \text{ Wb/km}$$

$$\Delta V_a = j\omega \lambda_a \times L = j 314 \times (-0.043 + 0.074) \times 15 = -348.5 - 262.5j$$

$$= 403 \text{ V}$$

ونفس الشيء بالسيار V_b و V_c

* Bundled Conductors



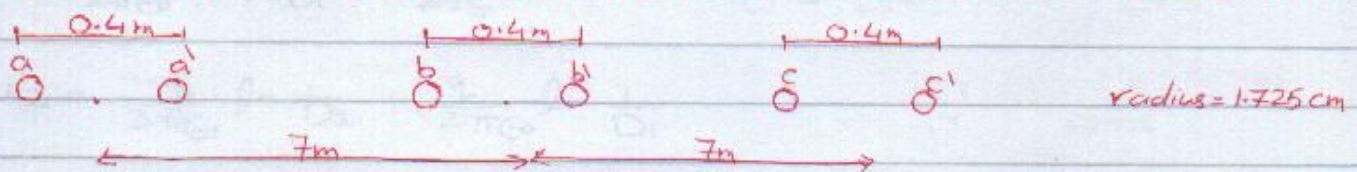
هي موصلات تستخدم لتوزيع الفاز الواحد (على) تزداد مساحة المقطع للسلك حيث يعمل على رفع القدرة التي
تنتج عنها / عنصرا ظاهرة corona وتقليل الخسارة لحظ التقل وبالتالي زيادة القدرة عبر السلك

corona: تفريغ جزئي للسحبات الكهربائية وتنتج عنها يكون من الضرورية حول الموصل عند فولتية عالية

→ bundled adjust by two advantages:

- 1) increasing the maximum voltage at which corona emerge
- 2) decrease the ind. of the line, thus the voltage drop decrease and the max power that can be transferred through the line is increase.

Ex: Calculate the inductance and reluctance for the bundled conductor as shown



$$L = 2 \times 10^{-7} \ln \frac{D_{eq}}{D_s}$$

$$D_{eq} = (D_{ab} \cdot D_{bc} \cdot D_{ac})^{1/3}$$

$$D_s = (r_a \cdot d_{aa'} \cdot r_a \cdot d_{aa'})^{1/4}$$

$$\text{Mutual GMD } D_{ab} = (D_{ab} \cdot D_{ab'} \cdot D_{ab''} \cdot D_{ab'''})^{1/4} = (7 \times 7.4 \times 6.6 \times 7)^{1/4} = 7 \text{ m}$$

$D_{bc} = 7 \text{ m}$ from symmetry

$$D_{ac} = (D_{ac} \cdot D_{ac'} \cdot D_{ac''} \cdot D_{ac'''})^{1/4} = (14 \times 14 \times 13.6 \times 14.4)^{1/4} = 14 \text{ m}$$

$$D_{eq} = (7 \times 7 \times 14)^{1/3} = 8.82 \text{ m}$$

$$D_s = ((0.7788 \times 1.725 \times 10^{-2})^2 \times (0.4)^2)^{1/4} = 0.0733 \text{ m}$$

$$L = 2 \times 10^{-7} \ln \frac{8.82}{0.0733} = 0.96 \text{ mH/km}$$

$$X = 2 \pi f L = 0.96 \times 2 \times \pi \times 50 = 0.301 \text{ } \Omega/\text{km}$$

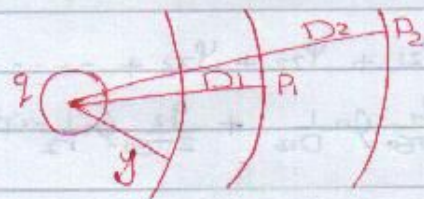
Capacitance

* Capacitance of Power transmission line

is the reason for drawing a current by a line over a line is not loaded. This current of leading character is called the charging current. It has an effect if the length of the trn-line $> 100\text{km}$, for less the cap can be neglected.

* Electric field of a long straight conductor

q is charge density
the E.F around this conductor will be consider cylindrical.



According to Gauss law $\int D \cdot ds = Q$

$$D \cdot 2\pi y L = q \cdot L \Rightarrow D = \frac{q}{2\pi y} \quad \text{Flux density}$$

$$E = \frac{D}{\epsilon_0} = \frac{q}{2\pi \epsilon_0 y}$$

$$V_{12} = \varphi_1 - \varphi_2 = \int_{D_1}^{D_2} E \cdot dl = \int_{D_1}^{D_2} \frac{q}{2\pi \epsilon_0 y} dl = \frac{q}{2\pi \epsilon_0} \int_{D_1}^{D_2} \frac{1}{y} dy$$

$$V_{12} = \frac{q}{2\pi \epsilon_0} [\ln y]_{D_1}^{D_2} = \frac{q}{2\pi \epsilon_0} [\ln D_2 - \ln D_1]$$

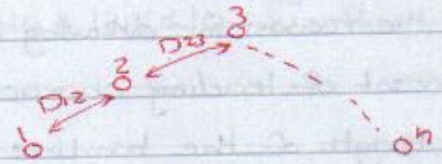
$$V_{12} = \frac{-q}{2\pi \epsilon_0} \ln \frac{1}{D_2} + \frac{q}{2\pi \epsilon_0} \ln \frac{1}{D_1}$$

$$= \underbrace{\frac{q}{2\pi \epsilon_0} \ln \frac{1}{D_1}}_{\varphi_1} - \underbrace{\frac{q}{2\pi \epsilon_0} \ln \frac{1}{D_2}}_{\varphi_2}$$

We can conclude that the potential at any point $= \frac{q}{2\pi \epsilon_0} \ln \frac{1}{D}$ where D is the distance between the point.

* Potential Difference between two conductor in a group of parallel conductors

$$V_{12} = \phi_1 - \phi_2$$



$$\phi_1 = \phi_{11} + \phi_{12} + \phi_{13} + \dots + \phi_{1n}$$

$$= \frac{q_1}{2\pi\epsilon_0} \ln \frac{1}{r_1} + \frac{q_2}{2\pi\epsilon_0} \ln \frac{1}{D_{12}} + \frac{q_3}{2\pi\epsilon_0} \ln \frac{1}{D_{13}} + \dots + \frac{q_n}{2\pi\epsilon_0} \ln \frac{1}{D_{1n}}$$

$$\phi_2 = \phi_{21} + \phi_{22} + \phi_{23} + \dots + \phi_{2n}$$

$$= \frac{q_1}{2\pi\epsilon_0} \ln \frac{1}{D_{12}} + \frac{q_2}{2\pi\epsilon_0} \ln \frac{1}{r_2} + \frac{q_3}{2\pi\epsilon_0} \ln \frac{1}{D_{23}} + \dots + \frac{q_n}{2\pi\epsilon_0} \ln \frac{1}{D_{2n}}$$

$$V_{12} = \phi_1 - \phi_2$$

$$= \frac{q_1}{2\pi\epsilon_0} \ln \frac{D_{12}}{r_1} + \frac{q_2}{2\pi\epsilon_0} \ln \frac{r_2}{D_{12}} + \frac{q_3}{2\pi\epsilon_0} \ln \frac{D_{23}}{D_{13}} + \dots + \frac{q_n}{2\pi\epsilon_0} \ln \frac{D_{2n}}{D_{1n}}$$

* Capacitance of two wire line

$$\phi_1 = \phi_{11} + \phi_{12}$$

$$= \frac{q}{2\pi\epsilon_0} \ln \frac{1}{r_1} - \frac{q}{2\pi\epsilon_0} \ln \frac{1}{D}$$



$$\phi_1 = \frac{q}{2\pi\epsilon_0} \ln \frac{D}{r_1}$$

$$\phi_2 = \phi_{22} + \phi_{21}$$

$$= \frac{-q}{2\pi\epsilon_0} \ln \frac{1}{r_2} + \frac{q}{2\pi\epsilon_0} \ln \frac{1}{D} = \frac{q}{2\pi\epsilon_0} \ln \frac{r_2}{D}$$

$$V_{12} = \phi_1 - \phi_2$$

$$= \frac{q}{2\pi\epsilon_0} \ln \frac{D}{r_1} - \frac{q}{2\pi\epsilon_0} \ln \frac{r_2}{D}$$

$$= \frac{q}{2\pi\epsilon_0} \ln \frac{D}{r_1} + \frac{q}{2\pi\epsilon_0} \ln \frac{D}{r_2} = \frac{q}{2\pi\epsilon_0} \ln \frac{D^2}{r_1 r_2}$$

usually $r_1 = r_2 = r$

$$V_{12} = \frac{q}{2\pi\epsilon_0} \ln \frac{D^2}{r^2} = \frac{q}{\pi\epsilon_0} \ln \frac{D}{r}$$

but $C = \frac{q}{V} \Rightarrow$

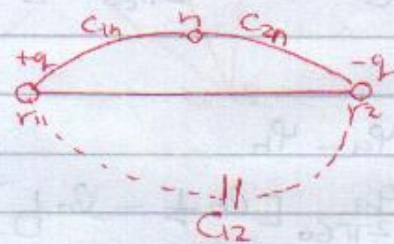
$$C_{12} = \frac{q}{V_{12}} = \frac{\pi\epsilon_0}{\ln \frac{D}{r}} = \frac{3.14 \times 8.85 \times 10^{-12}}{\ln \frac{D}{r}} = \frac{2.78 \times 10^{-11} \text{ F/m}}{\ln \frac{D}{r}}$$

$$C_{12} = \frac{2.78 \times 10^{-5} \text{ MF/m}}{\ln \frac{D}{r}} = \frac{2.78 \times 10^{-2} \text{ MF/km}}{\ln \frac{D}{r}}$$

إذا افترضنا وجود الترض

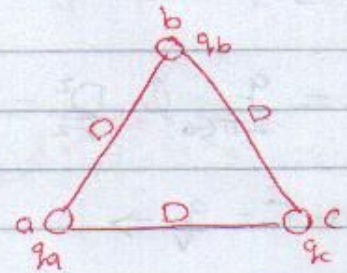
$$C_{1n} = C_{2n} = 2 \times C_{12}$$

$$C_{\text{كل سلك إلى الأرض}} = \frac{5.56 \times 10^{-2} \text{ MF/km}}{\ln \frac{D}{r}}$$



* Capacitance of 3-phase System

$$\begin{aligned} \varphi_a &= \varphi_{aa} + \varphi_{ab} + \varphi_{ac} \\ &= \frac{q_a}{2\pi\epsilon_0} \ln \frac{1}{r} + \frac{q_b}{2\pi\epsilon_0} \ln \frac{1}{D} + \frac{q_c}{2\pi\epsilon_0} \ln \frac{1}{D} \end{aligned}$$



$$\begin{aligned} \varphi_b &= \varphi_{ba} + \varphi_{bb} + \varphi_{bc} \\ &= \frac{q_a}{2\pi\epsilon_0} \ln \frac{1}{D} + \frac{q_b}{2\pi\epsilon_0} \ln \frac{1}{r} + \frac{q_c}{2\pi\epsilon_0} \ln \frac{1}{D} \end{aligned}$$

$$\begin{aligned} \varphi_c &= \varphi_{ca} + \varphi_{cb} + \varphi_{cc} \\ &= \frac{q_a}{2\pi\epsilon_0} \ln \frac{1}{D} + \frac{q_b}{2\pi\epsilon_0} \ln \frac{1}{D} + \frac{q_c}{2\pi\epsilon_0} \ln \frac{1}{r} \end{aligned}$$

$$\begin{aligned} V_{ab} &= \varphi_a - \varphi_b \\ &= \frac{q_a}{2\pi\epsilon_0} \left[\ln \frac{1}{r} - \ln \frac{1}{D} \right] + \frac{q_b}{2\pi\epsilon_0} \left[\ln \frac{1}{D} - \ln \frac{1}{r} \right] \end{aligned}$$

$$V_{ab} = \frac{q_a}{2\pi\epsilon_0} \ln \frac{D}{r} + \frac{q_b}{2\pi\epsilon_0} \ln \frac{r}{D} \dots\dots\dots ①$$

$$\begin{aligned} V_{ac} &= \varphi_a - \varphi_c \\ &= \frac{q_a}{2\pi\epsilon_0} \left[\ln \frac{1}{r} - \ln \frac{1}{D} \right] + \frac{q_c}{2\pi\epsilon_0} \left[\ln \frac{1}{D} - \ln \frac{1}{r} \right] \end{aligned}$$

$$V_{ac} = \frac{q_a}{2\pi\epsilon_0} \ln \frac{D}{r} + \frac{q_c}{2\pi\epsilon_0} \ln \frac{r}{D} \dots\dots\dots ②$$

$$V_{ab} + V_{ac} = \frac{q_a}{\pi\epsilon_0} \ln \frac{D}{r} + \frac{q_b + q_c}{2\pi\epsilon_0} \ln \frac{r}{D} \dots\dots\dots ③$$

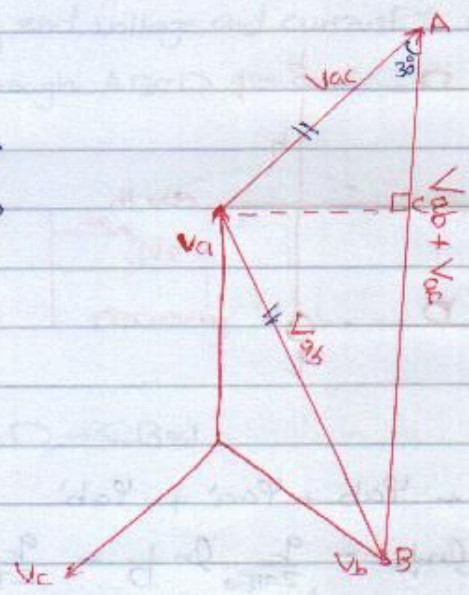
$$q_a + q_b + q_c = 0$$

$$q_b + q_c = -q_a \dots\dots\dots ④$$

$$V_{ab} + V_{ac} = \frac{q_a}{\pi \epsilon_0} \ln \frac{D}{r} - \frac{q_a}{2\pi \epsilon_0} \ln \frac{r}{D}$$

$$= \frac{q_a}{\pi \epsilon_0} \ln \frac{D}{r} + \frac{q_a}{2\pi \epsilon_0} \ln \frac{D}{r} = \frac{3q_a}{2\pi \epsilon_0} \ln \frac{D}{r} \text{ oooooo (5)}$$

ملاحظة: مثل متساوي الأضلاع
واخذ بركة الرسم



$$|AC| = \frac{|V_{ab} + V_{ac}|}{2} = |V_{ac}| \cdot \frac{\sqrt{3}}{2}$$

$$|V_{ab} + V_{ac}| = \sqrt{3} |V_{ac}|$$

but $V_{ac} = \sqrt{3} V_{an}$

$$V_{ab} + V_{ac} = \sqrt{3} \cdot (\sqrt{3} V_{an})$$

$$V_{ab} + V_{ac} = 3 V_{an}$$

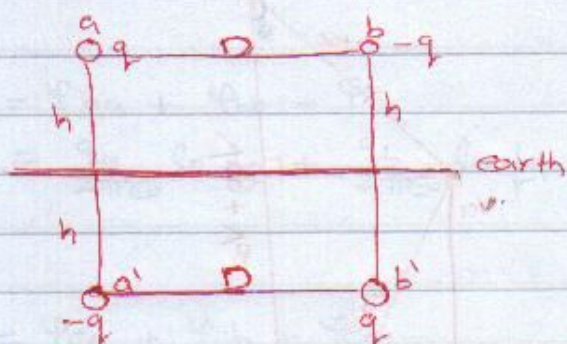
$$3 V_{an} = \frac{3q_a}{2\pi \epsilon_0} \ln \frac{D}{r}$$

$$C_{an} = \frac{q_{an}}{V_{an}} = \frac{2\pi \epsilon_0}{\ln \frac{D}{r}} = \frac{5.56 \times 10^{-2} \text{ MF/tm}}{\ln \frac{D}{r}}$$

From the previous, we can conclude that the capacitance of single phase same as capacitance of three phase.

* The effect of earth

All previous formula of capacitance were derived without taking the presence of earth. For taken the consideration of earth, the imaginary method used



هذا الأسلوب مع وجود الأرض، ويسمى الطريقة الخيالية

$$\varphi_a = \varphi_{aa} + \varphi_{ab} + \varphi_{aa'} + \varphi_{ab'}$$

$$= \frac{q}{2\pi\epsilon_0} \ln \frac{r}{r} - \frac{q}{2\pi\epsilon_0} \ln \frac{1}{D} - \frac{q}{2\pi\epsilon_0} \ln \frac{1}{2h} + \frac{q}{2\pi\epsilon_0} \ln \frac{1}{\sqrt{D^2 + 4h^2}}$$

$$\varphi_b = \varphi_{ba} + \varphi_{bb} + \varphi_{ba'} + \varphi_{bb'}$$

$$= \frac{q}{2\pi\epsilon_0} \ln \frac{1}{D} - \frac{q}{2\pi\epsilon_0} \ln \frac{1}{r} - \frac{q}{2\pi\epsilon_0} \ln \frac{1}{\sqrt{D^2 + 4h^2}} + \frac{q}{2\pi\epsilon_0} \ln \frac{1}{2h}$$

$$V_{ab} = \varphi_a - \varphi_b = \frac{q}{2\pi\epsilon_0} \left[\ln \frac{D}{r} + \ln \frac{r}{D} + \ln \frac{(4h^2 + D^2)^{1/2}}{2h} + \ln \frac{2h}{(4h^2 + D^2)^{1/2}} \right]$$

$$V_{ab} = \frac{q}{2\pi\epsilon_0} \ln \frac{2hD}{r(4h^2 + D^2)^{1/2}}$$

هذا الأسلوب مع وجود الأرض، ويسمى الطريقة الخيالية

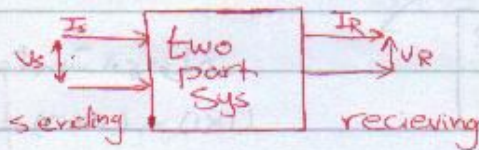
$$C_{ab} = \frac{q_{ab}}{V_{ab}} = \frac{\pi\epsilon_0}{\ln \frac{2hD}{r\sqrt{4h^2 + D^2}}} = \frac{\pi\epsilon_0}{\ln \frac{2hD}{2hr\sqrt{1 + \frac{D^2}{4h^2}}}} = \frac{\pi\epsilon_0}{\ln \frac{D}{r\sqrt{1 + \frac{D^2}{4h^2}}}}$$

$$C_{ab} = \frac{\pi\epsilon_0}{\ln \frac{D}{r\sqrt{1 + \frac{D^2}{4h^2}}}}$$

Transmission Lines

* Transmission Lines in Normal operation work under balanced

Transmission lines are normally operated with a balanced 3-phase load, the analysis can therefore proceed on a per phase basis. A trn-line on a per-phase can be regarded as a two part network wherein the sending end voltage and current I_s are related to the receiving end voltage V_R and I_R through ABCD constants



$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix} \quad AD - CB = 1$$

- There are some kinds of trn-line according to the lengths

- 1) Short Line $L \leq 100 \text{ km}$
- 2) Medium Line $100 \text{ km} < L < 250 \text{ km}$
- 3) Long Line $L > 250 \text{ km}$

- Short and medium lines are assume to be lumped parameter

- For long line the parameter are assumed distributed at the line.

- In short line, line represented by res, and cuz the effect of short line is low

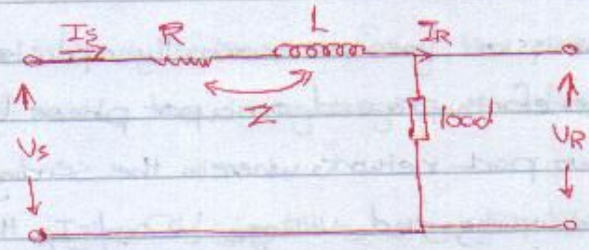
- For medium line, the capacitor is big value so we take the value of it.

1] Short transmission line

the eqn cir of short tm. lines

$$V_s = V_R + Z I_R$$

$$I_s = I_R$$



$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} 1 & Z \\ 0 & 1 \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

هذا يعطينا المعادلات
 $(1 \times 1) + (Z \times 0) = 1$

to find Z, we multiply it with length of line (Z given by per km)

$$|V_s| = \sqrt{(|V_R| \cos \phi_R + |I| \cdot R)^2 + (|V_R| \sin \phi_R + |I| \cdot X)^2}$$

$$|V_s| = \left[|V_R|^2 \cos^2 \phi_R + |I|^2 R^2 + 2|V_R||I|R \cos \phi_R + |V_R|^2 \sin^2 \phi_R + |I|^2 X^2 + 2|V_R||I|X \sin \phi_R \right]^{1/2}$$

$$|V_s| = \left[|V_R|^2 + |I|^2 (X^2 + R^2) + 2|V_R||I|(R \cos \phi_R + X \sin \phi_R) \right]^{1/2}$$

$$|V_R|^2 \cos^2 \phi_R + |V_R|^2 \sin^2 \phi_R = |V_R|^2 (\cos^2 \phi + \sin^2 \phi) = |V_R|^2 \quad \text{حيث}$$

$$|V_s| = |V_R| \left[1 + \frac{|I|^2 (R^2 + X^2)}{|V_R|^2} + \frac{2|I|}{|V_R|} (R \cos \phi_R + X \sin \phi_R) \right]^{1/2}$$

neglect
 تيار قليل مقارنة بمخرج الفولتية

$$|V_s| = |V_R| \left[1 + \frac{|I|}{|V_R|} (R \cos \phi_R + X \sin \phi_R) \right]$$

فإنه يمكن إجراء تقويم معادلة التناقص باستخدام متسلسلة تايلور حيث أننا نعلم أن طولها
 ليس مع التناقص كما سبق

$$|V_s| = |V_R| + |I| (R \cos \phi_R + X \sin \phi_R)$$

$$\Delta V = |V_s| - |V_R| \approx |I| (R \cos \phi_R + X \sin \phi_R) \quad |V_R| \rightarrow \text{منه است و بقایا به خط}$$

$$\Delta V = |V_s| - |V_R| = \frac{|I| |V_R| (R \cos \phi_R + X \sin \phi_R)}{|V_R|}$$

$$\Delta V \approx \frac{|I| |V_R| (R \cos \phi_R + X \sin \phi_R)}{|V_R|} \quad \text{است عبارت } P \text{ و } Q$$

$$\Delta V = \frac{P \cdot R + Q \cdot X}{|V_R|}$$

* Voltage Regulation

منه نسبت به الفولتیه تقیسی الفولتیه بیوه رجود لؤل



$$\frac{|V_{R1}| - |V_{R2}|}{|V_{R1}|} \times 100\%$$

$$V_{\text{reg}} = \frac{|V_s| - |V_R|}{|V_R|} \times 100\% = \frac{|\Delta V|}{|V_R|} \times 100\% = \frac{P \cdot R + Q \cdot X}{|V_R|^2} \times 100\%$$

$$V_{\text{reg}} = \frac{|V_R| |I| \cos \phi_R \cdot R + |V_R| |I| \sin \phi_R \cdot X}{|V_R|^2}$$

$$V_{\text{reg}} = |I_R| \left[\frac{R \cos \phi_R + X \sin \phi_R}{|V_R|} \right]$$

for inductive load, $\phi_R = +ve$. For Capacitive, $\phi_R = -ve$

$$\Rightarrow \text{For capacitive load's } V_{\text{reg}} = |I_R| \left[\frac{R \cos \phi_R + X \sin \phi_R}{|V_R|} \right]$$

$$\Rightarrow \text{Voltage regulation can be zero if } R \cos \phi_R = X \sin \phi_R \Rightarrow \tan \phi_R = \frac{R}{X}$$

\Rightarrow Voltage regulation have arelation only with reactive power.

Ex: A single phase, 50Hz gen supplies inductive load of 5MW at P.F=0.707 lagging by mean overhead of tm-line $l=20\text{ km}$, $r=0.0195\ \Omega/\text{km}$, $L=0.63\text{ mH}/\text{km}$ and the voltage at receiving end 10kV.

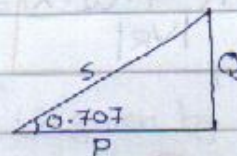
a) find the sending end voltage and voltage regulation of the line

b) find the value of C parallel to load such that V.R reduced to 50% as obtain in a.

$$R = r \cdot L = 0.0195 \times 20 = 0.39\ \Omega$$

$$X = 2\pi f \cdot L \cdot l = 314 \times 0.63 \times 10^{-3} \times 20 = 3.96\ \Omega$$

$$Q = \frac{P}{\tan(\cos^{-1}(0.707))} \approx 5\ \text{MVA}$$



$$|\Delta V| = \frac{P \cdot R + Q \cdot X}{|V_R|} = \frac{5\text{ MW} \times 0.39 + 5\text{ MVA} \times 3.96}{10\text{ kV}}$$

$$|\Delta V| = 21.75\%$$

$$|V_S| = |V_R| + |\Delta V| = 10000 + 2175 = 12.175\ \text{kV}$$

$$b) |\Delta V| = \frac{1}{2} |\Delta V| = 10.9\%$$

$$|\Delta V| = \frac{P \cdot R + Q \cdot X}{|V_R|}$$

$$10.9\% = \frac{5\text{ MW} \times 0.39 + Q \times 3.96}{10\text{ kV}} \Rightarrow Q = 2.27\ \text{MVA}$$

$$Q_{\#} = Q_C + Q_L$$

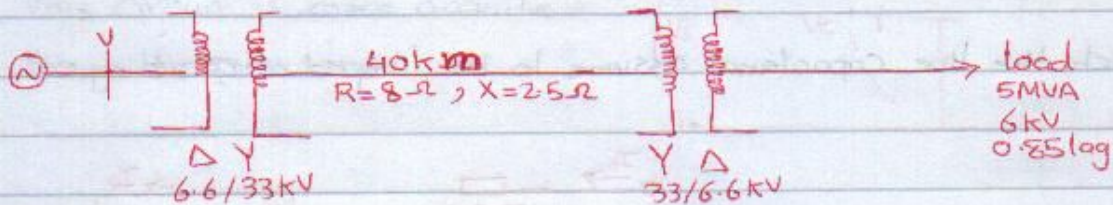
$$Q_C = Q - Q_L = 2.74\ \text{MVA}$$

$$Q_C = \frac{|V_R|^2}{X_C} \Rightarrow X_C = \frac{|V_R|^2}{Q_C} = 36.5\ \Omega$$

$$C = \frac{1}{2\pi f C} = 87\ \mu\text{F}$$

* Exercises

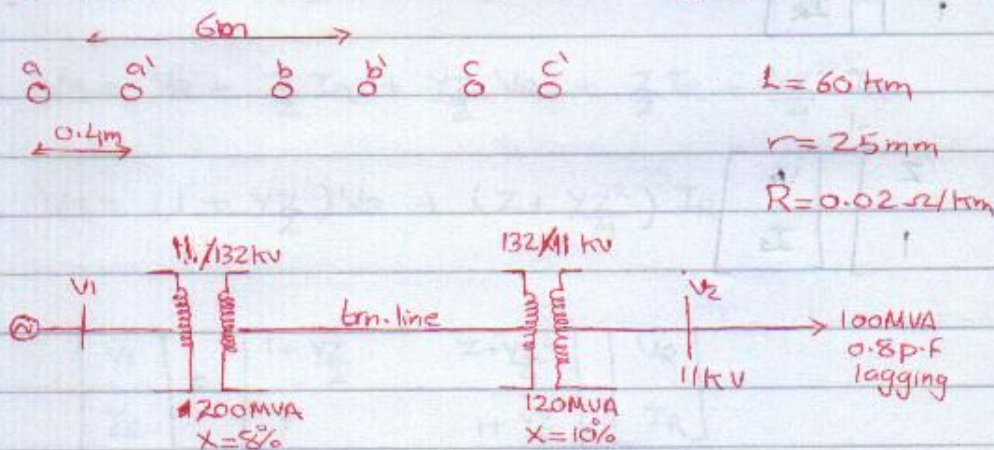
Q1) A load of 5 MVA is supply at station by 6 kV supply voltage through short line. find the voltages



for Δ winding $R=0.6\ \Omega$, $X=0.36\ \Omega$

for Y winding $R=0.5\ \Omega$, $X=3.75\ \Omega$

Q2) A 3-phase bundled radial transmission line shown in figure (1), with length of 60 km and radius of each conductor of 25 mm and resistance of $R=0.02\ \Omega/\text{km}$ is supplying a load of 100 MVA, 0.8 p.f lagging



a) Find the inductive reactance in Ω/km at 50 Hz of tm. line.

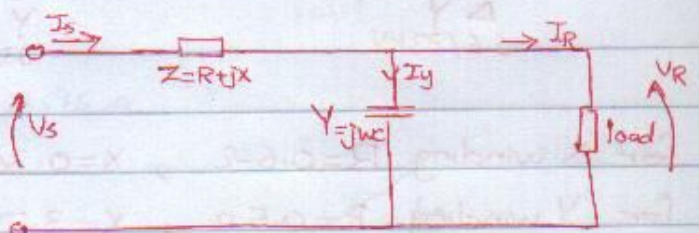
b) If the voltage at load bus required to be kept at 11 kV, find the generator terminal voltage and the voltage regulation of the line. Choose (100 MVA) ϕ and 132 kV of tm. line

c) Find the value of C to be placed in parallel with load such that the line regulat reduced to 50% of obtained in b. What will the generator terminal voltage in this case

* Medium Transmission Line

For line with length $100\text{km} < L < 250\text{km}$, the capacitance can be considered in the calculations

1) Circuit at which the line capacitance assume to be lumped at receiving end



$$I_s = I_R + Y \cdot V_R$$

$$V_s = V_R + Z \cdot I_s$$

$$V_s = V_R + Z(I_R + Y \cdot V_R)$$

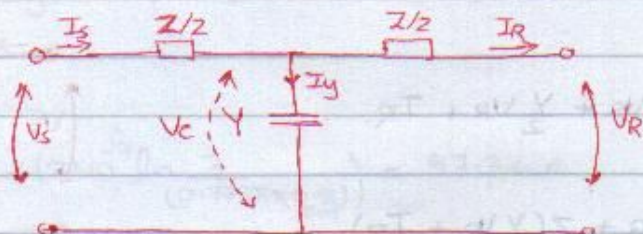
$$V_s = (1 + ZY)V_R + ZI_R$$

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} 1 + YZ & Z \\ Y & 1 \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

$$\begin{bmatrix} V_R \\ I_R \end{bmatrix} = \begin{bmatrix} 1 + YZ & Z \\ Y & 1 \end{bmatrix}^{-1} \begin{bmatrix} V_s \\ I_s \end{bmatrix}$$

2) T-equivalent Circuits in this circuit the capacitance of line assume to be lumped in the middle of the line

this circuit is more accurate than the previous



$$V_c = V_R + Z/2 I_R$$

$$I_s = I_R + Y \cdot V_c$$

$$\begin{aligned} I_s &= I_R + Y(V_R + Z/2 I_R) \\ &= Y \cdot V_R + I_R(1 + \frac{YZ}{2}) \end{aligned}$$

$$V_s = V_c + \frac{Z}{2} I_s$$

$$V_s = V_R + \frac{Z}{2} I_R + \frac{Z}{2} (Y \cdot V_R + (1 + \frac{YZ}{2}) I_R)$$

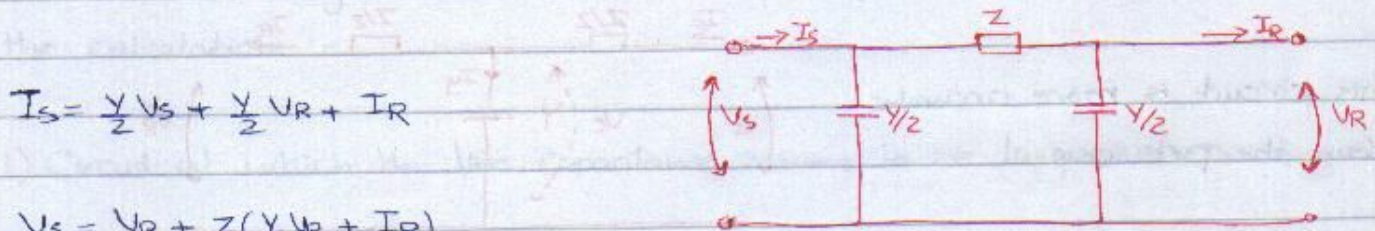
$$V_s = V_R + \frac{Z}{2} I_R + \frac{YZ}{2} V_R + \frac{Z}{2} I_R + \frac{YZ^2}{4} I_R$$

$$V_s = (1 + \frac{YZ}{2}) V_R + (Z + \frac{YZ^2}{4}) I_R$$

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} 1 + \frac{YZ}{2} & Z + \frac{YZ^2}{4} \\ Y & 1 + \frac{YZ}{2} \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

$$\Delta = (1 + \frac{YZ}{2})^2 - Y(Z + \frac{YZ^2}{4}) = 1$$

3) π -equivalent Circuit In this circuit, the cap of line assumed to be divided between receiving end and sending end. This circuit is most popular.



$$I_s = \frac{Y}{2} V_s + \frac{Y}{2} V_r + I_r$$

$$V_s = V_r + Z \left(\frac{Y}{2} V_r + I_r \right)$$

$$V_s = \left(1 + \frac{YZ}{2} \right) V_r + Z I_r$$

$$I_s = \frac{Y}{2} \left[\left(1 + \frac{YZ}{2} \right) V_r + Z I_r \right] + \frac{Y}{2} V_r + I_r$$

$$I_s = \frac{Y}{2} V_r + \frac{Y^2 Z}{4} V_r + \frac{YZ}{2} I_r + \frac{Y}{2} V_r + I_r$$

$$I_s = \left(Y + \frac{Y^2 Z}{4} \right) V_r + \left(1 + \frac{YZ}{2} \right) I_r$$

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} 1 + \frac{YZ}{2} & Z \\ Y + \frac{Y^2 Z}{4} & 1 + \frac{YZ}{2} \end{bmatrix} \begin{bmatrix} V_r \\ I_r \end{bmatrix}$$

$$\Delta = 1$$

All calculations used usually π -circuit.

Ex: Using π -circuit, find the sending-end voltage and voltage regulation of 250 km, 3-phase, 50 Hz, trn. line deliver 25 MVA at 0.8 PF to a balanced load of 132 kV (V_R). The line conductors are spaced equilaterally 3m apart, $r = 0.11 \Omega/\text{km}$, diameter 1.6 cm.

$$R = r \cdot L = 0.11 \times 250 = 27.5 \Omega$$

$$X = 2\pi fL = 2 \times 3.14 \times 50 \times 250 \text{ km} \times \left(2 \times 10^{-7} \ln \frac{3}{(0.7788 \times 0.8) \text{ cm}} \right) = 97.34 \Omega$$

$$Z = R + jX = 27.5 + 97.34j$$

$$Y = j\omega CL = j314 \times 250 \times \left(\frac{5.56 \times 10^{-2} \text{ MF/km}}{\ln \frac{D}{r}} \right) = j7.4 \times 10^{-4} \text{ S}$$

$$I_R = \frac{P}{\sqrt{3} \times V} = \frac{25 \text{ MVA}}{\sqrt{3} \times 132 \text{ kV}} = 109.35 \angle -36.9^\circ$$

حساب P في V_R

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} 1 + \frac{YZ}{2} & Z \\ Y + \frac{YZ}{2} & 1 + \frac{YZ}{2} \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

$$V_s = \left(1 + \frac{YZ}{2}\right) V_R + Z I_R$$

$$76.2 = 132 \left(1 + \frac{YZ}{2}\right) V_R$$

$$V_s = (73.45 + 0.775j) + (8.8 + 6.7j) = 82.25 + 7.475j = 82.6 \angle 5.2^\circ$$

$$V_s(\text{line}) = 82.6 \times \sqrt{3} = 143 \text{ kV}$$

calculate V_R

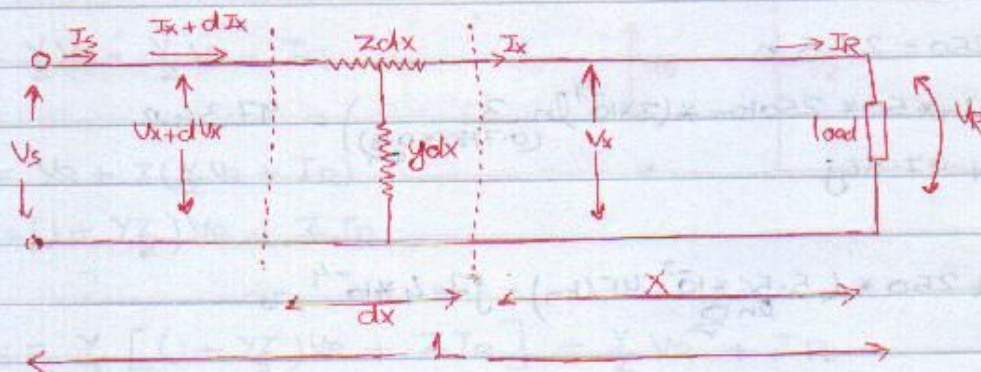
تكره حسب Z في V_R

$$V_R = \frac{V_s}{1 + \frac{YZ}{2}} = \frac{143 \text{ kV}}{0.964} = 148.3 \text{ kV}$$

$$\text{Voltage regulation} = \frac{148.3 - 132}{132} \times 100\% = 12.3\%$$

* long transmission line

line $> 250\text{km}$, assume to distributed uniformly along the line



$$dV_x = I_x \cdot Z dx$$

$$dI_x = V_x \cdot y dx$$

$$\frac{dV_x}{dx} = Z \cdot I_x$$

$$\frac{dI_x}{dx} = V_x \cdot y$$

$$\frac{d^2 V_x}{dx^2} = Z \cdot \frac{dI_x}{dx} \rightarrow \frac{d^2 V_x}{dx^2} = Z \cdot y \cdot V_x \rightarrow \frac{d^2 V_x}{dx^2} - yz V_x = 0$$

this is 2nd order differential equation

the characteristic equ $r^2 - yz = 0$

$$r_{1,2} = \pm \sqrt{yz} = \pm \gamma$$

$$V_x = C_1 e^{\gamma x} + C_2 e^{-\gamma x} \quad \text{by differentiate this equ}$$

$$\frac{dV_x}{dx} = C_1 \gamma e^{\gamma x} - C_2 \gamma e^{-\gamma x}$$

$$I_x = \frac{1}{Z} \frac{dV_x}{dx} = C_1 \frac{\gamma}{Z} e^{\gamma x} - C_2 \frac{\gamma}{Z} e^{-\gamma x}$$

$$I_x = C_1 \frac{\sqrt{yz}}{Z} e^{\gamma x} - C_2 \frac{\sqrt{yz}}{Z} e^{-\gamma x}$$

$$I_x = C_1 \sqrt{y/z} e^{\gamma x} - C_2 \sqrt{y/z} e^{-\gamma x}$$

$$I_x = \frac{C_1}{\sqrt{y/z}} e^{\gamma x} - \frac{C_2}{\sqrt{y/z}} e^{-\gamma x}$$

$\sqrt{y/z} \Rightarrow$ characteristic impedance

$$I_x = \frac{C_1}{Z_c} e^{\delta x} - \frac{C_2}{Z_c} e^{-\delta x}$$

the equs which describe the performance of the lines

$$\begin{aligned} V_x &= C_1 e^{\delta x} + C_2 e^{-\delta x} \\ I_x &= \frac{C_1}{Z_c} e^{\delta x} - \frac{C_2}{Z_c} e^{-\delta x} \end{aligned}$$

Constants C_1, C_2 are found from boundary condition

\Rightarrow When $x=0 \Rightarrow V_x = V_R, I_x = I_R$

$$V_R = C_1 + C_2 \Rightarrow C_1 + C_2 = V_R$$

$$I_x = \frac{C_1}{Z_c} - \frac{C_2}{Z_c} \Rightarrow C_1 - C_2 = Z_c I_x$$

$$2C_1 = V_R + Z_c I_x$$

$$C_1 = \frac{V_R + Z_c I_x}{2}, C_2 = \frac{V_R - Z_c I_x}{2}$$

$$V_x = \frac{V_R + Z_c I_x}{2} e^{\delta x} + \frac{V_R - Z_c I_x}{2} e^{-\delta x}$$

$$I_x = \frac{V_R/Z_c + I_x}{2} e^{\delta x} - \frac{V_R/Z_c - I_x}{2} e^{-\delta x}$$

$$V_x = V_R \left(\frac{e^{\delta x} + e^{-\delta x}}{2} \right) + Z_c I_x \left(\frac{e^{\delta x} - e^{-\delta x}}{2} \right)$$

$$I_x = \frac{V_R}{Z_c} \left(\frac{e^{\delta x} - e^{-\delta x}}{2} \right) + I_x \left(\frac{e^{\delta x} + e^{-\delta x}}{2} \right)$$

by simplifying these equation

$$V_x = \cosh \alpha x \cdot V_R + \sinh \alpha x \cdot Z_c I_R$$

$$I_x = \frac{V_R}{Z_c} \sinh \alpha x + I_R \cosh \alpha x$$

$$\begin{bmatrix} V_x \\ I_x \end{bmatrix} = \begin{bmatrix} \cosh \alpha x & Z_c \sinh \alpha x \\ \frac{1}{Z_c} \sinh \alpha x & \cosh \alpha x \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

at receiving end $x=l$, thus

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} \cosh(\alpha l) & Z_c \sinh(\alpha l) \\ \frac{\sinh(\alpha l)}{Z_c} & \cosh(\alpha l) \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

بعض العلاقات وتسمى طرق الخ

$$1) \alpha = \sqrt{YZ} = \alpha + j\beta$$

$$\begin{aligned} 2) \cosh(\alpha l) &= \cosh(\alpha l + j\beta l) \\ &= \cosh(\alpha l) \cosh(j\beta l) + \sinh(\alpha l) \sinh(j\beta l) \\ &= \cosh(\alpha l) \cos(\beta l) + j \sinh(\alpha l) \sin(\beta l) \end{aligned}$$

$$\begin{aligned} 3) \sinh(\alpha l + j\beta l) &= \sinh(\alpha l) \cosh(j\beta l) + \cosh(\alpha l) \sinh(j\beta l) \\ &= \sinh(\alpha l) \cos(\beta l) + j \cosh(\alpha l) \sin(\beta l) \end{aligned}$$

$$4) \sinh(\alpha l) = \alpha l + \frac{(\alpha l)^3}{3!} + \frac{(\alpha l)^5}{5!} + \dots$$

$$5) \cosh(\alpha l) = 1 + \frac{(\alpha l)^2}{2!} + \frac{(\alpha l)^4}{4!} + \dots$$

ملاحظة هامة نظراً لخصوصية القاطن hydraulic function من \sinh و \cosh باستخدام طريقة باستخدام 100% وهي صيغة

$$\begin{bmatrix} \cosh(\alpha l) & Z_c \sinh(\alpha l) \\ \frac{\sinh(\alpha l)}{Z_c} & \cosh(\alpha l) \end{bmatrix} \approx \begin{bmatrix} 1 + \frac{YZ}{2} & Z(1 + \frac{YZ}{6}) \\ Y(1 + \frac{YZ}{6}) & 1 + \frac{YZ}{2} \end{bmatrix}$$

Ex 3-phase, 50 Hz, $h = 400 \text{ km}$, $r = 0.125 \Omega/\text{km}$, $x = 0.4 \Omega/\text{km}$, $y = 2.8 \times 10^{-6} \text{ S}/\text{km}$. If $V_s = 220 \text{ kV}$

Find 1) Sending end current, receiving end voltage when line is not loaded

2) the max permissible length that the voltage on receiving end don't exceed 235 kV

$$R = 0.125 \times 400 = 50 \Omega$$

$$X = 0.4 \times 400 = 160 \Omega$$

$$Z = R + jX = 50 + 160j$$

$$Y = 2.8 \times 10^{-6} \times 400 = j1.12 \times 10^{-3} \text{ S}$$

a) not loaded i.e. $I_R = 0$

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} 1 + \frac{YZ}{2} & Z(1 + \frac{YZ}{2}) \\ Y(1 + \frac{YZ}{2}) & 1 + \frac{YZ}{2} \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

$$V_R = \frac{V_s}{1 + \frac{YZ}{2}} = 241.4 - 7.425j = 241.5 \text{ kV} \angle -1.76^\circ$$

$$I_s = Y(1 + \frac{YZ}{2})(V_R) = Y(1 + \frac{YZ}{2}) \left(\frac{V_R}{\sqrt{3}} \right) = -1.46 + 151.5j = 151.5 \text{ A} \angle -89.49^\circ$$

power system analysis error نسبة الخطأ. دالة أي طلب. $\text{error} = \pm 5\%$

b) $V_s = (1 + \frac{YZ}{2}) V_R$

$$\frac{V_s}{V_R} = (1 + \frac{YZ}{2}) \Rightarrow \frac{V_s}{V_R} = 1 + \frac{1}{2} * l^2 * j 2.8 * 10^{-6} * (0.125 + 0.4j)$$

$$\frac{220}{235} = 1 + \frac{1}{2} * l^2 * j 2.8 * 10^{-6} * (0.125 + 0.4j)$$

by solving this equ $\Rightarrow h = 338 \text{ km}$

* Interpretation of Long Line Equation

$$V_x = \frac{V_R + Z_c I_R}{2} e^{\gamma x} + \frac{V_R - Z_c I_R}{2} e^{-\gamma x}$$

$$I_x = \frac{V_R/Z_c + I_R}{2} e^{\gamma x} - \frac{V_R/Z_c - I_R}{2} e^{-\gamma x}$$

but $\gamma = \sqrt{yz} = \alpha + j\beta$

$$V_x = \frac{V_R + Z_c I_R}{2} e^{(\alpha + j\beta)x} + \frac{V_R - Z_c I_R}{2} e^{-(\alpha + j\beta)x}$$

$$\frac{V_R + Z_c I_R}{2} = \left| \frac{V_R + Z_c I_R}{2} \right| \angle \phi_1 = \left| \frac{V_R + Z_c I_R}{2} \right| e^{j\phi_1}$$

$$\frac{V_R - Z_c I_R}{2} = \left| \frac{V_R - Z_c I_R}{2} \right| \angle \phi_2 = \left| \frac{V_R - Z_c I_R}{2} \right| e^{j\phi_2}$$

$$V_x = \left| \frac{V_R + Z_c I_R}{2} \right| e^{\alpha x} e^{j(\beta x + \phi_1)} + \left| \frac{V_R - Z_c I_R}{2} \right| e^{-\alpha x} e^{j(\phi_2 - \beta x)}$$

V_{x1}

V_{x2}

From this, we can see that V_x has two components V_{x1} , V_{x2}

$$V_{x1} = \left| \frac{V_R + Z_c I_R}{2} \right| e^{\alpha x} e^{j(\beta x + \phi_1)} = \sqrt{2} \left| \frac{V_R + Z_c I_R}{2} \right| e^{\alpha x} \cos(\omega t + \beta x + \phi_1)$$

amplitude

magnitude

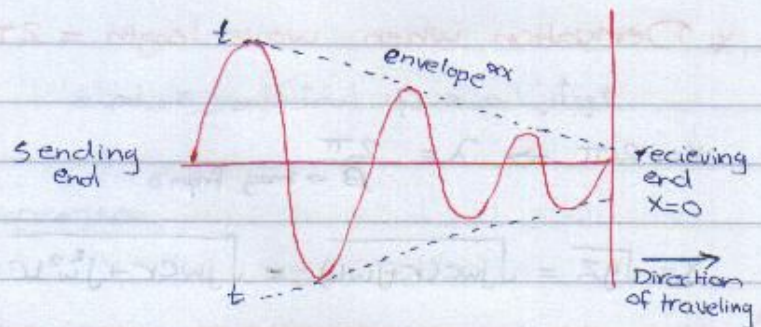
$$V_{x2} = \left| \frac{V_R - Z_c I_R}{2} \right| e^{-\alpha x} e^{j(\phi_2 - \beta x)} = \sqrt{2} \left| \frac{V_R - Z_c I_R}{2} \right| e^{-\alpha x} \cos(\omega t - \beta x + \phi_2)$$

$$\omega \Delta t + \beta \Delta x = 0$$

$$\omega \Delta t = -\beta \Delta x$$

$$\Delta x = -\frac{\omega}{\beta} \Delta t$$

(incident waveform)

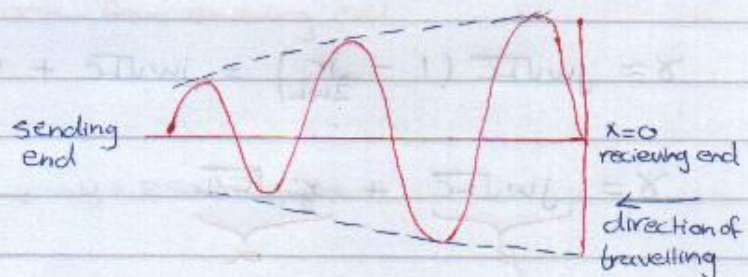


$$\omega \Delta t - \beta \Delta x = 0$$

$$\omega \Delta t = \beta \Delta x$$

$$\Delta x = \frac{\omega}{\beta} \Delta t$$

(reflected waveform)



- From this waveform, we can conclude that the voltage has two components:

- 1) incident waveform as appearing from sending end to receiving end
- 2) reflected waveform as appearing from receiving end to sending end.

- If the line is loaded by its characteristic impedance, that means no reflected exists in the waveform, in this case the line is called infinite bus (line).

- Sometimes, the characteristic impedance of the line is $Z_c = \sqrt{Z/Y} = Z_s$ (surge impedance)
for overhead line $Z_s = 400 \Omega$, for cables $= 40 \Omega$

- **Surge impedance**: the line when it is loaded by characteristic impedance

$$S \cdot I = 3 V_{ph} \cdot I_{ph}$$

$$= 3 \cdot \frac{|V_R|}{\sqrt{3}} \cdot \frac{|V_R|}{\sqrt{3} \cdot Z_s} = \frac{|V_R|^2}{Z} \text{ MW} = \frac{1000 \times |V_R|^2}{400} = 2.5 |V_R|^2 \text{ kW}$$

* Derivation when wave length = 2π

$$x = 2\pi \Rightarrow \lambda = \frac{2\pi}{\beta} \rightarrow \text{may from } \delta$$

$$\gamma = \sqrt{YZ} = \sqrt{j\omega C(r + j\omega L)} = \sqrt{j\omega Cr + j^2\omega^2 LC} = \sqrt{j^2\omega^2 LC \left(1 + \frac{j\omega Cr}{j^2\omega^2 LC}\right)}$$

$$\gamma = j\omega\sqrt{LC} \sqrt{1 + \frac{r}{j\omega L}} = j\omega\sqrt{LC} \sqrt{1 - \frac{j r}{\omega L}}$$

$$\gamma \approx j\omega\sqrt{LC} \left(1 - \frac{j r}{2\omega L}\right) = j\omega\sqrt{LC} + \frac{\omega r\sqrt{LC}}{2\omega L}$$

$$\gamma = \underbrace{j\omega\sqrt{LC}}_{\beta} + \underbrace{\frac{r}{2}\sqrt{C/L}}_{\alpha}$$

\Rightarrow if / for cases of lossless line $r=0$

$$v = f \cdot \lambda \quad \text{speed of propagation}$$

$$\alpha = 0, \quad \beta = \omega\sqrt{LC}$$

$$\text{but } \lambda = \frac{2\pi}{\beta} = \frac{2\pi}{2\pi f\sqrt{LC}} = \frac{1}{f\sqrt{LC}}$$

$$v = f \cdot \lambda = \frac{1}{\sqrt{LC}}$$

$$\gamma = j\omega\sqrt{LC}$$

$$L = \frac{\mu_0 \ln D}{2\pi r}, \quad C = \frac{2\pi\epsilon_0}{\ln D/r}$$

سرعت انتقال سیگنال

$$v = \frac{1}{\sqrt{\frac{\mu_0 \ln D}{2\pi r} \cdot \frac{2\pi\epsilon_0}{\ln D/r}}}$$

$$v \approx \frac{1}{\sqrt{\mu_0\epsilon_0}} \approx 3 \times 10^8 \text{ m/s}$$

i.e. waveform propagate over total line by light speed.

- Practically is less than this value

$$\lambda = \frac{v}{f} = \frac{3 \times 10^8}{50} = 6000 \text{ km}$$

الطول الموجي هو سرعة الضوء مقسومة على التردد

but this length is very large as a comparison.

Ex: 3-phase, 50HZ, open circuit overhead line 400km, $r=0.125 \Omega/\text{km}$, $x=0.4 \Omega/\text{km}$, $y=2.8 \times 10^{-6}$

if $V_R = 220 \text{ kV}$. find a) incident and reflected voltage to neutral at receiving end.

b) the incident and reflected voltage at 200km from receiving end.

c) find the resultant

$$r=0.125 \Omega/\text{km}, \quad x=0.4 \Omega/\text{km}, \quad y=2.8 \times 10^{-6} \text{ S}/\text{km}$$

$$Z = (0.125 + j0.4) = 0.42 \angle 76.6^\circ \Omega/\text{km}$$

r, x \downarrow Z_{small} R, x \downarrow Z_{capitol}
 المقاومة الصغيرة \downarrow Z_{capitol} \downarrow Z_{capitol}

$$\gamma = \sqrt{yz} = (j2.8 \times 10^{-6} \times 0.42 \angle 76.6^\circ)^{1/2} = (0.163 + j1.068) \times 10^{-3}$$

$$\therefore \alpha = 0.163 \times 10^{-3}, \quad \beta = j1.068 \times 10^{-3}$$

a) at receiving end, open circuit so $I_R = 0$, x at receiving end = 0.

$$\text{Incident Voltage } V_{x1} = \frac{V_R + Z_C I_R}{2} = \frac{V_R}{2} = \frac{220/\sqrt{3}}{2} = 63.51 \text{ kV to neutral}$$

$$\text{Reflected voltage } V_{x2} = \frac{V_R - Z_C I_R}{2} = \frac{V_R}{2} = 63.51 \text{ kV}$$

b) At 200 km from receiving end

$$V_{x1} = \frac{V_R}{2} e^{\alpha x} e^{j\beta x} = 63.51 \exp(0.163 \times 10^{-3} \times 200) \times \exp(j1.068 \times 10^{-3} \times 200) = 65.5 \text{ kV} \angle 12.2^\circ \text{ to neu.}$$

$$V_{x2} = \frac{V_R}{2} e^{-\alpha x} e^{-j\beta x} = 63.51 \times e^{-0.0326} \times e^{-j0.2136} = 61.47 \angle -12.2^\circ \text{ kV to neu.}$$

© Resultant $V_x = V_{x1} + V_{x2}$

$$= 65.5 \angle 122^\circ + 61.47 \angle -12^\circ = 124.1 \angle 10.4^\circ$$

resultant Line to line at 200km

$$124.1 \times \sqrt{3} = 215 \text{ km}$$

يجب على المحطة أن تكون قريبة من ال V_R

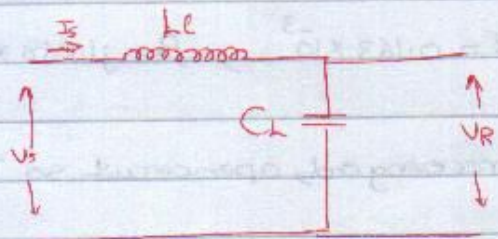
* Ferranti Effect

- درسا سابقاً أن ال V_R يجب أن تكون أقل من V_s وذلك لوجود drop volt على طول الخط ، لكن في بعض الحالات تكون ال $V_R > V_s$ وهذه تسمى هيرانتى

- When the line open circuit or lightly loaded, the receiving end voltage can reach values greater than sending end. This can be explain by lumping the capacitance and inductance as shown in the figure.

L_e, C_e total inductance and capacitance

i.e $L_e = L \cdot l$ induct * length



$$I_s = \frac{V_s}{j\omega L_e + \frac{1}{j\omega C_e}}$$

but for practical line $\frac{1}{\omega C_e} \gg \omega L_e$

$$I_s = \frac{V_s}{\frac{1}{j\omega C_e}} = j\omega C_e \cdot V_s$$

$$V_R = V_s - I_s(j\omega L_e)$$

$$V_R = V_s - j\omega C_e \cdot V_s(j\omega L_e)$$

$$V_R = V_s + V_s \omega^2 C_e L_e$$

$$V_R = V_s (1 + \omega^2 C_e L_e)$$

From this result, we can see that $V_R > V_S$ cuz $\omega^2 L C e > 0$

$$|V_R - V_S| = \omega^2 C e \cdot L e \cdot V_S$$

$$\Delta V = \omega^2 \cdot C \cdot e \cdot L \cdot e \cdot V_S$$

$$\Delta V = \frac{\omega^2 \cdot e^2 \cdot V_S}{\frac{1}{LC}}$$

فرانسا LC (مقام مقام حیت آنرا نقیضی اثری بسط
(مقام مقام = بسط)

$$\Delta V = \frac{\omega^2 \cdot e^2 \cdot V_S}{\left(\frac{1}{\sqrt{LC}}\right)^2} = \frac{\omega^2 \cdot e^2 \cdot V_S}{V^2}$$

ΔV حیت آنرا نقیضی (مربع اثری) الی

- In order to decrease ferranti effect, sometimes an inductance is connected at the receiving end of the line.

V_R	V_S	I_R	I_S
0	1	1	0
1	0	0	1

V_R	V_S	I_R	I_S
0	1	1	0
1	0	0	1

* Tuned Power Line

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} \cosh(\gamma l) & Z_c \sinh(\gamma l) \\ \frac{\sinh(\gamma l)}{Z_c} & \cosh(\gamma l) \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

$$\gamma = \sqrt{yZ} = \sqrt{j\omega C \cdot j\omega L} = j\omega \sqrt{LC}$$

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} \cosh(j\omega l \sqrt{LC}) & Z_c \sinh(j\omega l \sqrt{LC}) \\ \frac{\sinh(j\omega l \sqrt{LC})}{Z_c} & \cosh(j\omega l \sqrt{LC}) \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

$$\left. \begin{aligned} \cosh(jx) &= \cos(x) \\ \sinh(jx) &= j \sin(x) \end{aligned} \right\} \text{قواعد}$$

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} \cos(\omega l \sqrt{LC}) & jZ_c \sin(\omega l \sqrt{LC}) \\ \frac{j \sin(\omega l \sqrt{LC})}{Z_c} & \cos(\omega l \sqrt{LC}) \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

$$\omega l \sqrt{LC} = n \cdot \pi, \quad \cos(\omega l \sqrt{LC}) = \pm 1, \quad \sin(\omega l \sqrt{LC}) = 0$$

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} \pm 1 & 0 \\ 0 & \pm 1 \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix} \quad \begin{aligned} |V_s| &= |V_R| \\ |I_s| &= |I_R| \end{aligned}$$

This case, the line set to be tuned, no voltage drop exists.

⇒ Condition of tuned line:

$$\omega l \sqrt{LC} = n \cdot \pi$$

$$l = \frac{n \cdot \pi}{\omega \sqrt{LC}} = \frac{n \cdot \pi}{\omega} \cdot \frac{1}{\sqrt{LC}} = \frac{n \cdot \pi \cdot \sqrt{f}}{2 \pi f} = \frac{n \cdot 3 \times 10^8}{2 \times 50} = n \times 3000 \text{ km}$$

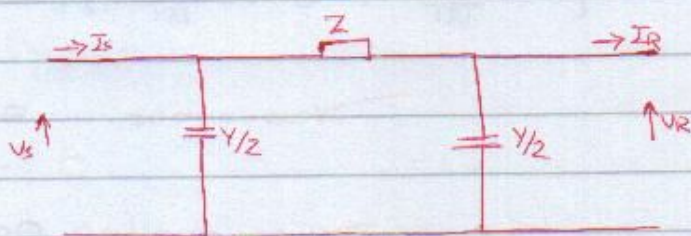
- practically, this is very long line. Tuned can be done industrial by adding series inductance and parallel capacitance to the line, but usually this is not done for power line cuz it's not economical cuz the low frequency of power system, it's done for communication line cuz the high frequency of it

- Nowadays, in order to decrease the effect of line inductance (voltage drop), a series capacitance is added to the line. In order to decrease the effect of line capacitance on inductance (coil or reactor) is added at receiving end of the line to cancel the parallel capacitance of the line.

* Equivalent Circuit of Long Lines

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} \cosh(\gamma l) & Z_c \sinh(\gamma l) \\ \frac{\sinh(\gamma l)}{Z_c} & \cosh(\gamma l) \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} 1 + \frac{YZ}{2} & Z \\ Y + \frac{Y^2 Z}{4} & 1 + \frac{YZ}{2} \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$



$Z = Z_c \sinh(\gamma l)$ ← $Z_c \sinh(\gamma l)$ مساهمة تقابل Z مساهمة Z من طرف Z_c من طرف Z_c (استقالات عنصر من الدائرة ما يكافئ)

$$1 + \frac{YZ}{2} = \cosh(\gamma l)$$

$$\frac{YZ}{2} = \cosh(\gamma l) - 1 \Rightarrow \frac{Y}{2} = \frac{\cosh(\gamma l) - 1}{Z} = \frac{\cosh(\gamma l) - 1}{Z_c \cdot \sinh(\gamma l)}$$

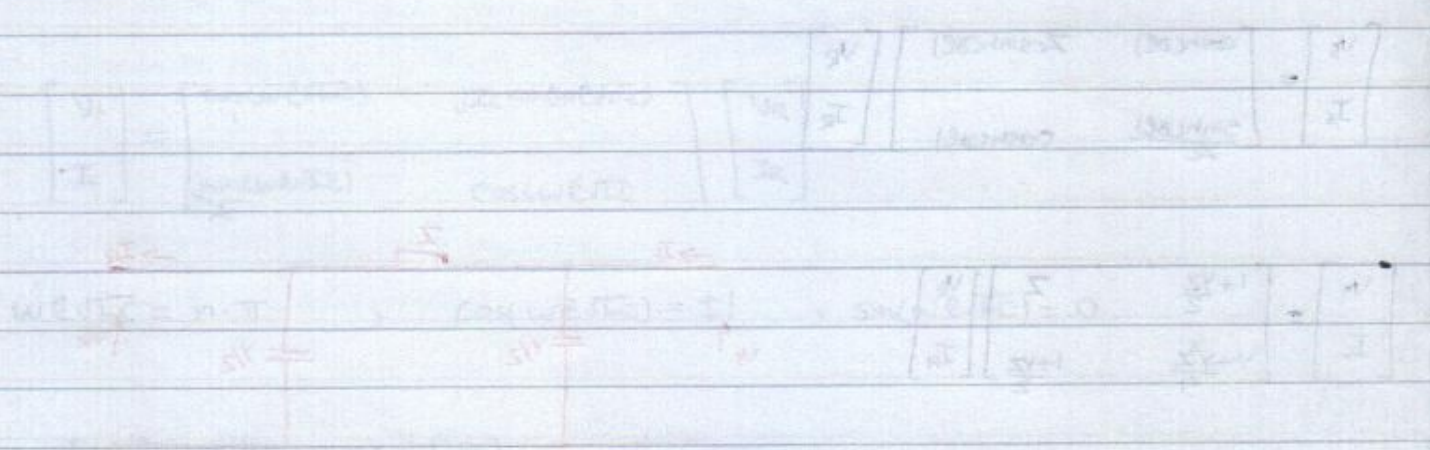
$$\frac{Y}{2} = \frac{\cosh(\gamma l) - 1}{Z_c \sinh(\gamma l)} \xrightarrow{\text{متكافئة}} \frac{2 \sinh^2(\frac{\gamma l}{2}) + 1 - 1}{2 Z_c \sinh(\frac{\gamma l}{2}) \cdot \cosh(\frac{\gamma l}{2})} = \frac{1}{Z_c} \tanh(\frac{\gamma l}{2})$$

وهذا ما يكافئ عن عناصر الدائرة

Ex: A 50HZ, 300 km long line has a total impedance $Z = 10 + j125$ and total shunt admittance $Y = 10^{-3}$. The receiving end voltage 220 kV and $P = 50$ MW, 0.8 p.f lagging. Find $V_s, I_s, P_s, P.F?$

حل السؤال مشابه بنفس الطريقة السابقة للحل ونفس المعادلات ونفس مصفوفة الحل

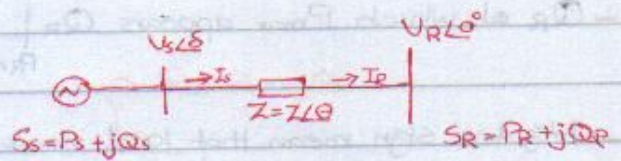
(Faint handwritten notes and diagrams, including a circuit diagram of a transmission line with series impedance and shunt admittance.)



(Faint handwritten calculations and notes, including the ABCD parameters for a transmission line: A = 1 + YZ, B = Z, C = Y, D = 1.)

* Power flow (load flow) through trn. line

Consider the following two bus system



عادة ما يؤخذ الـ V_R كمرجع لنا تكون زاوية θ صفر

$$I_s = I_R = \frac{V_s - V_R}{Z} = \frac{|V_s| \angle \delta - |V_R| \angle \theta}{|Z| \angle \theta} = \frac{|V_s| \angle \delta - \theta}{|Z|} - \frac{|V_R| \angle -\theta}{|Z|}$$

$$I_s^* = I_R^* = \frac{|V_s| \angle \theta - \delta}{|Z|} - \frac{|V_R| \angle \theta}{|Z|}$$

$$S_R = V_R \cdot I_R^* = P_R + jQ_R = |V_R| \left[\frac{|V_s| \angle \theta - \delta}{|Z|} - \frac{|V_R| \angle \theta}{|Z|} \right]$$

$$S_R = \frac{|V_R| |V_s| \angle \theta - \delta}{|Z|} - \frac{|V_R|^2 \angle \theta}{|Z|}$$

$$= \frac{|V_R| |V_s|}{|Z|} [\cos(\theta - \delta) + j \sin(\theta - \delta)] - \frac{|V_R|^2}{|Z|} [\cos \theta + j \sin \theta]$$

$$= \frac{|V_R| |V_s| \cos(\theta - \delta) - |V_R|^2 \cos \theta}{|Z|} + j \left[\frac{|V_R| |V_s| \sin(\theta - \delta) - |V_R|^2 \sin \theta}{|Z|} \right]$$

$$P_R = \frac{|V_R| |V_s| \cos(\theta - \delta) - |V_R|^2 \cos \theta}{|Z|} \quad \text{ooooooooooooo} \checkmark$$

$$Q_R = \frac{|V_R| |V_s| \sin(\theta - \delta) - |V_R|^2 \sin \theta}{|Z|} \quad \text{ooooooooooooo} \checkmark$$

$$S_s = V_s \cdot I_s^* = |V_s| \angle \delta \left[\frac{|V_s| \angle \theta - \delta}{|Z|} - \frac{|V_R| \angle \theta}{|Z|} \right]$$

$$S_s = P_s + jQ_s = \frac{|V_s|^2 \angle \theta}{|Z|} - \frac{|V_s| |V_R| \angle \theta + \delta}{|Z|}$$

$$= \frac{|V_s|^2}{|Z|} [\cos \theta + j \sin \theta] - \frac{|V_s| |V_R|}{|Z|} [\cos(\theta + \delta) + j \sin(\theta + \delta)]$$

$$P_s = \frac{|V_s|^2 \cos \theta}{|Z|} - \frac{|V_s| |V_R| \cos(\theta + \delta)}{|Z|} \quad \text{ooooooooooooo} \checkmark$$

$$Q_s = \frac{|V_s|^2 \sin \theta}{|Z|} - \frac{|V_s| |V_R| \sin(\theta + \delta)}{|Z|} \quad \text{ooooooooooooo} \checkmark$$

- P_R max appears when $\theta = \delta$. In this case $P_{Rmax} = \frac{|V_R||V_s|}{|Z|} - \frac{|V_R|^2 \cos \theta}{|Z|}$

- Q_R at which P_{max} appears $Q_R |_{P_{Rmax}} = - \frac{|V_R|^2 \sin \theta}{|Z|}$ load is capacitive

- Negative sign mean that load must generate Q_R in order to receive P_{Rmax} .

- Usually, R for the line is neglect as it small with compare to inductance \Rightarrow
 $\theta = 90^\circ$, $|Z| = X$

$$P_R = \frac{|V_s||V_R|}{X} \sin \delta, \quad Q_R = \frac{|V_s||V_R|}{X} \cos \delta - \frac{|V_R|^2}{X}$$

also in normal cases δ is a small angle $\Rightarrow \cos \delta \approx 1$

$$Q_R \approx \frac{|V_s||V_R|}{X} - \frac{|V_R|^2}{X} = \frac{|V_R|}{|X|} [|V_s| - |V_R|]$$

$$Q_R = \frac{|V_R||\Delta V|}{X} \Rightarrow \Delta V = \frac{Q_R \cdot X}{|V_R|}$$

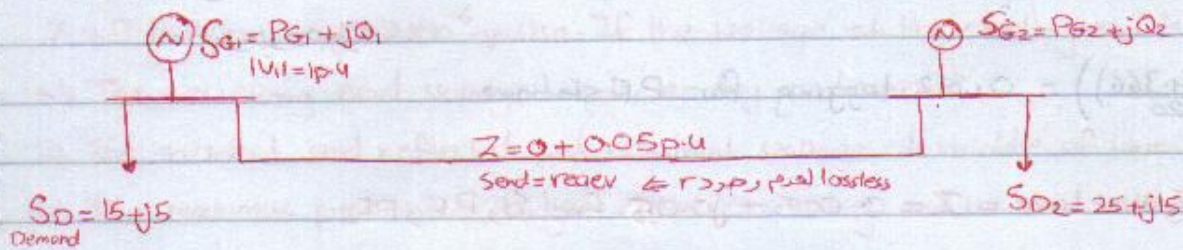
- Notes:

- 1] the received power is a function of angle δ .
- 2] the max. received power is directly proportional to the square of line voltage
- 3] P_R is inversely proportional with X , when increase P_{Rmax} , X decreases, this is why series capacitance is adding to line to decrease the effect

$$4] |\Delta V| = \frac{QX}{|V_R|}$$

ذكرنا سابقاً $V_R \propto \frac{1}{X}$ علاقة عكسية

Exg Two generation station are interconnected by a cable link, the desired voltage is flat
 i.e. $(V_1 = V_2) = 1 \text{ p.u.}$



If the active power generated by two station is equal, find δ , P.F., P.F2

$$V_2 = 1 \angle 0^\circ \text{ reference}$$

$$V_1 = 1 \angle \delta$$

$$\sum P_G = \sum P_D \quad \text{Power balanced}$$

$$P_{G1} + P_{G2} = P_{D1} + P_{D2} + P_{\text{losses}}$$

$$P_{G1} + P_{G2} = 15 + 25 = 40 \Rightarrow P_{G1} = P_{G2} = 20 \text{ p.u.}$$

$$P_S = P_R \Rightarrow P_R = \frac{|V_S| \cdot |V_R| \cos(\theta - \delta)}{|Z|} - \frac{|V_R|^2 \cos \theta}{|Z|}$$

$$P_R = P_G - P_D = 5 = \frac{1 \times 1}{0.05} \cos(90 - \delta) - 0$$

$$5 = \frac{1}{0.05} \cos(90 - \delta) \Rightarrow \delta = 14.47^\circ$$

$$\delta = (10^\circ - 25^\circ) \angle \text{LE}$$

$$Q_S = \frac{|V_S|^2 \sin \theta}{|Z|} - \frac{|V_S| |V_R| \sin(\theta + \delta)}{|Z|}$$

$$= \frac{1}{0.05} \sin 90^\circ - \frac{1 \times 1}{0.05} \sin(90^\circ + 14.47^\circ) = 0.634 \text{ p.u.}$$

$$S_{G1} = (P_{G1} + P_{D1}) + j(Q_G + Q_{D1})$$

$$= (15 + 5) + j(5 + 0.634) = 20 + j5.634$$

$$\cos(\tan^{-1}(\frac{Q_G}{P_G})) = 0.963 \text{ lagging P.F. for first station}$$

$$S_{G2} = (P_{D2} - P_R) + j(Q_{D2} - Q_{R-s})$$

$$= (25 - 5) + j(15 - 0.634)$$

$$= 20 + j14.366$$

الاستارة ناقص بين (Q) ال
 load هو يولد reactive power في توليد
 ويعطى 'send' لتغطية استاري receive
 اصرم وهو صينات

$$\cos(\tan^{-1}(\frac{14.366}{20})) = 0.812 \text{ lagging for P.F station}$$

extrag if the Zoverline = $Z = 0.005 + j0.05$ And θ , P.F, P_{F2}

نفس الحل السابق ولكن الاختلاف يصبح الزاوية θ بدلاً من أنها 90° في الفري الأول لعدم وجود r
 يصبح لها قيمة أقل من 90° وبالخصائص نفرض قوتها

$$Z = |0.005| \angle 84.29^\circ$$

افرض 84.29° في حسابان بدلاً من 90°

* Exercises Years Questions

Q1) 3-phase, 50Hz, open circuit transmission line 500km long. The line parameters are $r = 0.1 \Omega/\text{km}$, $X = 0.5 \Omega/\text{km}$, $y = 2 \times 10^{-6} \text{ S}/\text{km}$. If the voltage at the sending end is 400kV.

- The receiving end voltage and sending end current. (4 marks)
- The incident and reflected and resultant voltage at middle of line. (4 marks)
- The maximum permissible length if the receiving end no-load voltage is not exceed 420kV. (2 marks)

Q2) Two generation station are interconnected by a cable link with impedance $Z = 0.01 + j0.1 \text{ pu}$, the load demands at two buses $S_{D1} = 10 + j5 \text{ pu}$, and $S_{D2} = 20 + j10 \text{ pu}$. If the active power generated by G_1 is $P_{G1} = 15 \text{ pu}$, and the desired voltage profile is flat $|V_1| = |V_2| = 1 \text{ pu}$.

- finds-
- torque angle of bus 1, assuming bus 2 reference. (4 marks)
 - active and reactive powers generated by each generator. (4 marks)
 - the active and reactive losses in the line. (4 marks)

